



Proposed Modifications to IEEE P802.3az/D0.9 Clause 40

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IEEE P802.3az Task Force Meeting
Seoul, KR
September 2008

Motivation

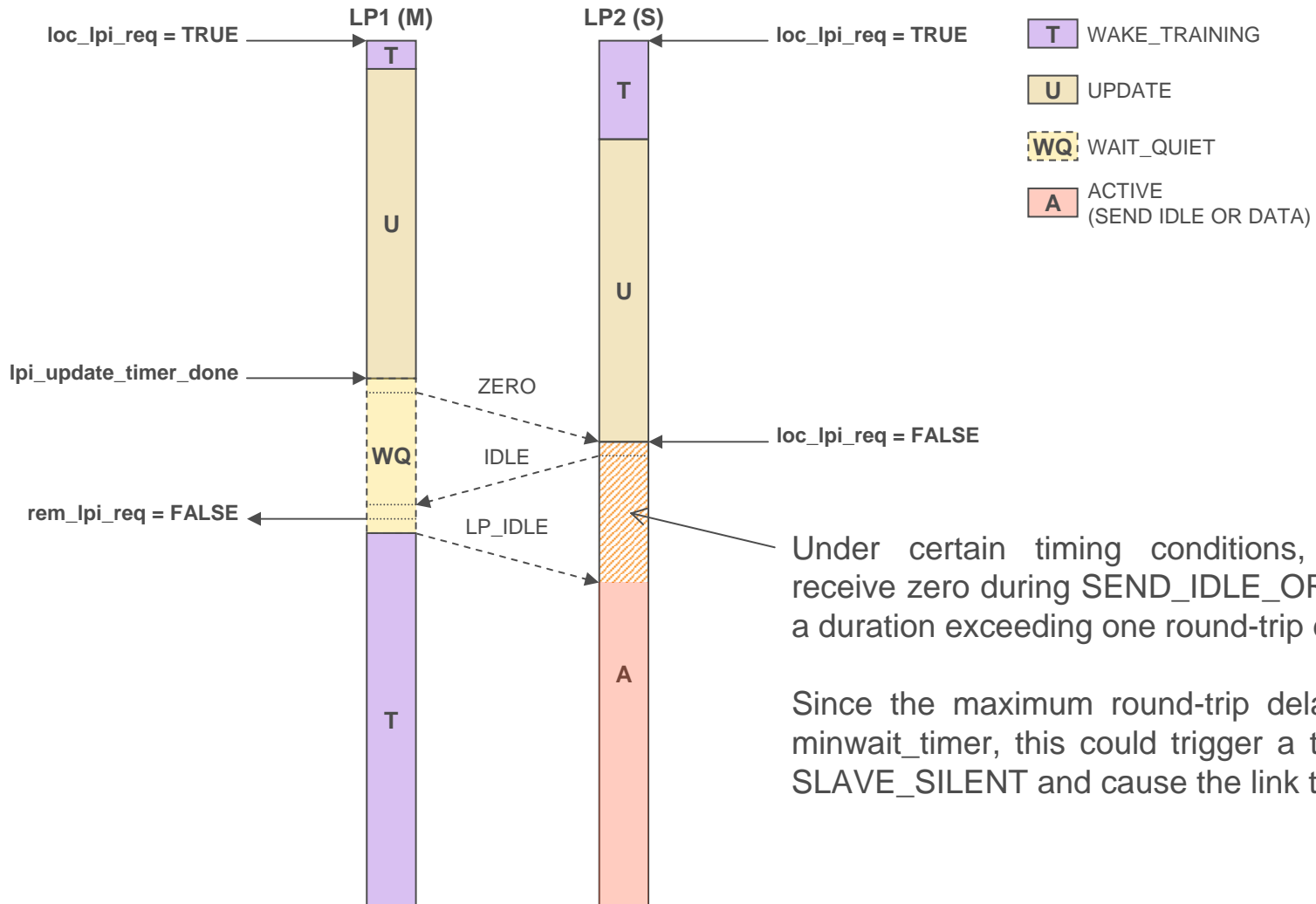
- It has been pointed out* that, per the current PHY Control state diagram, there is a possibility that the local device could receive zero during SEND_IDLE_OR_DATA when the local device de-asserts loc_lpi_req during UPDATE but the link partner transitions to WAIT_QUIET prior to receiving the notification
 - Under certain timing conditions, the duration of zero could be on the order of the round-trip delay, leading to a link restart
- It has also been pointed out* that there is a possibility that the SLAVE can bypass the WAKE_SILENT state and cause the WAKE process to fail
- Finally, it has been pointed out that the roles of SLEEP and UPDATE are similar so they may be consolidated into a single state
 - This is reinforced by the fact that lpi_sleep_timer has recently been assigned a range similar to lpi_update_timer

* Joseph Chou, Realtek

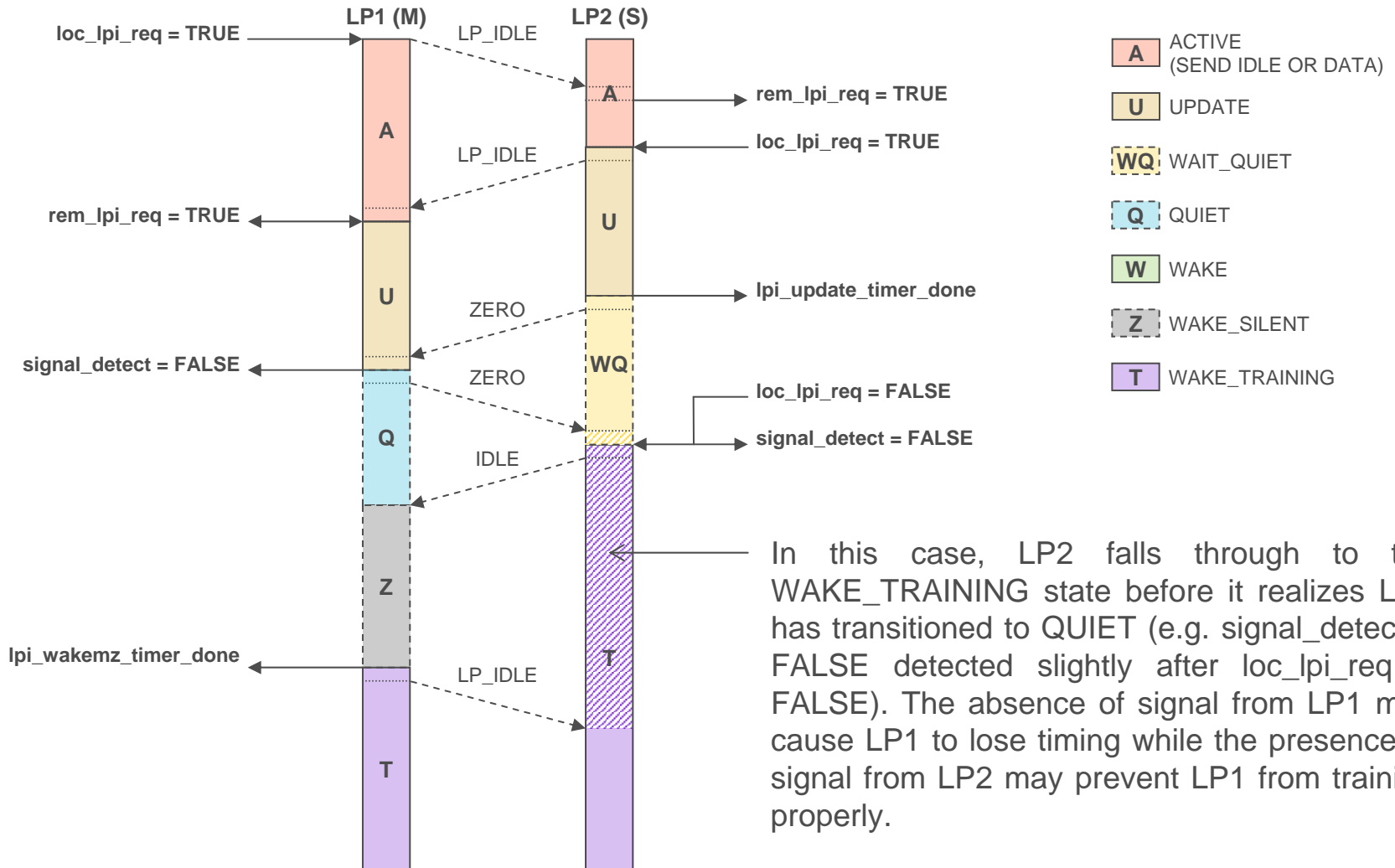
Before we begin...

- State diagram transitions are not gated by a clock and it is possible to instantaneously “fall through” states
- For example, starting at UPDATE...
 - signal_detect = FALSE causes fall through to QUIET
 - loc_lpi_req = FALSE causes fall through to WAKE
- Interpreting the state machine in this way leads one to the conclusion that Case 1 in chou_01_0908.pdf is not an issue

chou_01_0908: Case 2

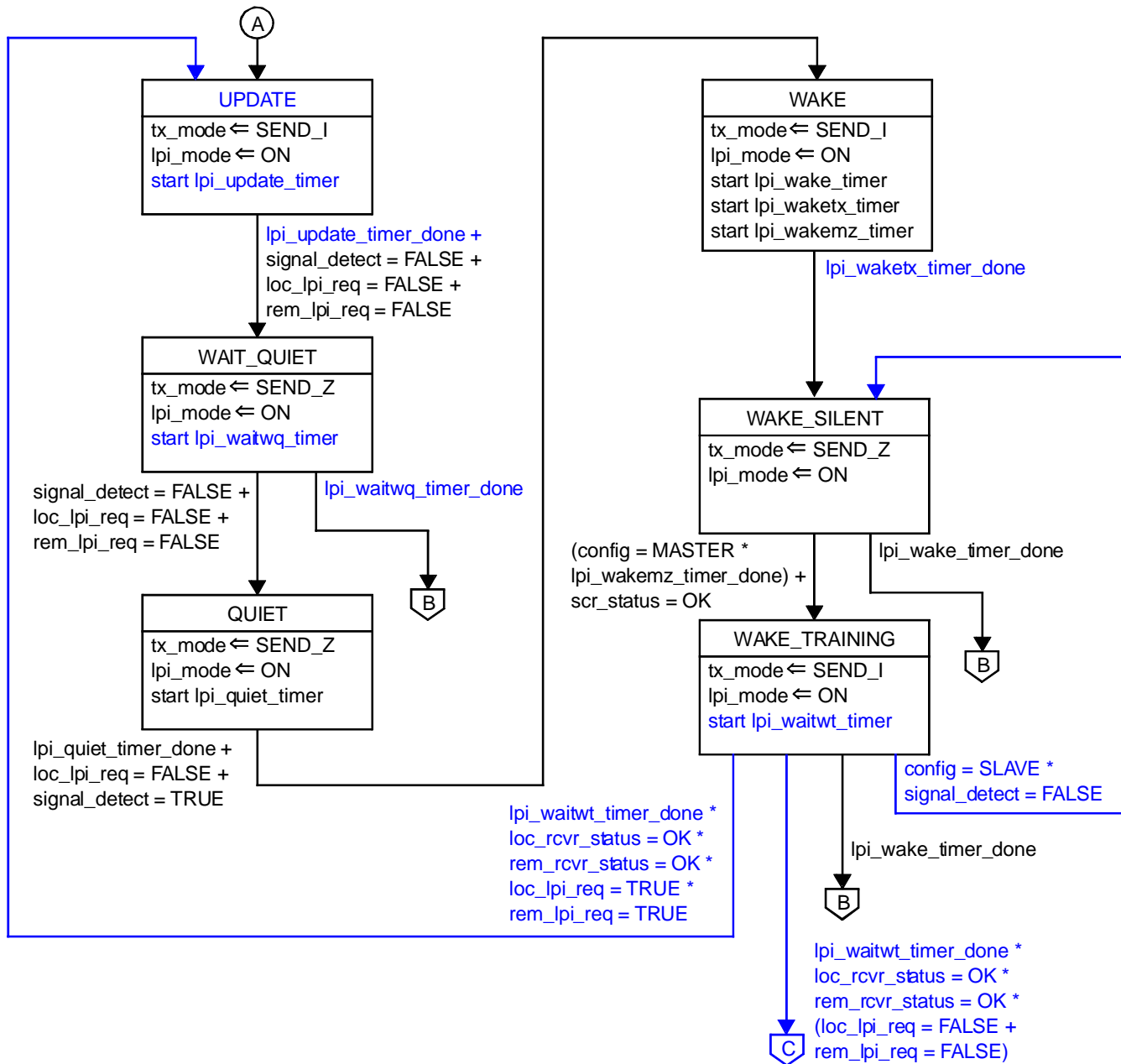


chou_01_0908.pdf: Case 3



Corrective actions

- Refer to the proposed state diagram in the next slide...
- Note – changes recommended in grimwood_01_0908.pdf included for completeness



Supporting edits

- **40.4.2.4:** Upon activation of the low power mode, the PHY Control asserts `tx_mode = SEND_I` for period of time defined by ~~`lpi_sleep_timer`~~`lpi_update_timer` which allows the remote PHY to prepare for the transition to the `WAIT_QUIET` state. When ~~`lpi_sleep_timer`~~`lpi_update_timer` expires, PHY Control asserts `tx_mode = SEND_Z` and transmission ceases.
- **40.4.5.2:** Delete `lpi_sleep_timer`
- **40.4.5.2:** Replace `lpi_wait_timer` with `lpi_waitwt_timer`
 - This timer defines the minimum time the PHY must remain in the `WAKE_TRAINING` state.
 - Values: The condition `lpi_waitwt_timer_done` becomes true upon timer expiration.
 - Duration: This timer shall have a period between 1.8 μ s and 2.0 μ s.

Supporting edits (continued)

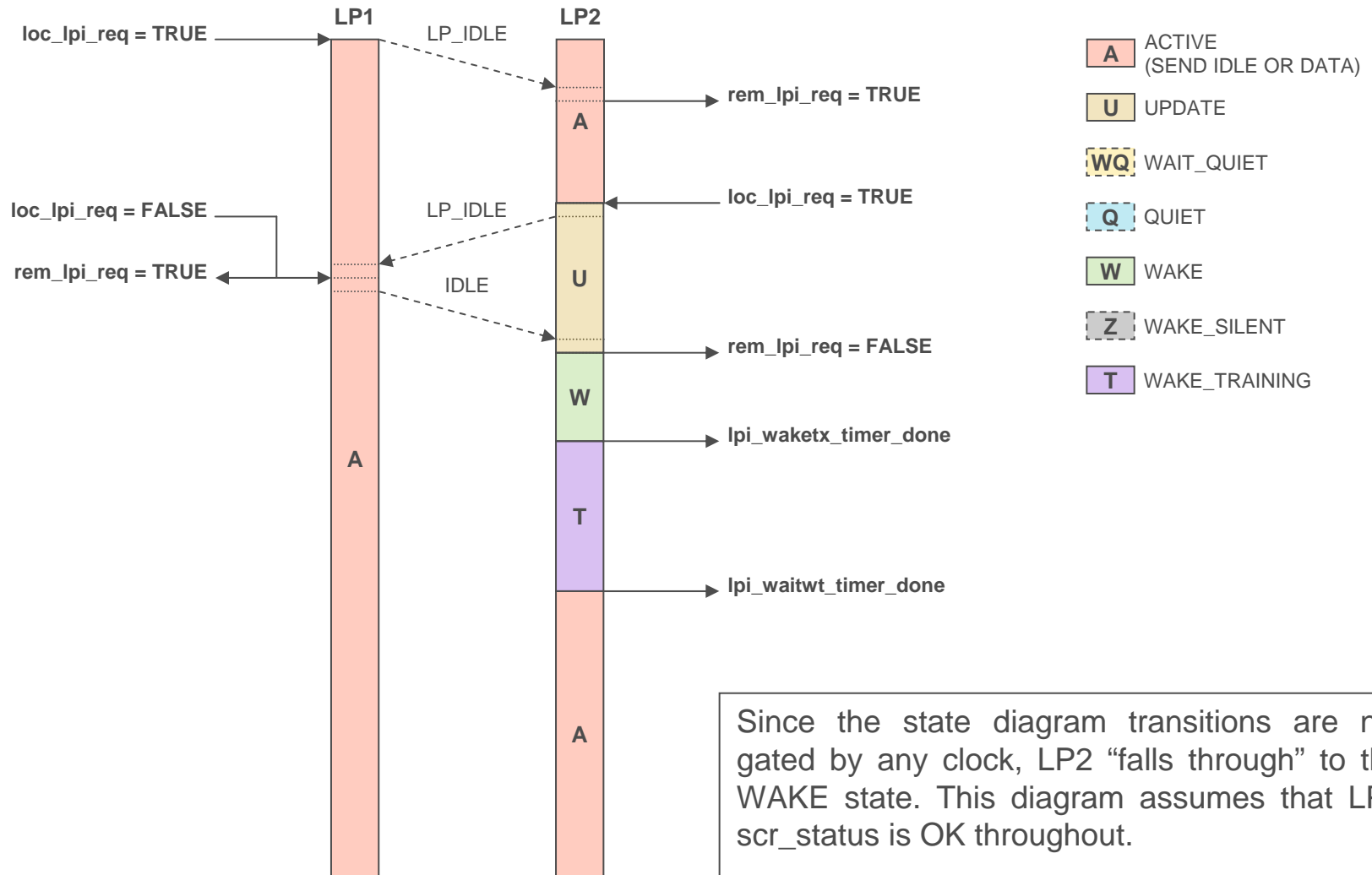
- **40.4.5.2:** Add `lpi_waitwq_timer`

This timer defines the maximum time the PHY will dwell in the WAIT_QUIET state before forcing the link to restart.

Values: The condition `lpi_waitwq_timer_done` becomes true upon timer expiration.

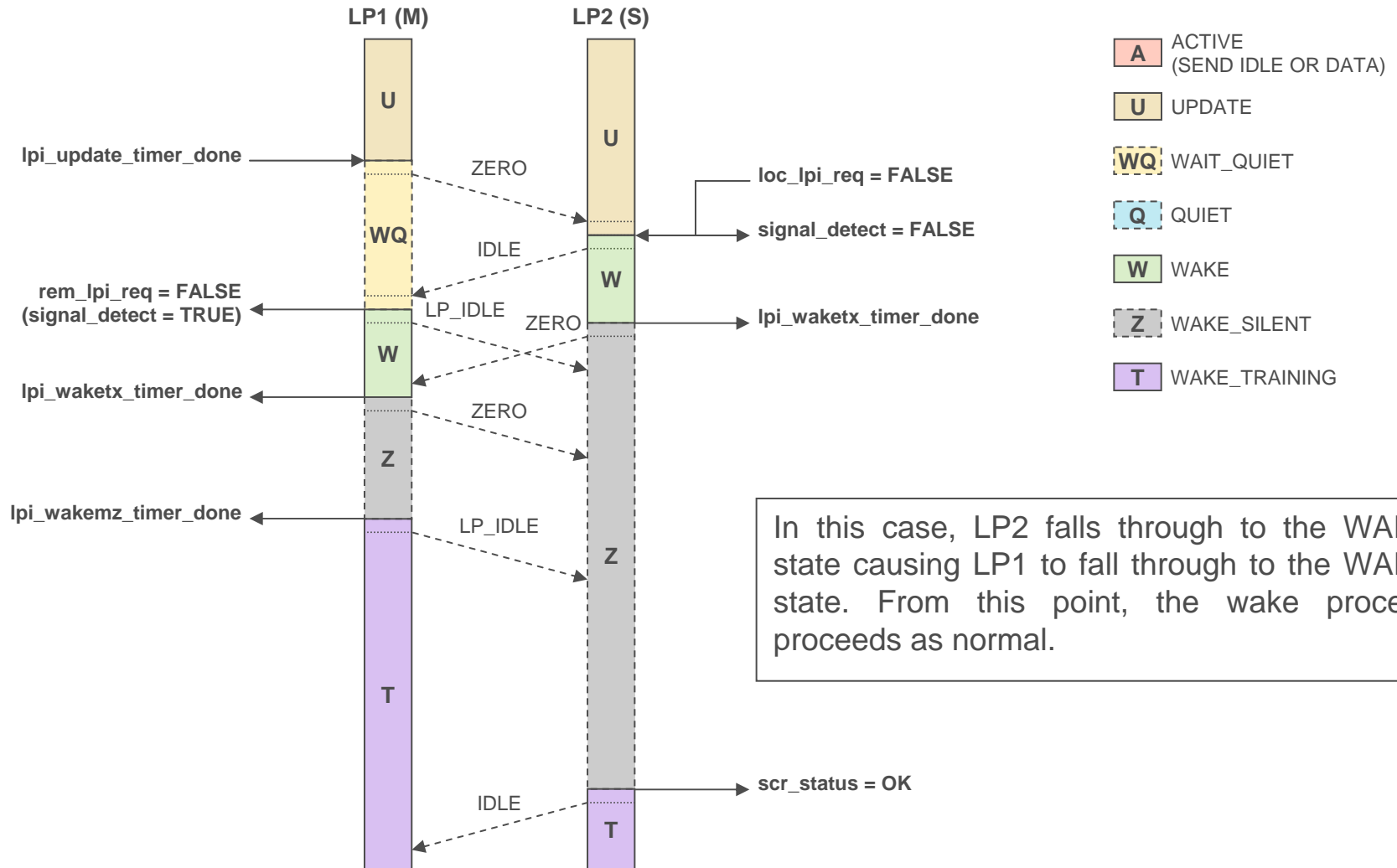
Duration: This timer shall have a period between 4.5 μ s and 5.0 μ s.

chou_01_0908.pdf: Case 1



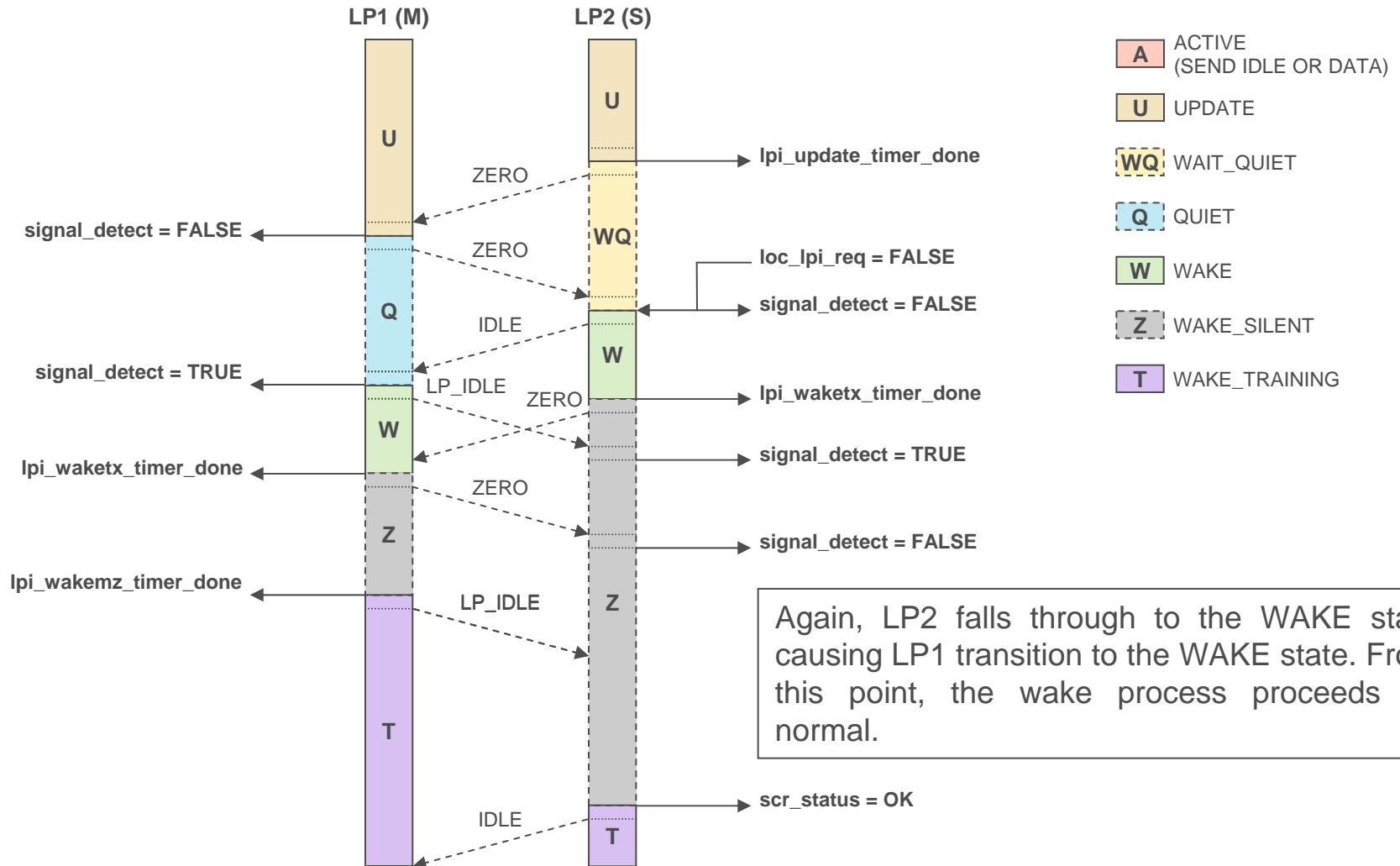
Since the state diagram transitions are not gated by any clock, LP2 “falls through” to the WAKE state. This diagram assumes that LP2 scr_status is OK throughout.

chou_01_0908.pdf: Case 2



In this case, LP2 falls through to the WAKE state causing LP1 to fall through to the WAKE state. From this point, the wake process proceeds as normal.

chou_01_0908.pdf: Case 3



Again, LP2 falls through to the WAKE state causing LP1 transition to the WAKE state. From this point, the wake process proceeds as normal.



Questions?