## SEND\_S Signaling for 1000BASE-T1 Initial Synchronization

San Antonio, TX, USA November 4, 2014

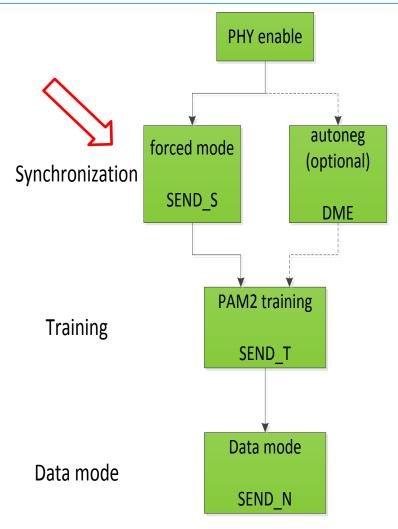
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## **Overall Startup Sequence**



TX Mode	Definition
SEND_Z	Send all zeros
DME	Differential Manchester encoding for autoneg
SEND_S	Send special periodic PAM2 sequences with good correlation properties
SEND_T	Send PAM2 training sequence
SEND_N	Send normal data

## Overview

- In July 14' plenary, a synchronization & start-up method was proposed (wang\_3bp\_01\_0714.pdf)
  - Detailed analysis was provided for a robust & fast handshake mechanism
  - Several corner cases were discussed
  - Essential timer values were defined (link\_fail\_inhibit\_timer & break\_link\_timer)

#### In this contribution,

- SEND\_S signaling is defined
- Master and Slave Synchronization State Machines are refined
- Simulation results are shown for various noise conditions
- A baseline proposal for the synchronization is now complete

## Highlights

- SEND\_S is based on wideband PAM-2 PN sequence
- The PN sequence should have a good autocorrelation characteristic
- Both Master and Slave will send its own 255 PN sequence (based on its 8<sup>th</sup> degree polynomial)
- Matched Filter-based correlator can be used for PN sequence detection of SEND\_S
- Simulations show that we can achieve very reliable detection of SEND\_S under the worst case NBI or burst noise conditions

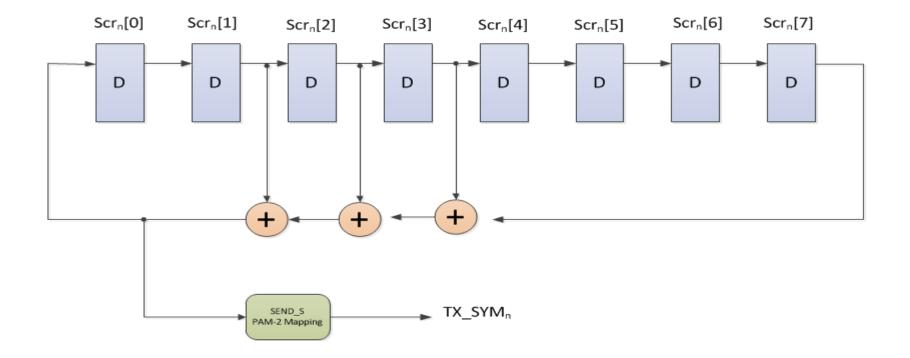
# SEND\_S Signaling

- Master and Slave polynomials for 255 PN sequence:
  - The scrambler generator polynomial for Master :  $g_M(x) = 1 + x^2 + x^3 + x^4 + x^8$
  - The scrambler generator polynomial for Slave :  $g_S(x) = 1 + x^4 + x^5 + x^6 + x^8$
  - The PN sequence has the period of 255 ( $2^8 1$ ).
- PAM2 Signaling
  - PAM-2 signal is based on the scrambler output  $Scr_n[0]$ :

Scr <sub>n</sub> [0]	TXSYM <sub>n</sub>
0	-1
1	+1

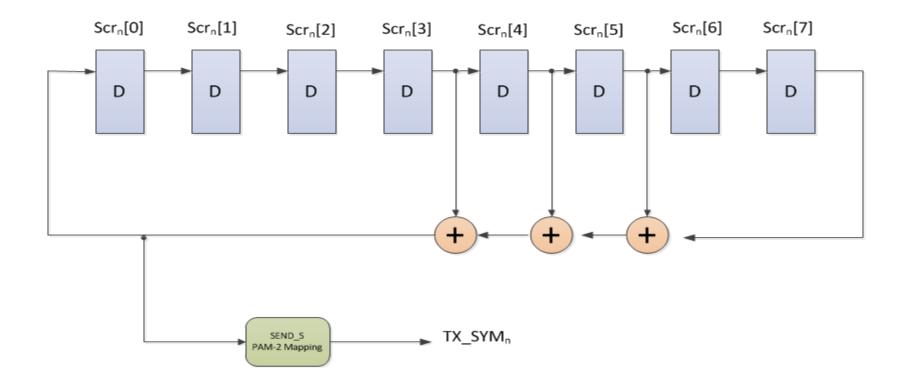
## Master SEND\_S Signaling



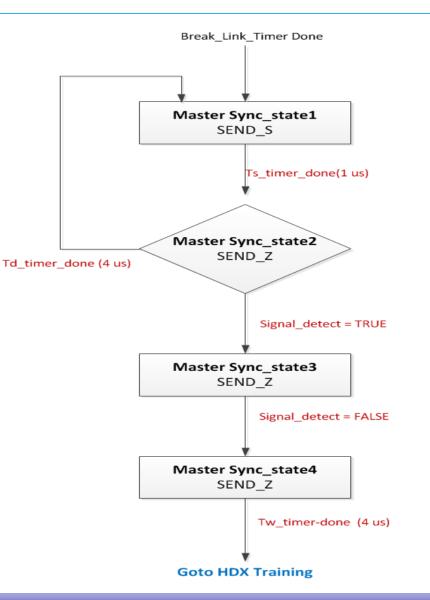


# Slave SEND\_S Signaling

Slave SEND\_S PN Sequence

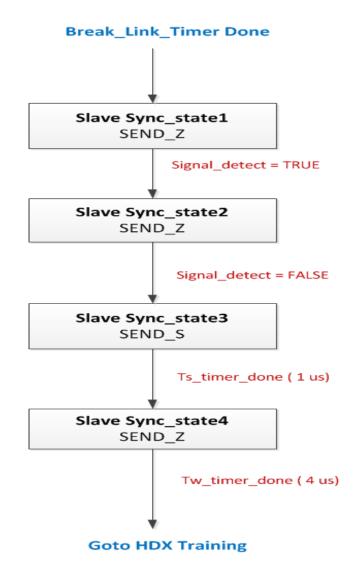


## Master SEND\_S State Machine



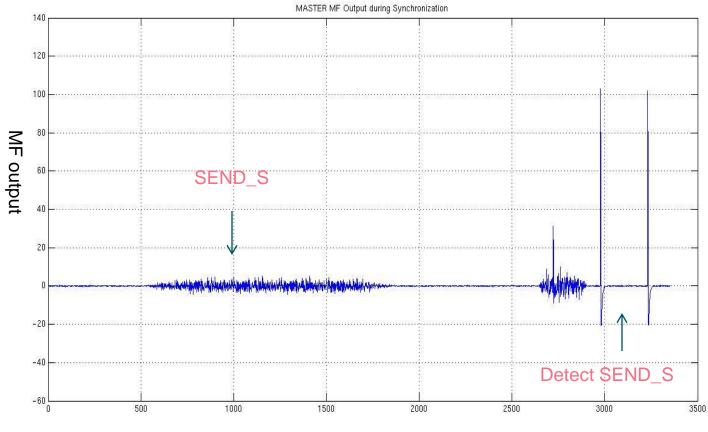
- Ts\_timer\_done is the duration for SEND\_S (send 4 frames to the slave)
- Td\_timer\_done is the maximum time Master will stay in Sync\_state2 to detect SEND\_S from Slave
- Tw\_timer\_done is the time that both Slave and Master will stay in its Sync\_state4 to wait 4 us

## Slave SEND\_S State Machine



## Master SEND\_S Detection

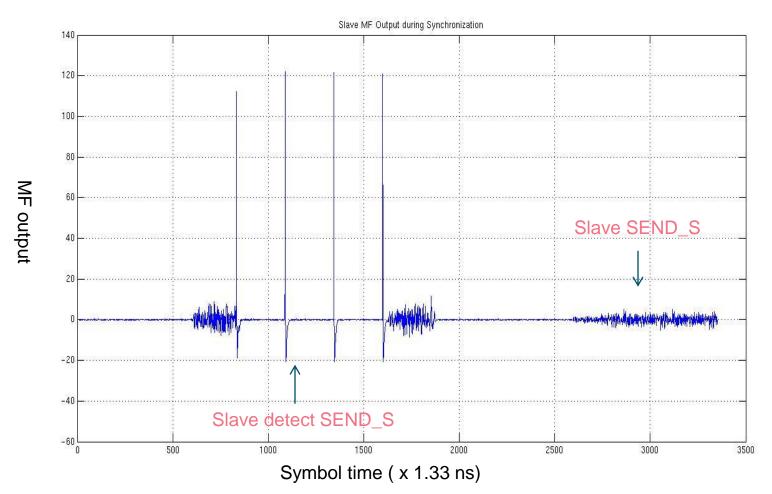
• Master MF output during synchronization (without noises):



Symbol time ( x 1.33 ns)

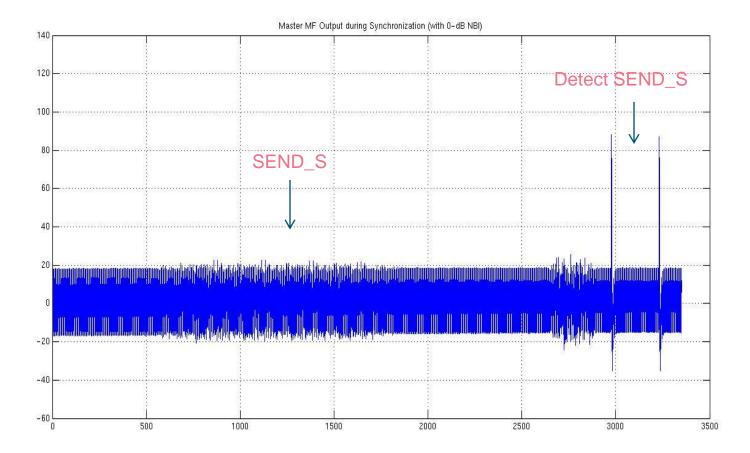
## Slave SEND\_S Detection

• Slave MF output during synchronization (without noises):



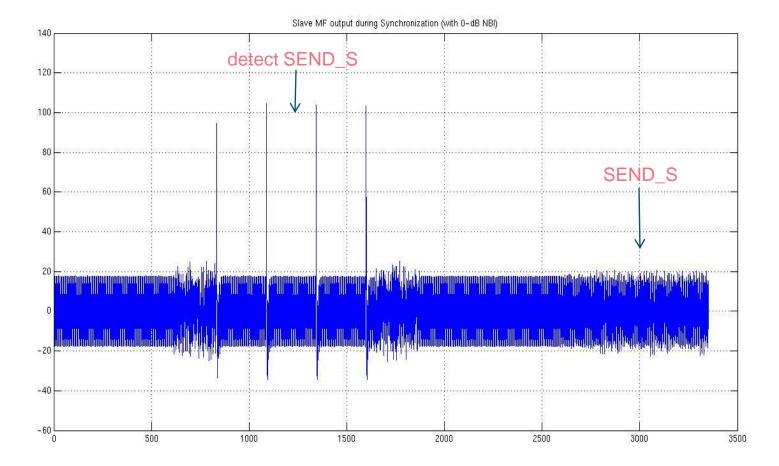
## **Master NBI Performance**

• Master MF output during synchronization (with 0 dB NBI ):



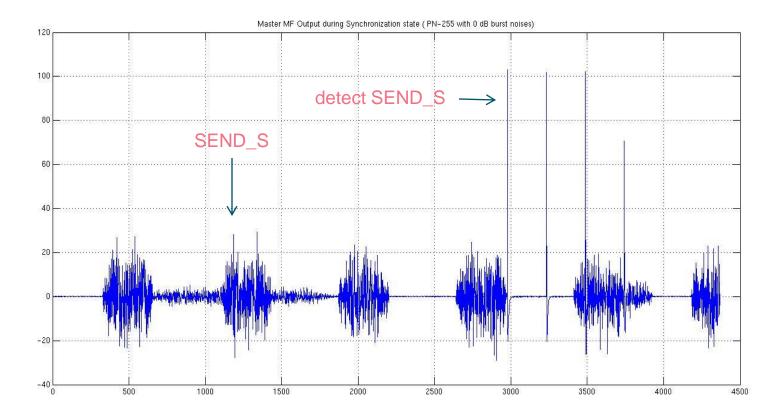
## **Slave NBI Performance**

• Slave MF output during synchronization (with 0 dB NBI ):



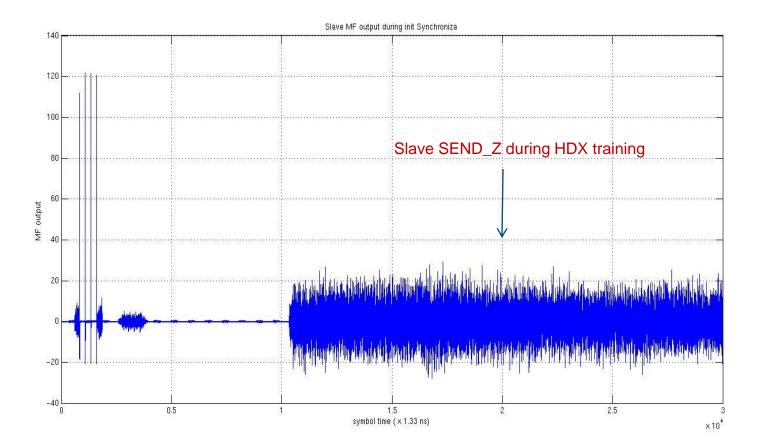
## Master Burst Noise Performance

• Master MF output during synchronization (with 0 dB Burst Noise ):



## Slave Burst Noise Performance

• Slave MF output during synchronization and coming into HDX training:



## Conclusions

When AN is bypassed, a synchronization method is needed between Master and Slave in order to support both *link\_fail\_inhibit\_timer* and *maxwait\_timer* 

- Previously, a fast and robust synchronization method is proposed based on signal detection
- PHY Control state diagrams are proposed to support the new synchronization method and the link timers

In this presentation, SEND\_S signaling is defined in order to complete the baseline proposal