

## Automotive E/E Architecture evolution and the impact on the network

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# Content of this presentation

- › Introduction of E/E architecture trend
- › Network implication for TSN features
- › Types of automotive Ethernet TSN nodes

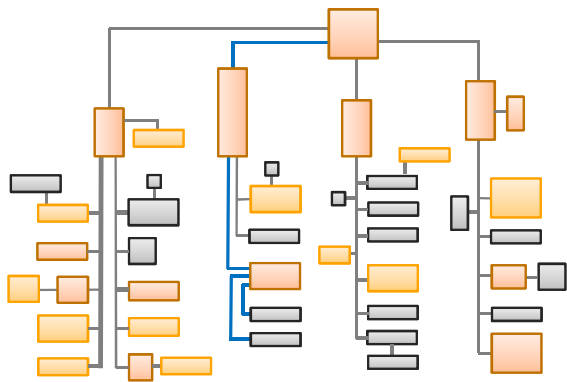
## Definitions

- › 10 Mbit/s (e.g. IEEE P802.3cg 10BASE-T1) was not taken into account
- › only Ethernet was taken into account ( no CAN, LIN, SerDes ...)
- › arrows in drawings of communication indicate logical data flow, NOT half-duplex connections
- › there is no “one common” E/E architecture among the car manufacturers
  - › every car manufacturer uses its own architecture (different number of hops & requirements)
  - › but the main concept is often similar

# Automotive E/E architecture

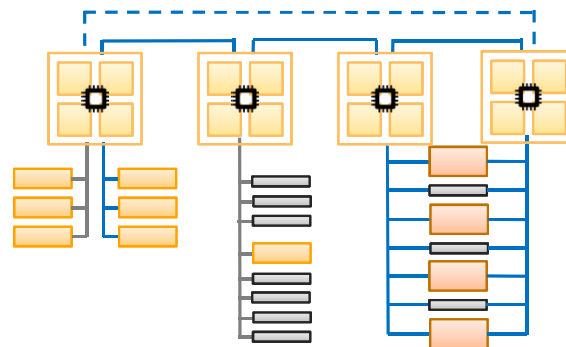
## Current state and outlook

Today: Traditional architecture



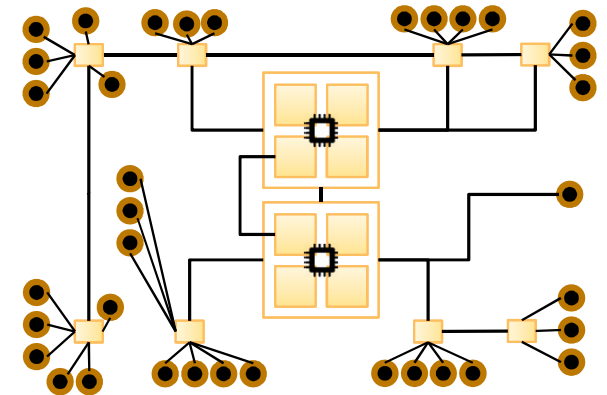
- › application-specific ECUs
- › application-specific bus systems
- › 1-to-1 communication

In development: Domain architecture



- › application-specific ECUs
- › functional consolidation in domain controllers
- › 1-to-1, “many-to-one” communication

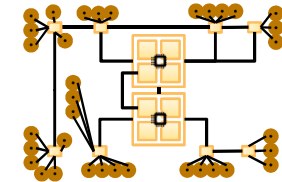
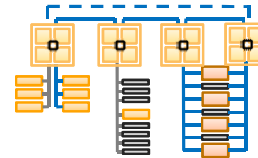
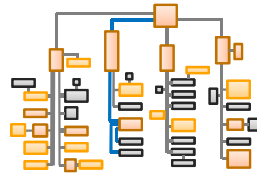
Tomorrow: Centralized architecture



- › software-driven architecture
- › centralized processing
- › “all-to-some” communication

# Automotive E/E architecture

## Characteristics

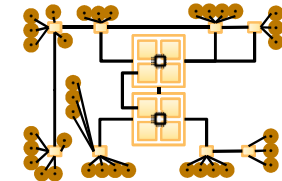
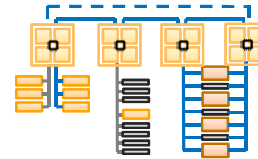
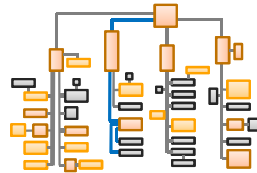


| Network topology                      |                      |                            |                                      |
|---------------------------------------|----------------------|----------------------------|--------------------------------------|
| topology                              | point-to-point, star | point-to-point, star, ring | point-to-point, star, multiple rings |
| no. of hops for a stream              | 1-2                  | 2-4                        | 3-6                                  |
| link speed                            | 100 Mbit/s           | 100 Mbit/s – 10 Gigabit/s  | 100 Mbit/s – 50 Gigabit/s            |
| no. of Ethernet links                 | < 10                 | 10 - 50                    | > 50                                 |
| no. of congestion points for a stream | 0-1                  | 1-3                        | 2-5                                  |
| no. of segments (VLANs, IP-networks)  | < 8                  | < 8                        | > 8                                  |

*Information here is based on educated guess, no full centralized architectures are in development today yet*

# Automotive E/E architecture

## Characteristics

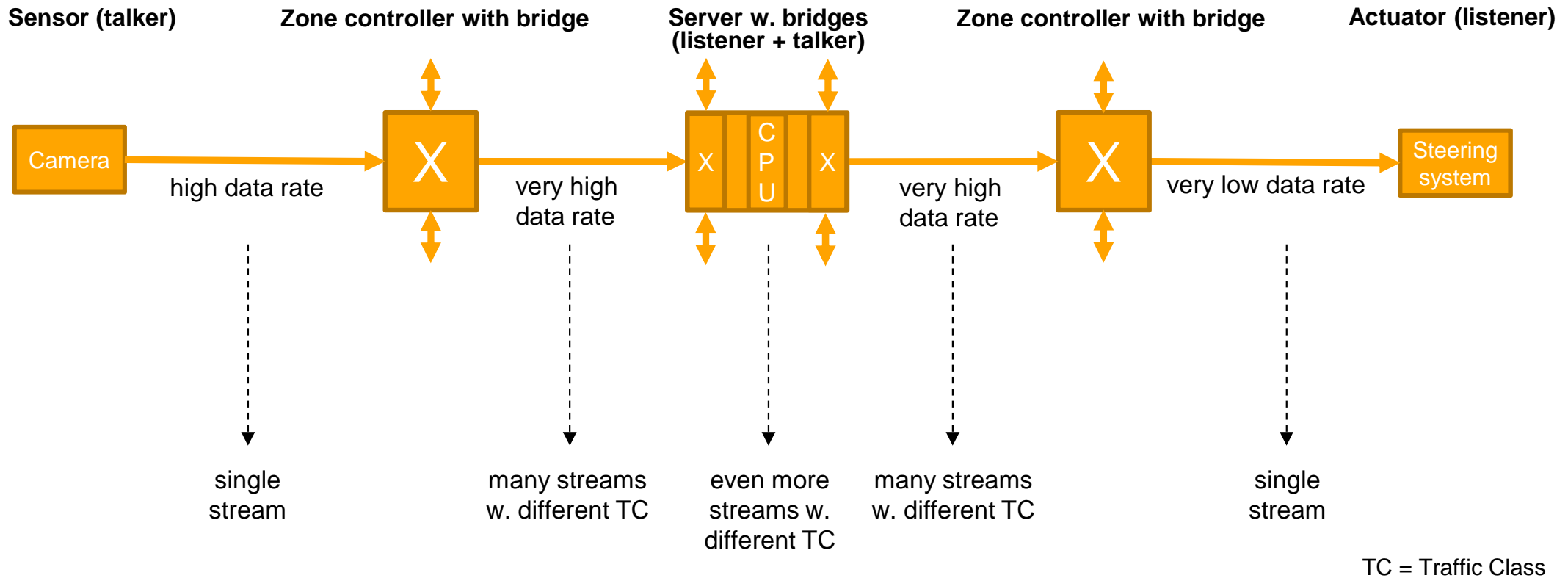


| Data characteristics                                  |                         |                           |                              |
|-------------------------------------------------------|-------------------------|---------------------------|------------------------------|
| no. of different traffic classes at congestion points | < 8                     | < 8                       | > 8                          |
| no. of streams at congestion points                   | < 10                    | < 50 at domain controller | > 200 (at Server)            |
| typical latency requirements                          | milliseconds (2 digits) | milliseconds (1-2 digits) | microseconds (2-3 digits)    |
| typical target of traffic load per link               | mid to high             | mid                       | low (at vehicle SOP)         |
| typical L2 frame size                                 | 64 Byte, 1500 Byte      | 64 Byte, 1500 Byte        | > 64 Byte (no encapsulation) |
| periodicity of data                                   | various types           | various types             | various types                |
| time synchronization requirements                     | milliseconds (1 digit)  | milliseconds (1 digit)    | microseconds (2-3 digits)    |
| dynamic network configuration                         | very little             | little                    | partially                    |

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# Classes of Ethernet devices

Example use case: Object detection camera in system context (simplified illus.)



# Classes of Ethernet devices

## Types of different TSN automotive implementation: Profiles?

- › TSN endpoints
  - › single port talker/listener
    - › focus: safety relevant data processing e.g. server, antenna module
    - › other:
  - › single port talker only (back channel data is not time critical)
    - › focus: safety relevant sensors for ADAS (Cameras, Radars, Lidars,...)
    - › other: microphone
  - › single port listener only (back channel data is not time critical)
    - › focus: safety relevant actuators (steering, braking, display)
    - › other: speaker

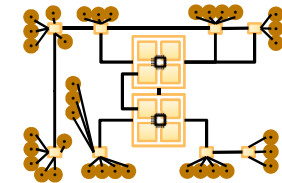
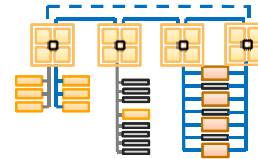
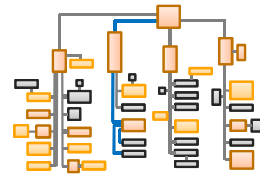


# Classes of Ethernet devices

Types of different TSN automotive implementation: Profiles?

- › TSN bridges
  - › 3-port bridge (supports ring topology)
  - › access bridge (interface to outside vehicle networks)
    - › focus: security
  - › aggregation bridge (low port count)
  - › aggregation bridge (high port count)

# Classes of Ethernet devices



| Types                            |      |      |      |
|----------------------------------|------|------|------|
| no. of talker endpoints only     | < 10 | < 20 | > 25 |
| no. of listener endpoints only   | < 5  | < 10 | < 20 |
| no. of talker/listener endpoints | < 5  | < 10 | < 10 |
| no. of 3-port bridges            | 0    | < 5  | < 5  |
| no. of aggregation bridges mid   | 1-2  | < 5  | < 10 |
| no. of aggregation bridges high  | 0    | < 3  | < 5  |

*Information here is based on educated guess, no full centralized architectures are in development today yet*