Industrial Automation Bus Topology

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Purpose

 The purpose of this presentation is to examine bus topology relevance for Industrial Automation

Reference

Industrial Automation and Emerging Single-pair Ethernet

<u>http://www.ieee802.org/3/10SPE/public/adhoc/brandt</u> <u>083116_10SPE_01_adhoc.pdf</u>

- Describes:
 - Substantial market forecasts exist for Industrial Internet of Things
 - In-cabinet, On-machine, and Plant-wide applications
 - Components that are very cost sensitive, have low performance and short distance requirements

In-cabinet Devices



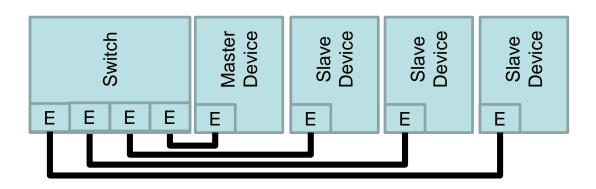


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In-cabinet characteristics

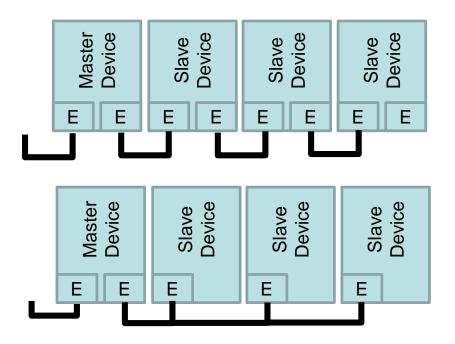
- Many densely packed devices
- Default is hardwired
 - Devices becoming "smart", driving network connection (via CAN, LIN, etc.)
- Low performance requirements
- <u>Very</u> cost sensitive devices
- "Device" fieldbus networks are commonly <u>bus topology</u>
 - Total length < 50m

Average interfaces per device



<u>Star</u>

- Many switches
- Bundles of wires
- 2 interfaces per device



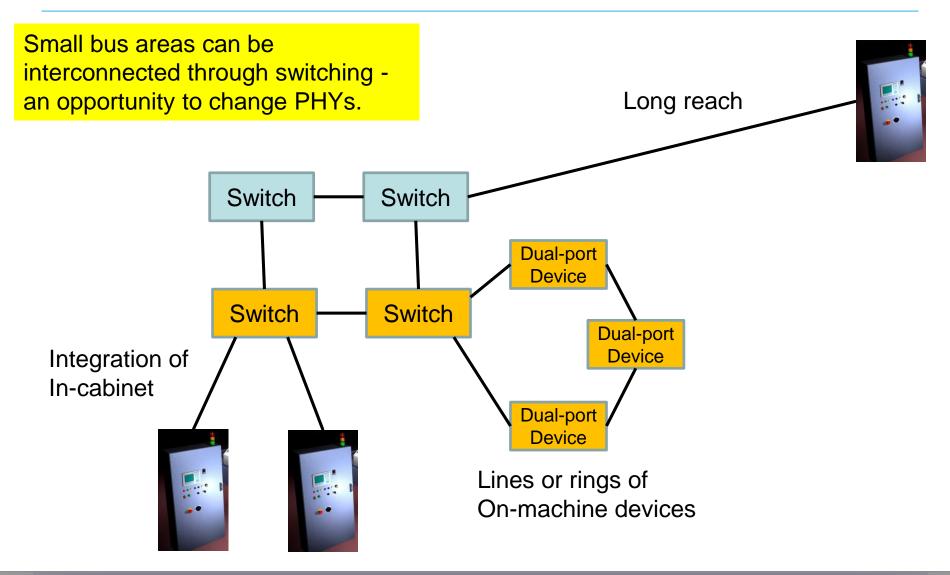
<u>Linear</u>

- Few switches
- No bundles of wires
- 2 interfaces per device

<u>Bus</u>

- Few switches
- No bundles of wires
- Average approaches 1 interface per device

Example topology



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Power

- In-cabinet power:
 - 1-pair Ethernet + PoDL
 - Communication and sensors
 - Separate power in the same cable
 - Actuators
 - Saves additional wiring

Determinism

- First thought on bus is CSMA/CD which creates collisions and determinism issues
- But:
 - Applications are Master/Slave
 - Traffic is periodic
 - Timing can be controlled to avoid collisions
 - IEEE 802.1 TSN scheduling techniques could be applied
- Low latency event traffic and client/server efficiency may present technical challenges

Conclusions

- In-cabinet industrial automation could benefit from a bus Ethernet solution
- There may be a good match with transportation requirements in cost sensitivity and reach