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# **On The Need For Precoder Updates In Data Mode: Laboratory Results**

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# Introduction

- **There are two questions surrounding the use of TH precoding for 10GBase-T**
  - Initialization of the precoder
  - Data mode adaptation
- **This contribution addresses the latter by presenting laboratory results where the precoder and DFE are fixed in data mode**
- **The experiment uses 4D-TCM/PAM10 transceivers operating at 10Gbps**
- **Results extendable to TH precoded systems**

# System Under Test

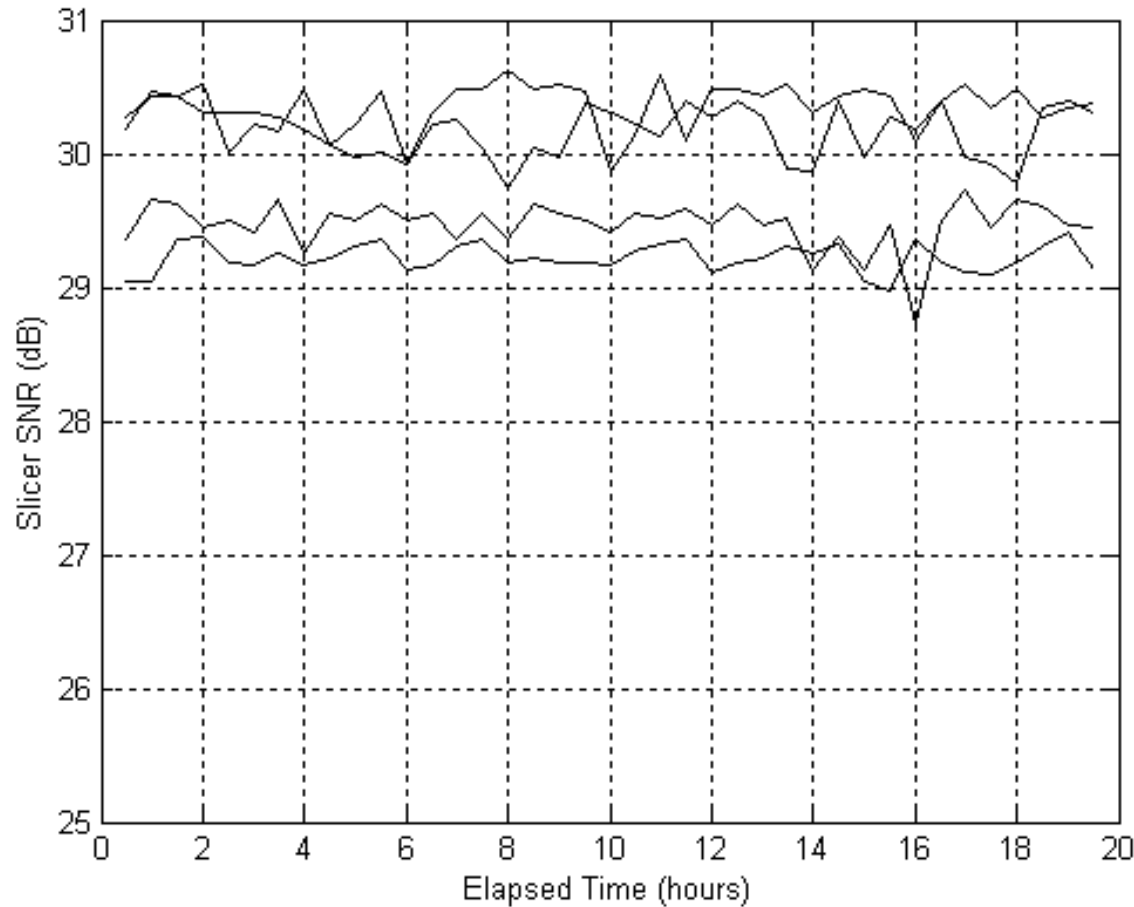
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- **4D-TCM/PAM10**
  - Linear precoder
  - Residual DFE
- **The linear precoder was adapted and then fixed as part of startup**
- **The residual DFE was allowed to adapt for one billion frames in data mode and then frozen**
- **All other control loops were allowed to continue adapting, e.g., FFE, TRL, etc.**

# Lab Setup

- **Data mode consisted of duplex 10G Ethernet traffic generated with Spirent test equipment**
- **1400 byte frames**
- **Periodically measured slicer SNR on all four pairs**
- **Measurement period was 30 minutes**
- **Estimation interval was 80 microseconds**
- **Test time was 19.5 hours**
- **65 billion frames transmitted**
- **1 CRC error recorded**
- **Channel configuration was 45m of Cat6**

# Measured Slicer SNR



Std. Dev.

A = .20 dB

B = .19 dB

C = .11 dB

D = .18 dB

12:00 noon

7:30 am

# Summary

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- **Laboratory data has been presented that illustrated over an extended period of time that the slicer SNR does not vary appreciably**
- **Thus, with modest receiver equalization there is no need to update the TH precoder**