

EEE Proposal for 1000BASE-T1

San Diego, CA

July 16, 2014

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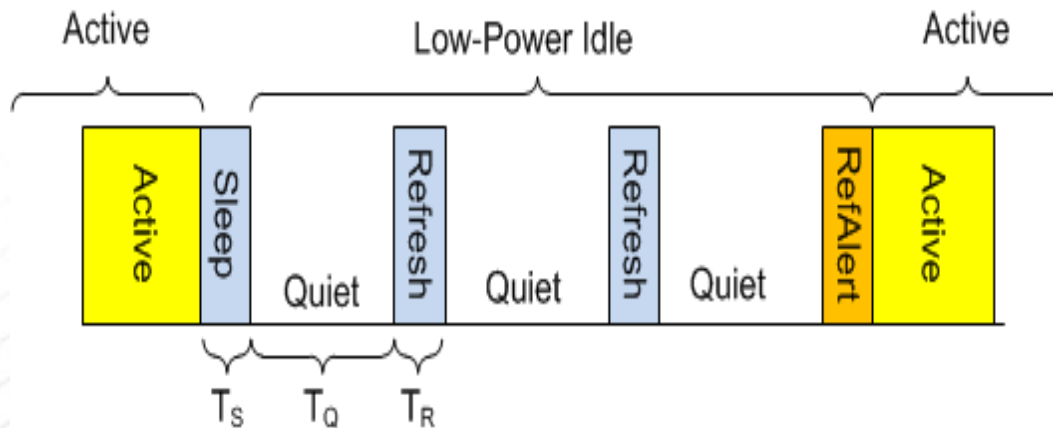
Overview

- **General 1000BASE-T1 EEE Format**
- **EEE Tradeoffs**
- **Use Similar 10G LPI Timing?**
- **Alert & Refresh**
- **LPI Exit – Case Analysis**
- **LPI Parameter Choices**
- **Conclusions**

General 1000BASE-T1 EEE Format

- **10G EEE provides a baseline**

- Use Refresh segments to allow adaptation while dissipating little power
- Leave LPI mode without incurring a large latency
- Allow asymmetrical LPI mode (1000BASE-T EEE did not)



- **1000BASE-T1 EEE differences with 10G EEE**

- One twisted pair
- Refresh can use the same modulation as Normal data – opportunity for simplification
- Reed Solomon frame is larger than 10G's LDPC frame

EEE Tradeoffs

- **Adaptation**

- Updates are decimated by RefreshLen / QRPeriod
- Loop BW decrease during LPI is roughly proportional to the decimation
- Sampling phase can drift during last Quiet before exiting LPI mode

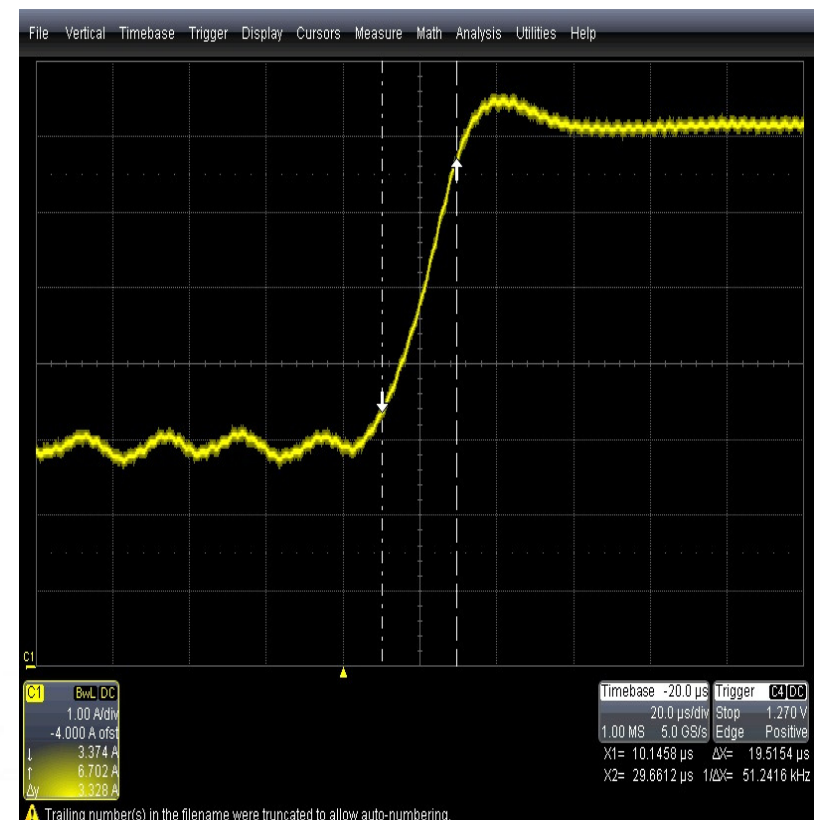
- **Better power savings => more latency**

- Analog circuits take time to obtain full capability when leaving a low power state
- Regulator circuits take time to settle LPI mode

- **1000BASE-T1 EEE vs 10G EEE**

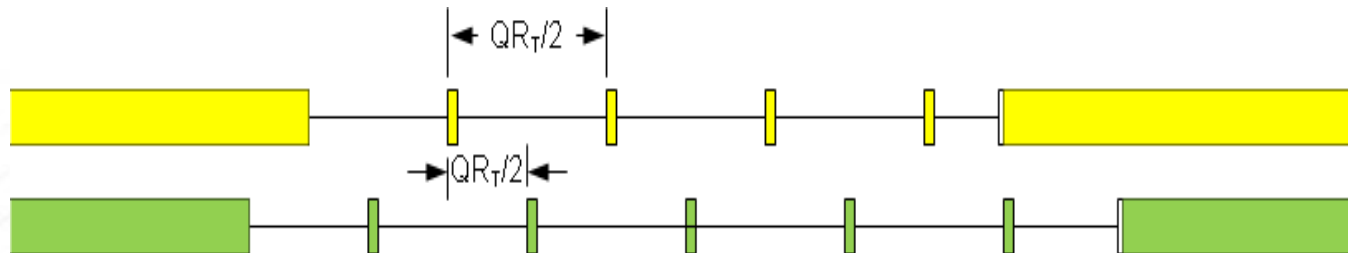
- Less current swing between power states
- PAM3 is less sensitive to phase offset compared to 10G's DSQ
- Only 1 twisted pair to deal with => less Refresh congestion
- ECC blocks are much bigger

Power supply current at LPI exit



Use similar 10G LPI timing?

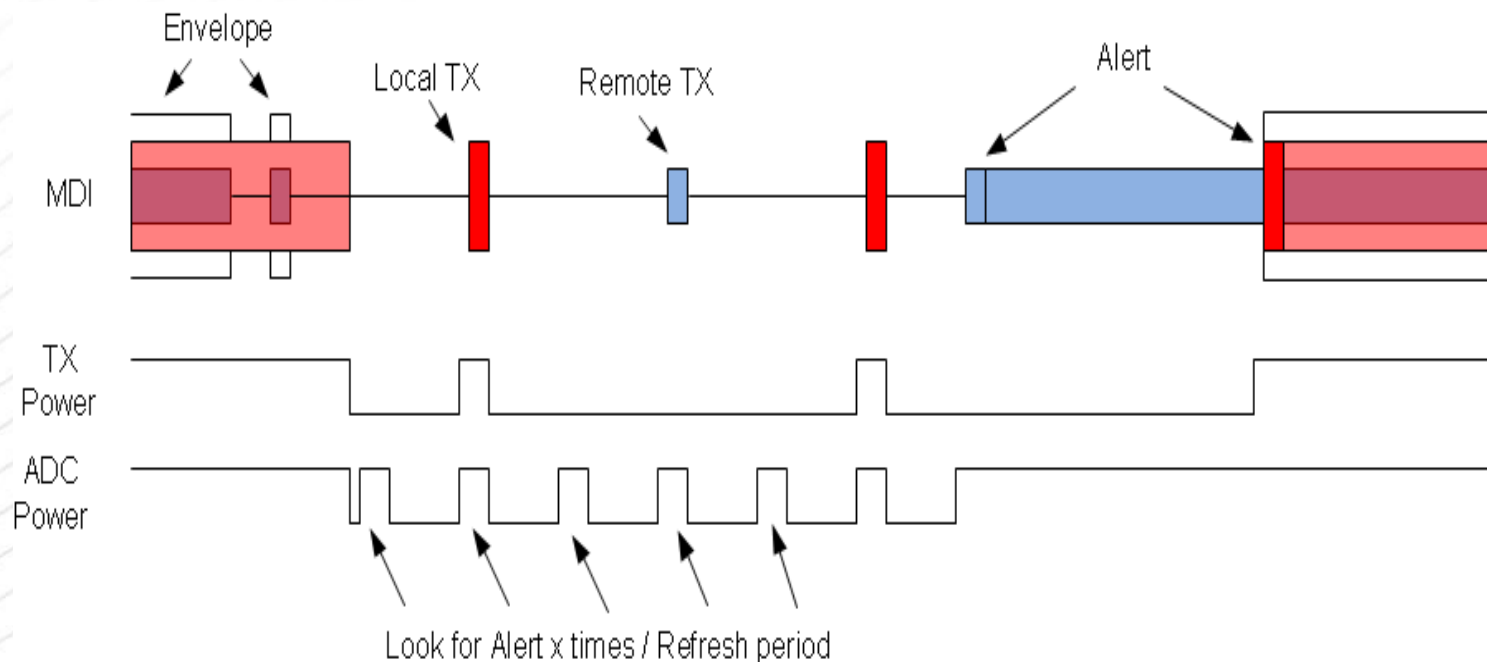
- **On a single twisted pair the Quiet/Refresh period is ~163us**
 - Adaptation decimation = $512/4 = 128 \Rightarrow$ LPI adaptation rate = Normal/128
 - 10G time between any TX or RX Refresh was ~20us
 - Now that time ($QR_T/2$) would be 80us. Should we reduce it to 20us for 1000BASE-T1 EEE?



- **If we reduce QR_T too much we lose the capability to put the RX AFE in a low power state**
 - See next page
- **Need to align Slave RX and TX Refreshes during Training akin to 10G LPI**

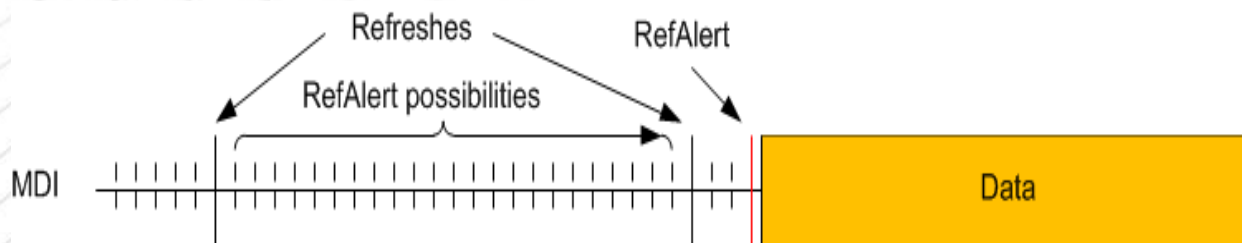
Alert

- **10G EEE Alert could start at any 0.32us interval => the Alert twisted pair channel must be powered on continually**
 - Following this blindly means the ADC cannot power down
- **Solution: allow the Alert to only appear at discrete times**
 - Now the ADC can be powered on at those times only to check for Alert
 - Need enough time between Alert possibilities to power down => long Quiet time



Embed Alert into Refresh

- **During LPI mode Refreshes consist of zeros scrambled and converted to PAM3 symbols**
- **To leave LPI mode transmit a Refresh with a scrambled pattern instead of zeros - RefAlert**



RefAlert composition

- **Length**

- Long enough to reliably detect the embedded Alert pattern
- Enough time after pattern detection to account for detection latency
- 3xPRS* of Alert + 2xPRS filled with scrambled zeros
- $\sim 0.7\mu\text{s} \leq \frac{1}{2}$ Refresh length



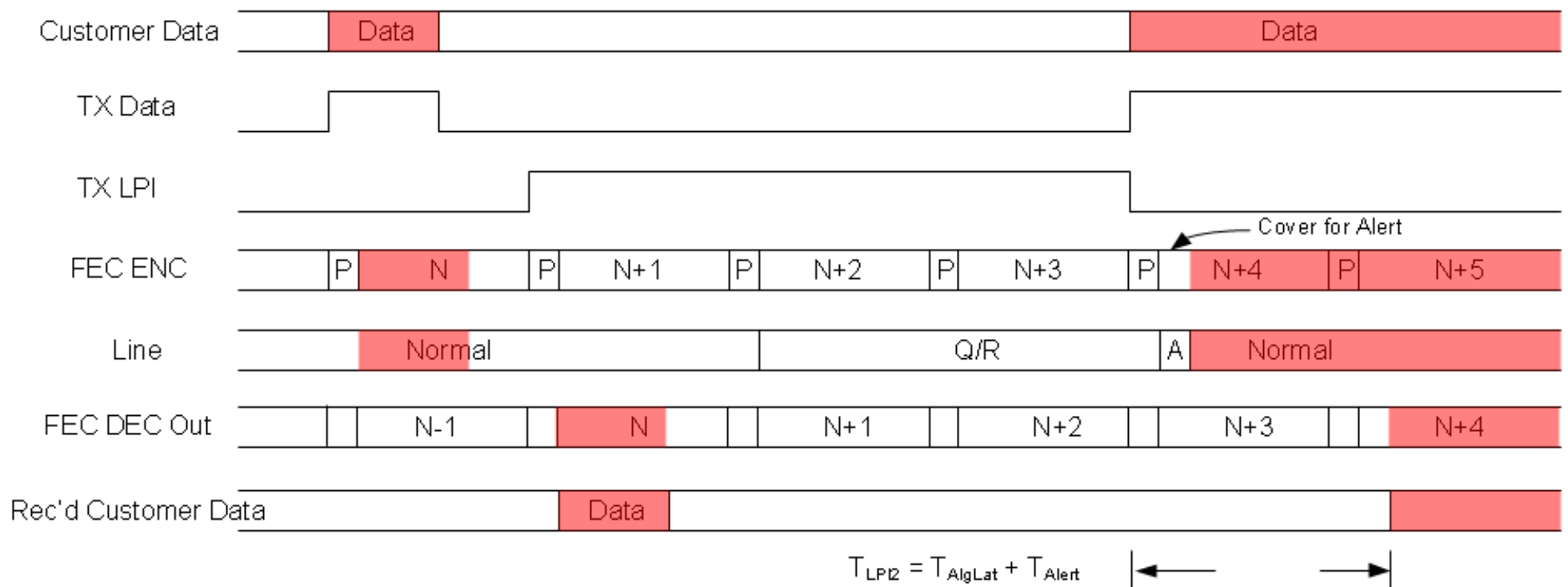
- **Benefits**

- Can be detected using normal data DSP => 10G Alert needs to be detected pre-DSP
- Don't have to deal with non-random echo => 10G is a fixed pattern
- Power on time for possible RefAlert = 1/3 Refresh length

Leaving LPI – Case 2 (Table 78-4)

- **Most likely**
- **Keep RS frame cadence constant**
 - Use partially filled RS frames

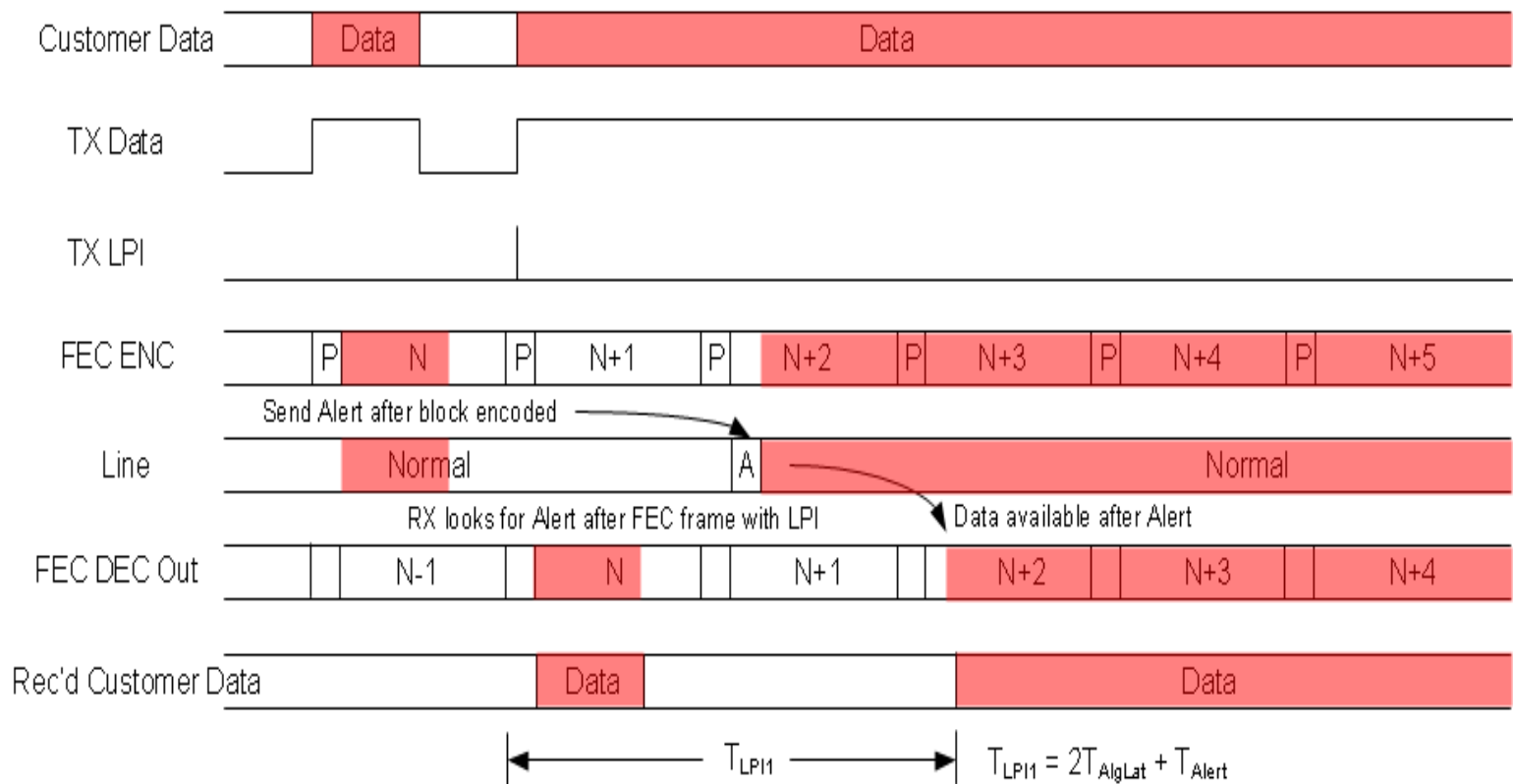
CASE 2: Send data while in LPI mode



Leaving LPI – Case 1

- **Send data immediately after signaling intention to enter LPI**
 - Worst latency
 - Well within 16.5us
- **Corner case**

CASE 1: Send data immediately after entering LPI mode



LPI parameters choices

- **1000BASE-T1 RS frames are much larger than 10G LDPC frames**
 - These are too large to use to place Refreshes
 - Use partial RS frames (proposed by William Lo)
 - Use Broadcom's 3B2T RS(450, 406) scheme

Parameter	10G EEE	1000BASE-T1 EEE	units
RS_T	0.32	3.6	us
PRS_T	N/A	144	ns
QR_T	163.84	108	us
$Refresh_T$	1.28	1.44	us
QR_{Ratio}	128	75	$Refresh_T/QR_T$
$Alert_T$	1.28	0.72	us
$AlertGranularity_T$	0.32	4.03	us

Conclusion

- **Propose we use 10G EEE type LPI**
- **Propose we embed Alert into Refresh**
- **Propose we keep the RS framing phase constant throughout the LPI process**
- **Need to determine parameters**
- **Need to specify LPI alignment during training**