

# KSP Update

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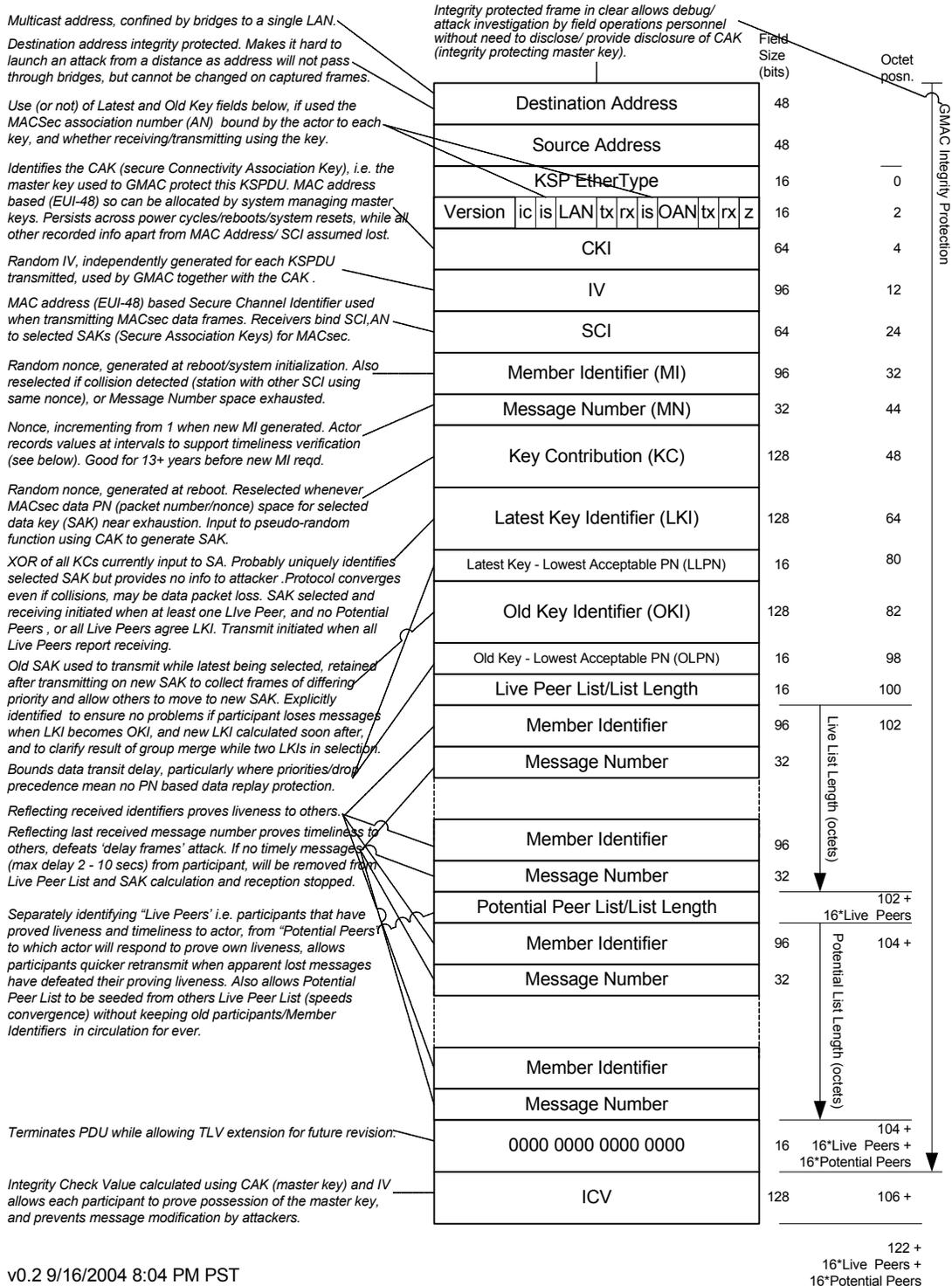
This note includes: an annotated description of the proposed KSPDU format, describing the life and purpose of all PDU fields; object diagrams of the classes that represent the entities, state machines, and data maintained by a KSP entity; the more significant KSP state machines; and the most important procedures. All these reflect revision of KSP to use a contributory key agreement mechanism to determine each SAK, although the transport and basic communication mechanisms remain unchanged from the first proposal.

With the possible exception of the annotated KSPDU format, it is unlikely that the information contained in this note will prove illuminating or satisfactory to anyone who wasn't at the last meeting. It is being distributed in advance of the upcoming meeting because the essential diagrams and code contain too much information to be satisfactorily presented on an LCD projector, or perused on a laptop while in a meeting. Bring your own printed copies.

## Further notes

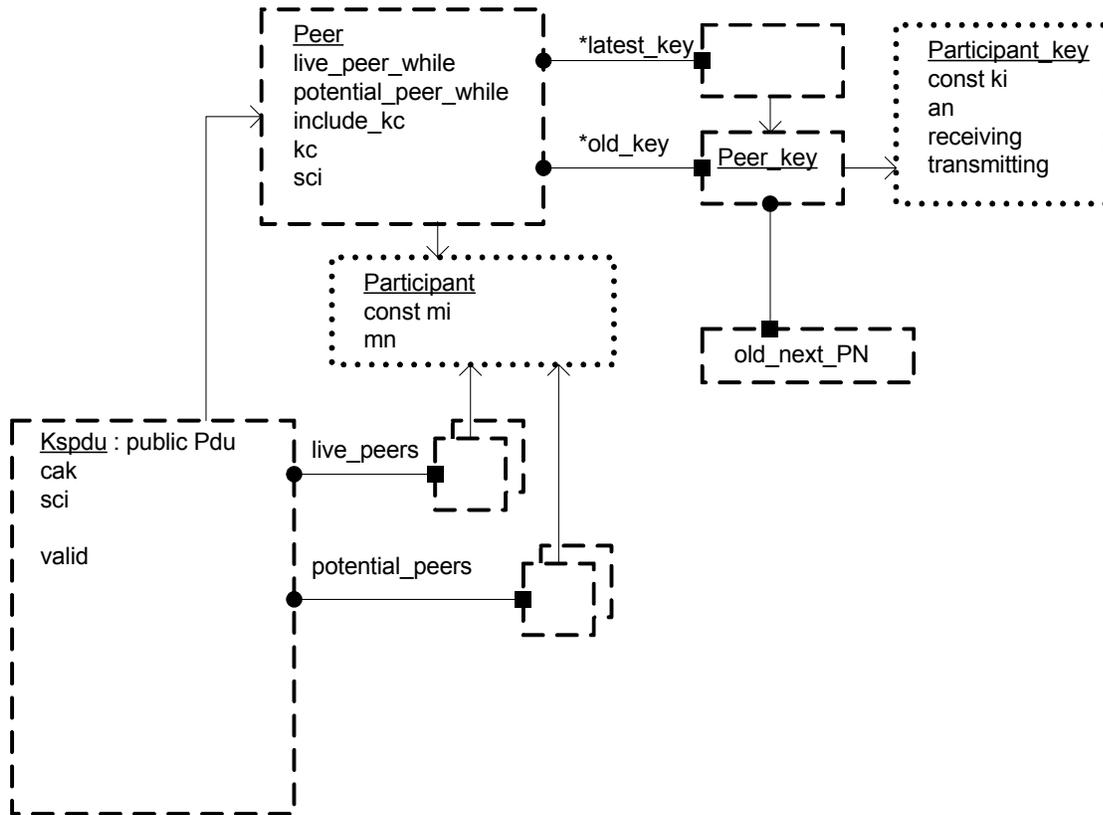
## KSPDU format and fields

KSP uses a single packet type and format (illustrated below). KSPDUs are transmit periodically and as needed subject to a leaky bucket rate limiter. The transmitter of the PDU is referred to as the 'actor', and other protocol participants as its 'peers'.



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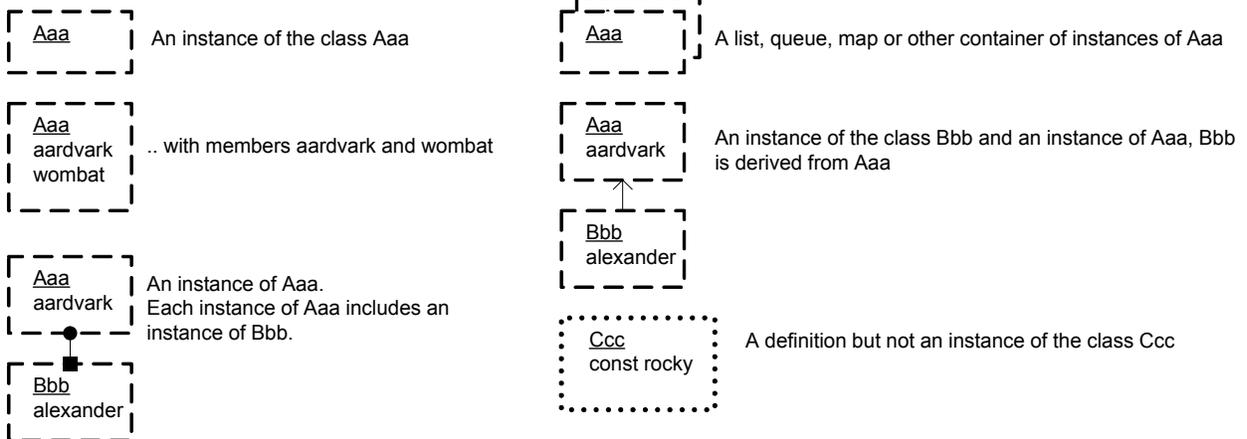




### KSPDU Objects

<<KSPDO 0.1>>

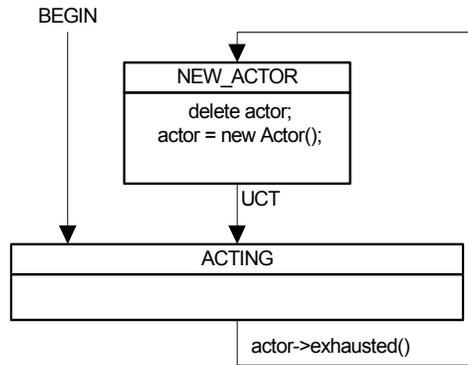
#### LEGEND



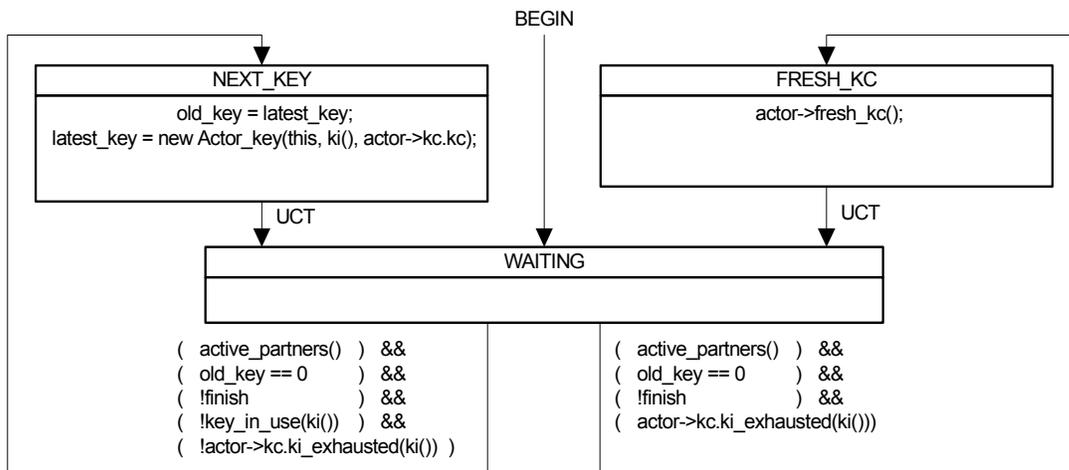
```

Ksp::Ksp(Kspy *p, const CAK ca_key, const CKI ca_key_id) : kspy(p), cak(ca_key), cki(ca_key_id)
{ actor = new Actor();
};

```



Ksp actor state machine <<AM 0.1>>



Ksp keys state machine <<KKM 0.1>>

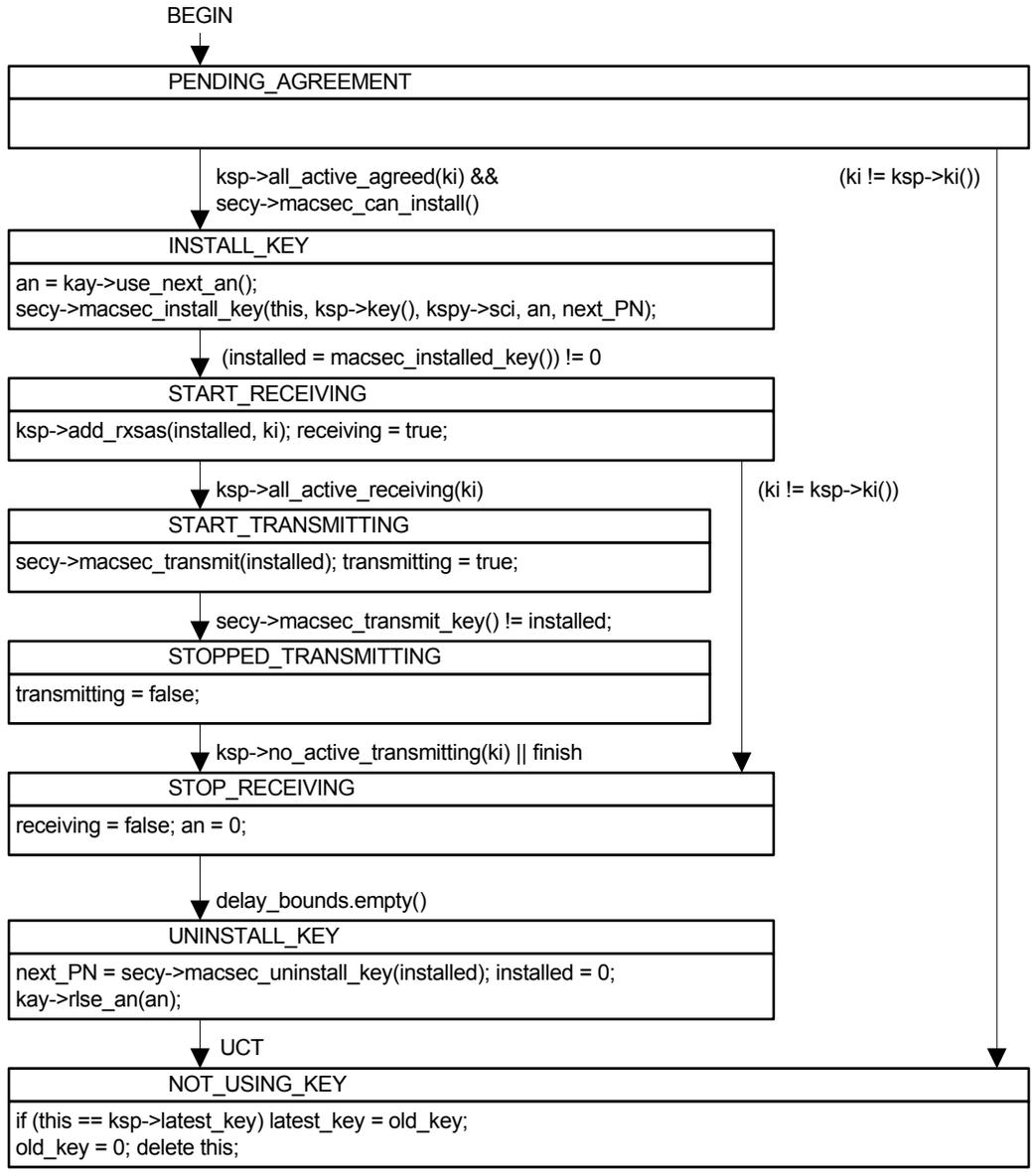
```

Actor_key::Actor_key(Ksp *p, KI key_id, KC key_contribution) : Participant(key_id), ksp(p), kc(key_contribution),
{
    receiving = transmitting = finish = false; installed = 0; an = 0;
    next_PN = ksp->next_pn_for(key_contribution, key_id);

    for (int i = 0; i < ticks_to_record; i++) delay_bounds.push(next_PN);

    akm = PENDING_AGREEMENT;
    dbm = DELAY_BOUND;
};

```

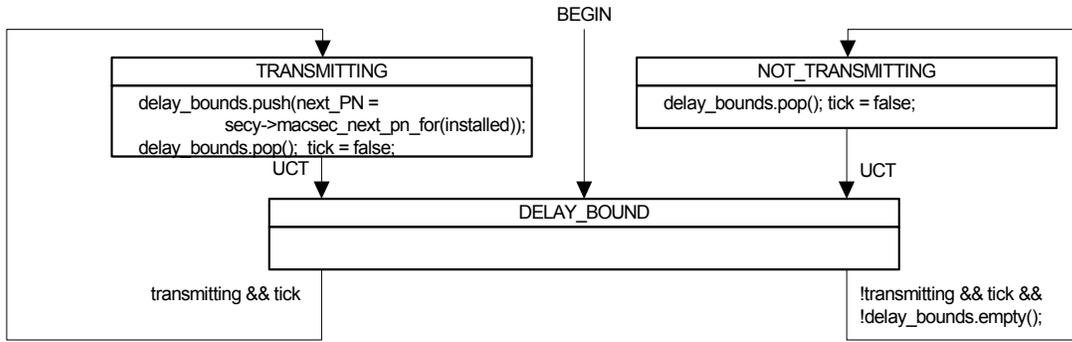


```

KaY * const kay = ksp->kspy->kay;
SecY* const secy = kay->secy;

```

Actor key state machine <<AKM 0.2>>



Delay bound state machine

<<DBM 0.1>>

```

void Ksp::rxpdu(Pdu *received_pdu)
{
    Kspdu rcvd(received_pdu);

    if (!rcvd.valid ) { rcv_event(Invalid_pdu) return; };
    if ( rcvd.sci == sci ) { rcv_event(Loopback_pdu) return; };
    if ( rcvd.mi == actor.mi)
    {
        this.change_mi(); rcv_event(Duplicate_mi) return; };
    }; // broken psrng?

    Peer *peer = find_peer( rcvd->mi);

    if (peer != 0)
    {
        if (rcvd.mn < peer->mn) { rcv_event(Misordered_pdu) return; };
        if (rcvd.mn == peer->mn) { rcv_event(Duplicate_pdu) return; };

        if (rcvd.sci != peer->sci){ rcv_event(Peer_sci_changed);
            delete peer; peer = 0; }
    }
    if (peer == 0)
    {
        peers.push_back(Peer( this, rcvd.mi, rcvd.sci));
        peer = &(*peers.last());
    };

    peer->potential_peer_while = potential_peer_life;

    peer->mn = rcvd->mn;

    Ticks life = actor->life(rcvd->find_me(actor->mi));
    if (life > peer->live_peer_while) peer->live_peer_while = life;

    if (peer->live_peer_while != 0)
    {
        if ((peer->include_kc != rcvd->include_kc) || (peer->kc != rcvd->kc))
            bool recalculate_key = true;

        peer->include_kc = rcvd->include_kc;
        peer->kc = rcvd->kc;

        peer->rx_keys(&rcvd);

        add_potential_peers(*(rcvd->peers)); // from live peer's live list

        if (recalculate_key)
        {
            if (old_key != 0) old_key->execute_akm();
            if (latest_key != 0) latest_key->execute_akm();
            execute_kkm();
        };
    }; };
}; };

```