## 1 <u>Comment #65, #44 (Page 201, Line 8 clause 145.3.8.10)</u>

In the text "Single-signature PDs shall not exceed ICon-2P-unb for longer than TCUT-2P min and 5 %
duty cycle, and shall not exceed IPeak-2P-unb, as defined in Table 145–16 on any pair when PD PI
pairs...", there are few problems that makes the spec broken:

- 5 1) IPeak-2P-unb is not defined in Table 145-16. It is defined by Equation 145-12.
- 2) IPeak-2P-unb is a PSE parameter and not a PD parameter. We need separate parameter name and content
   for the PD i.e. IPeak\_PD-2P\_unb for PD (as we did for Icon and named it Icon\_PD for the PD).
- 3) Equation 145-12 belongs to PSE section and set the actual Ipeak-2P\_unb current which is not the maximum
   Ipeak-2P\_unb since it depends on PSE voltage. PDs must be designed to the maximum Ipeak-2P\_ub (and to

12 the maximum Icon-2P\_unb as we did for PD during last cycle) due to the fact that the PD doesn't control

- 13 the actual Ipeak-2P-unb since it doesn't have the knowledge of PSE voltage and more important, they can
- 14 be connected to PSE with the minimum voltage which will create the maximum possible current.
- 15 As a result of the above arguments we need to define new PD parameters name for Icon-2P\_unb and Ipeak-
- 16 2P\_unb i.e. Icon\_PD-2P\_unb and Ipeak\_PD-2P\_unb with fixed maximum values that are PD parameters and not
- 17 depend on PSE (as we did per the concept we adopt on march for comment #320 from D2.3, see
- 18 yseboodt\_08\_0315\_peakunbalance.pdf arguments that has generated the new Equation 145-28 and 145-29).
- 19 Suggested Remedy

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# <mark>(BASELINE STARTS HERE</mark>]

### 2 1. Add the following rows to Table 145-28

Item	Parameter	Symbol	Unit	Min	Max	PD Type	Additional information
X1	Pairset current continuous including unbalance effect per the assigned Class for a single-signature PDs						
	Class 1 to 4	Icon_PD-2P-	Α		Icon_PD <sup>a</sup>	3, 4	See 145.3.8.X and
	Class 5	unb			0.55	3, 4	145.3.8.10
	Class 6				0.682	3, 4	
	Class 7				0.781	4	
	Class 8				0.932	4	
Y1 Pairset peak current including unbalance effect per the assigned				e assigned Cla	lass for a single-signature PDs		
	Class 1 to 4	Ipeak_PD-	Α		IPeak_PD	3, 4	See 145.3.8.X and
	Class 5	2P-unb			0.560	3, 4	145.3.8.10
	Class 6				0.700	3, 4	
	Class 7				0.827	4	
	Class 8				0.988	4	
Z1	Overload time	T <sub>cut_PD-2P</sub>	ms		50	3, 4	See 145.3.8.X,
	limit per						145.3.8.4 and
	pairset						145.3.8.10

<sup>a</sup>The Icon\_PD value is higher than the value for Class 5 as unbalance for Class 4 is not restricted.

## 4 2. Make the following changes:

### 5 145.3.8.4 Peak operating power

6 VOverload-2P is the PD PI voltage when the PD is drawing the permissible PPeak\_PD for single-signature PDs, or PPeak\_PD-2P
7 for dual-signature PDs.

At any static voltage at the PI, and any PD operating condition, with the exception described in 145.3.8.4.1, the peak power
 for single-signature PDs shall not exceed PClass\_PD for more than <u>T<sub>cut\_PD-2P</sub>\_TCUT-2P min</u>, as defined in <u>Table 145–16\_Table</u>
 <u>145–28</u>-and 5% duty cycle. Peak operating power shall not exceed PPeak\_PD.

At any static voltage at the PI, and any PD operating condition, with the exception described in 145.3.8.4.1, the peak power
 for a dual-signature PD shall not exceed PClass\_PD-2P for more than <u>T<sub>cut\_PD-2P</sub>\_TCUT-2P min</u>, as defined in <u>Table 145–28</u><u>Table</u>
 <u>145–16</u> and 5% duty cycle. Peak operating power shall not exceed PPeak\_PD-2P.

- 14 NOTE—The duty cycle of the peak current is calculated using any sliding window with a width of 1 s.
- 15 Peak power is defined in Table 145–28 and depends on the Class assigned by the PSE. The equations in Table 145–28 are
- used to approximate the ratiometric peak powers of Class 1 through Class 8. These equations may be used to calculate
- PPeak\_PD or PPeak\_PD-2P for Data Link Layer classification by substituting PClass\_PD or PClass\_PD-2P with PDMaxPowerValue
   and for Autoclass by substituting PClass\_PD with PAutoclass\_PD.

### 19 145.3.8.4.1 Peak operating power exceptions

- 20 For Class 6 and Class 8 single-signature PDs and for Class 5 dual-signature PDs, when additional information is available to
- 21 the PD regarding actual channel DC resistance between the PSE PI and the PD PI, in any operating condition with any static
- voltage at the PI, the peak power shall not exceed PPort\_PD for single-sig-nature PDs and PPort\_PD-2P for dual-signature PDs
- 23 at the **PSE PI** PD PI for more than <u>T<sub>cut PD-2P</sub> TCUT-2P min</u>, as defined in <u>Table 145–28</u> Table 145–16 and with 5% duty cycle.
- Peak operating power shall not exceed  $1.05 \times PPort_PD$  for single-signature PDs and shall not exceed  $1.05 \times PPort_PD-2P$  for
- 25 dual-signature PDs on each pairset.



### 1

- Operating under 145.3.8.4.1 conditions is allowed if PPeak\_PD and PPeak\_PD-2P requirements are met and the total input
   power is less than or equal to PClass or PClass-2P at the PSE PI respectively when calculated over a 1 second interval.
- 3 145.3.8.10 PD pair-to-pair current unbalance
- 4 5

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Single-signature PDs shall not exceed ICon 2P unb ICon PD-2P unb as defined in Table 145-28 for longer than TCUT-2P T<sub>CUT PD-2P</sub>\_min and 5 % duty cycle, and shall not exceed IPeak 2P unb IPeak PD -2P unb, as defined in Table 145-16 Table 145-28 -on any pair when PD PI pairs of the same polarity are connected to any voltage in the range of VPort\_PSE-2P through two common mode resistances, Rsource\_min and Rsource\_max, as defined in Equation (145–27) and shown in Figure 145–32.

9 10

Dual-signature PDs shall not exceed ICon\_PD-2P as defined in Equation (145–28) Equation (145–Y8) for longer than
TCUT-2PT<sub>CUT\_PD-2P</sub> as defined in Table 145-28-\_min and 5 % duty cycle, as defined in Table 145–16, and shall not exceed
IPeak\_PD-2P as defined by Equation (145-Y10) on any pair when PD PI pairs of the same polarity are connected to any
voltage in the range of VPort\_PSE-2P through two common mode resistances, Rsource\_min and Rsource\_max, as defined
in Equation (145–27) and shown in Figure 145–32.

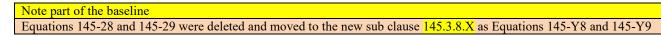
16 NOTE—The duty cycle of the peak current is calculated using any sliding window with a width of 1 second.

$$R_{\text{source}\_max} = \left\{ (-0.03 \times R_{\text{source}\_min} + 1.324) \times R_{\text{source}\_min} \text{ for } (0.145\Omega \le R_{\text{source}\_min} \le 5.47\Omega) \right\}_{\Omega}^{(145-27)}$$



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RPD\_min, RPD\_max ensures that along with any other parts of the system, i.e., channel (cables and connectors) and the PSE,
 the maximum pair current including unbalance does not exceed ICon\_2P\_unb\_Icon\_PD-2P-unb\_as defined in Table 145–16
 Table 145-28 during normal operating conditions. See Annex 145A.

## 28 3. Add the following text after Table 145-28 and before 145.3.8.10

#### Note part of the baseline

I have used the same concept and text used in the PSE side so the concept is proven and clear. The main changes made to have separate variable names for the PD as done in many cases in the spec to separate PSE variables and PD variables to be independent

29

## 30 145.3.8.X Continuous output current capability in the POWERED state

- 31 IPort\_PD-2P and IPort\_PD-2P\_other are the currents on the pairs with the same polarity of the two pairsets and are defined in
- **32** Equation (145-Y1) and Equation (145-Y2).



1 
$$I_{Port\_PD-2P} = \begin{cases} \text{IPort\_PD} - 2P\_\text{modeA} & \text{for } \mod e & A \\ \text{IPort\_PD} - 2P\_\text{modeB} & \text{for } \mod e & B \end{cases} \right\}_{A}$$
 (145-Y5)

2

3 
$$I_{Port\_PD-2P\_other} = \begin{cases} IPort\_PD - 2P\_modeB & for mod e B \\ IPort\_PD - 2P\_modeA & for mod e A \end{cases}$$
(145-Y6)

4 IPort\_PD is the total current on both pairs with the same polarity and is defined in Equation (145-Y7).
5

$$I_{Port\_PD} = \left\{ I_{Port\_PD-2P} + I_{Port\_PD-2P\_other} \right\}_{A}$$
(145-Y7)

7 where

8 IPort\_PD-2P is the input current consumed by mode A or mode B

9 IPort\_PD-2P is the input current consumed by mode B or mode A10

PDs shall be able to support Icon\_PD-2P, the current the PD supports on each powered pairset, as defined in Equation (145–12 Y8).

13

#### Note part of the baseline We could use PClass\_PD/VPD instead of ICon\_PD in Equation 145-7a however the requirements for 4-pairs are better understood with the next introduction using Icon\_PD and Icon\_PD-2P\_unb.

14

15 When powering a single-signature PD over 4 pairs, a PD supports:

- 16 A total current of ICon\_PD, defined in Equation (145– Y7a), over both pairs with the same polarity;
- A minimum current of Icon\_PD-2P\_unb over one of the pairs of the same polarity under maximum unbalance condition
   (see 145.3.8.10) in the POWERED state.

19 
$$I_{Con_PD} = \left\{ \frac{P_{Class_PD}}{V_{PD}} \right\}_{A}$$
 (145-Y7a)  
20  
21 where  
22  $P_{Class_PD}$  is PClass\_PD as defined in Table 145-28  
23  $V_{PD}$  is the voltage on the pairset at the PD PI as defined in 145.1.3.

24

25

26	$I_{Con_PD-2P} = $	I <sub>Con_PD</sub>	when in 2– pair mode	(145-Y8)
		$\min(I_{Con_PD} - I_{Port_PD-2P\_other}, I_{Con_PD-2P\_unb})$	when a single-signature PD is powere in $4 - pair \mod -2P$	
		$P_{Class_PD2P}/V_{PD}$	when a dual-signature PD is powere in 4-pair mode	A

27

28	where		
29		Icon_PD	is the total current a PD is able to consume as defined in Equation (145-Y7a)
30		VPD	is the voltage on the pairset at the PD PI as defined in 145.1.3.
31		<i>I</i> Port_PD-2P_other	is the output current on the other pairset as defined in Equation (145-Y6).
32		Icon_PD-2P_unb	is the minimum current due to unbalance effects that a PD must support on a pairset when
33			powering a single-signature PD over 4 pairs as defined in Table 145-28
34		PClass_PD-2P	is PClass_PD-2P as defined in Table 145-28.
35			

35 36 37

38 39

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The PD shall support the AC current waveform parameter IPeak\_PD-2P, defined in Equation (145–Y9), on each powered pairset, while within the operating voltage range of VPort\_PD-2P, for a minimum of TCUT\_PD-2P and a duty cycle of at least 5%.



1	$I_{Peak\_PD-2P} = \begin{cases} P_{Peak\_PD} / Vpd & when in 2 - pair \mod e \\ \min(P_{Peak\_PD} / Vpd - I_{Port\_PD-2P\_other}, I_{Peak\_PD-2P\_umb}) & when a \sin gle - signature PD is powere in 4 - pair \mod e \\ P_{Peak\_PD-2P} / Vpd & when a dual - signature PD is powere in 4 - pair \mod e \\ \end{cases} $ $(145-Y9)$
2	$\left(\begin{array}{c}P_{eak\_PD-2P}\\P_{eak\_PD-2P}\end{array}\right) Vpd \qquad when a dual - signature PD is powere in 4 - pair mode \right)_{A}$
2	
3 4	where <i>Ppeak PD</i> is the total peak power a PD may consume per Table 145-28
5	IPort_PD-2P_other is the output current on the other pairset as defined in Equation (145-Y6).
6 7	<i>IP</i> eak_PD-2P_unb is the minimum current due to unbalance effects a PD must support on a pairset as defined in Table
/ 0	145-28 during peak operating power condition. See 145.3.8.4. VPD is the voltage on the pairset at the PD PI as defined in 145.1.3.
8 9	<i>P</i> Peak_PD-2P is the peak power a dual-signature PD may draw per its assigned Class on a pair-set; see Table 145–28
10	
11	IPeak, defined in Equation (145–Y10), is the total current of the powered pairs with the same polarity that a PD supports,
12 13	when powering a PD over 2-pairs or powering a single-signature PD over 4 pairs.
14	$I_{Peak\_PD} = \left\{ \frac{P_{Peak\_PD}}{V_{PD}} \right\}_{A} $ (145-Y10)
15	
16	where
17	VPD is the voltage on the pairset at the PD PI as defined in 145.1.3.
18	<i>P</i> Peak_PD is the total peak power a PD may draw for its Class; see Table 145–28
19	
20	4. Replace Tcut-2P with Tcut_PD-2P in the following locations:
21	PD50, PD51, PD52, PD56, PD69 and PD70.
22	
23	5. Replace the reference to Table 16 with Table 28in the following locations: PD51 and PD56
24	

