# Changing assigned Class through DLL v101

> **Info (not part of baseline)**
>
> In the legacy state diagram, the PD would move from the MDI_POWER1 to the MDI_POWER2 state if it started out in Class 3 and successfully increased its power budget through LLDP. The legacy SD enforces that only PDs that request Class 4 are able to move to a higher power state. ~~Which is correct....~~
>
> This currently does not work: changes through DLL are not reflected in the pd_max_power variable. This baseline implements that same functionality for the Type 3/4 state diagrams. For now focus is on single-signature, once this is stable, a sync with the dual-signature state diagrams needs to happen.

## PSE section

### 33.2.5.9 Type 3 and Type 4 variables

*Add variable as follows:*

pse_power_update

>A variable that is set when the PSEAllocatedPowerValue in the DLL state diagram in Figure 33–46 has been updated.
>Values:
>
>>FALSE: The value of PSEAllocatedPowerValue has not changed.
>>TRUE: The value of PSEAllocatedPowerValue has changed.

### 33.2.5.11 Type 3 and Type 4 functions

*Add function as follows:*

do_update_pd_allocated_pwr

>A function that updates the pd_allocated_value based on the value of PSEAllocatedPowerValue as defined in Table 33–14. This function returns the following variable:
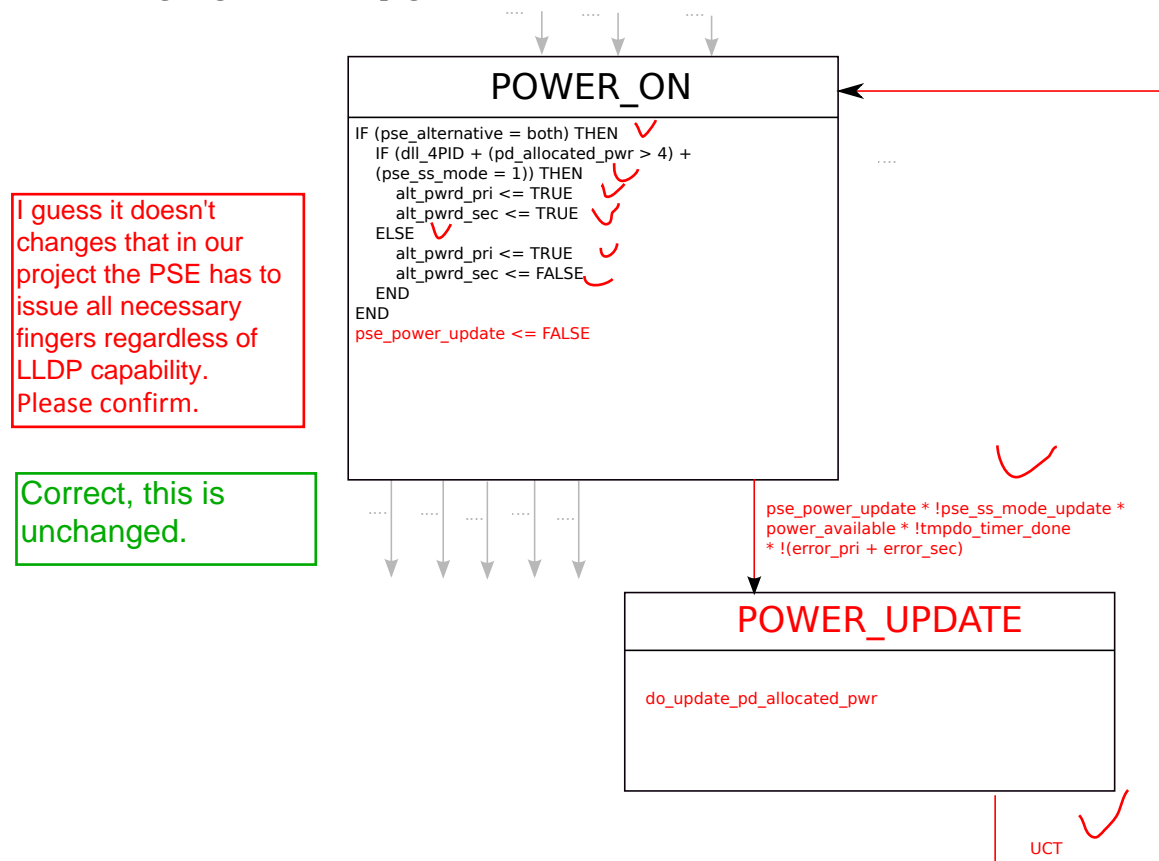>
>pd_allocated_pwr: this variable indicates the Class assigned to the PD.
>Values:
>
>>1: Class 1
>>2: Class 2
>>3: Class 3
>>4: Class 4
>>5: Class 5
>>6: Class 6
>>7: Class 7
>>8: Class 8

### 33.2.5.12 Type 3 and Type 4 state diagrams

*Change Figure 33–15 on page 95 as follows:*

```
                  ....      ....      ....
                   |         |         |
                   v         v         v
        +-----------------------------------------+
        |              POWER_ON                   |  <------+
        |-----------------------------------------|         |
        | IF (pse_alternative = both) THEN        |         |
        |   IF (dll_4PID + (pd_allocated_pwr > 4) +|        |
        |   (pse_ss_mode = 1)) THEN               |   ....  |
        |     alt_pwrd_pri <= TRUE                |         |
        |     alt_pwrd_sec <= TRUE                |         |
        |   ELSE                                   |         |
        |     alt_pwrd_pri <= TRUE                |         |
        |     alt_pwrd_sec <= FALSE               |         |
        |   END                                    |         |
        | END                                      |         |
        | pse_power_update <= FALSE                |         |
        |                                          |         |
        |                                          |         |
        +-----------------------------------------+         |
          |      |      |      |                             |
          v      v      v      v      pse_power_update * !pse_ss_mode_update *
         ....   ....  ....  ....      power_available * !tmpdo_timer_done
                                      * !(error_pri + error_sec)
                             +-------------------------------+
                             |        POWER_UPDATE           |
                             |-------------------------------|
                             |                               |
                             |   do_update_pd_allocated_pwr  |
                             |                               |
                             |                               |
                             +-------------------------------+

                                      UCT
```

**I guess it doesn't changes that in our project the PSE has to issue all necessary fingers regardless of LLDP capability. Please confirm.**

**Correct, this is unchanged.**

# PD section

### 33.3.3.8 Type 3 and Type 4 single-signature variables

> **Info (not part of baseline)**
>
> Variable summary:
>
> | | |
> |---|---|
> | pd_req_pwr | A constant that denotes the requested Class of the PD. This variable determines what signatures present_class_sig_A and present_class_sig_B are. It is also the maximum power the PD can ever draw. |
> | pse_power_level | A variable the counts the number of classification events. One event sets it to 3. Two or three events sets it to 4. Four events sets it to 6. Five events sets it to 8. These values are chosen such that it becomes easy to derive pd_max_power. |
> | pse_assigned_class | Is the Class assigned by the PSE. This is initially set based on the min(pse_power_level, pd_req_class) but can change after a DLL negotiation. Note that the assigned Class can be higher than the requested Class. See pd_max_power. |
> | pd_max_power | This variable is the maximum power limit of the PD. In normal operation this will be equal to the pse_assigned_class variable. In the exceptional case that the PSE has assigned a higher Class than the requested Class, this variable will be equal to the requested Class and thus prevent the PD from going above its Physical Layer requested power. |

*Add the following variables:*

**In the exceptional case: Do you mean to extended power?**

pse_assigned_class

A variable that indicates the assigned Class. This variable is initially set by Physical Layer classification and may be updated through DLL classification.
Values:

**append to teh end of this text: "to lower values than the initially set by Physical Layer classification"**

   1: Class 1
   2: Class 2
   3: Class 3
   4: Class 4

**This is true, but is already handled by a SHALL, why do we keep repeating this ? Yair: Otherwise the intent will not be clear. This is state machine variable and has priority over text that doesnt belong to the state**

**Power demotion, not ext. pwr.**

2

5: Class 5
6: Class 6
7: Class 7
8: Class 8

pd_power_update

A variable that is set when the PDMaxPowerValue in the DLL state diagram in Figure 33–49 has been updated.
Values:
FALSE: The value of PDMaxPowerValue has not changed.
TRUE: The value of PDMaxPowerValue has changed.

### 33.3.3.10 Type 3 and Type 4 single-signature functions

***Add the following function:***

do_update_pse_assigned_class

A function that updates the pse_assigned_class based on the value of PDMaxPowerValue as defined in Table 33–24.
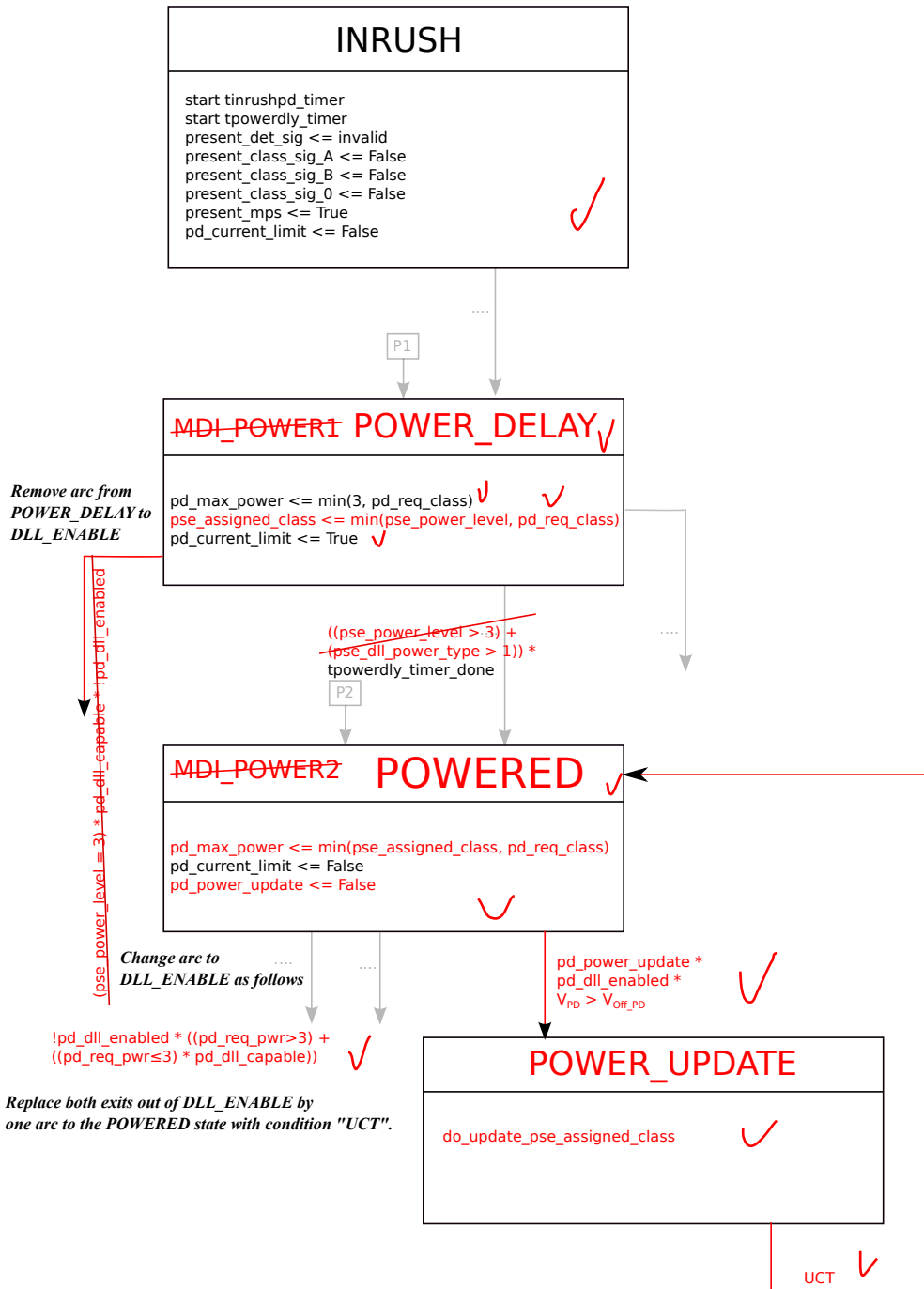This function returns the following variable:

pse_assigned_class: this variable indicates the Class assigned to the PD.
Values:

1: Class 1
2: Class 2
3: Class 3
4: Class 4
5: Class 5
6: Class 6
7: Class 7
8: Class 8

## 33.3.3.11 Type 3 and Type 4 single-signature PD state diagrams

*Change Figure 33–32 as follows:*



**INRUSH**

start tinrushpd_timer
start tpowerdly_timer
present_det_sig <= invalid
present_class_sig_A <= False
present_class_sig_B <= False
present_class_sig_0 <= False
present_mps <= True
pd_current_limit <= False

P1

~~MDI_POWER1~~ **POWER_DELAY**

pd_max_power <= min(3, pd_req_class)
pse_assigned_class <= min(pse_power_level, pd_req_class)
pd_current_limit <= True

*Remove arc from POWER_DELAY to DLL_ENABLE*

(pse_power_level = 3) * pd_dll_capable * !pd_dll_enabled

~~((pse_power_level > 3) +~~ ~~(pse_dll_power_type > 1)) *~~ tpowerdly_timer_done

P2

~~MDI_POWER2~~ **POWERED**

pd_max_power <= min(pse_assigned_class, pd_req_class)
pd_current_limit <= False
pd_power_update <= False

*Change arc to DLL_ENABLE as follows*

!pd_dll_enabled * ((pd_req_pwr>3) +
((pd_req_pwr≤3) * pd_dll_capable))

*Replace both exits out of DLL_ENABLE by one arc to the POWERED state with condition "UCT".*

pd_power_update *
pd_dll_enabled *
$V_{PD} > V_{Off\_PD}$

**POWER_UPDATE**

do_update_pse_assigned_class

UCT

---

**Info (not part of baseline)**

The following non-normative text is added to explain that it is not permitted to draw more power than the requested Class. The actual requirement is in the PD state diagram, as well as on D2.2, page 153, line 47.

---

## 33.3.6 PD classifications

*Make changes to the text as follows:*

After a successful DLL classification, the assigned Class changes depending on the value of PDMaxPowerValue variable, as defined in Table 33–24. A PD may be able to get a Class assigned that is higher than its requested Class, however it is not permitted to draw more power than what corresponds to the PDs requested Class.

Why to allow it in the text???

Fair point, I will change/delete it.

4

### 33.5.3.6 Power control S state diagrams

*Change Figure 33–46 as follows:*

....

```
┌─────────────────────────────────────────────┐
│              MIRROR UPDATE                    │
├─────────────────────────────────────────────┤
│                                               │
│  PSEAllocatedPowerValue <= PSE_NEW_VALUE      │
│  PDRequestedPowerValueEcho <= TempVar         │
│  pse_power_update <= True                     │
│                                               │
└─────────────────────────────────────────────┘
```

....

*Change Figure 33–49 as follows:*

```
┌─────────────────────────────────────────────┐
│         PD POWER REALLOCATION 2               │
├─────────────────────────────────────────────┤
│                                               │
│  PDMaxPowerValue <= PDRequestedPowerValue     │
│  pd_power_update <= True                       │
│                                               │
└─────────────────────────────────────────────┘
```

```
┌─────────────────────────────────────────────┐
│         PD POWER REALLOCATION 1               │
├─────────────────────────────────────────────┤
│                                               │
│  PDMaxPowerValue <= PD_NEW_VALUE              │
│  pd_power_update <= True                       │
│                                               │
└─────────────────────────────────────────────┘
```

....