

Consideration for CRU BW and Jitter Tolerance

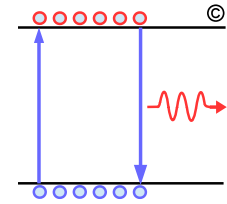
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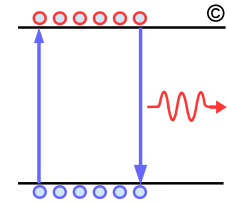
July 2015

Overview



- ❑ Consideration for CRU and CDR BW
- ❑ Background on jitter transfer and tolerance
- ❑ Review of several IEEE standard jitter filter and tolerance
- ❑ Fundamental issue the disconnect between transmitter and receivers
- ❑ Host receiver must operate with cascaded jitter
- ❑ Slides 4, 5, 6, and 9 are form Ghiasi – Le Cheminant addressing the same issue
 - http://www.ieee802.org/3/bm/public/mar14/ghiasi_01_0314_optx.pdf

Consideration for CRU and CDR BW



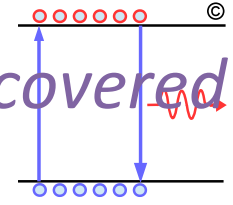
❑ Consideration for the golden PLL CRU BW

- Oscillator phase noise
 - With most oscillator have flat phase noise > 1 MHz no benefit
- Crosstalk
 - High frequency effects \gg CRU BW
- VCO phase noise
 - No benefit when CRU BW > 4 MHz

❑ Consideration for CDR BW

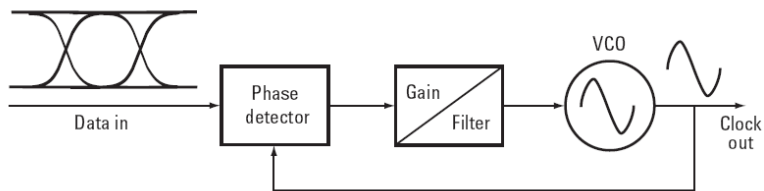
- Pattern dependent effect
 - Does not apply to 64B/66B/scrambled data with spectrum in the ~ 100 KHz
- Power
 - Higher loop BW results in higher CDR power
- DSP receiver
 - Timing recovery introduces latency making it challenging to meet traditional $F_{\text{baud}}/2578$ CDR loop BW
- Backward compatibility
 - Does an HOM port only operate at single speed with another HOM port or the port need to interoperate at lower bit rate with CAUI-4, CR4, SFI, etc?
 - An implementation requiring backward compatibility through a common data path would need 10 MHz CDR BW.

PLL concepts: PLL jitter transfer indicates how *recovered clock* (jitter out) tracks the data (jitter in)

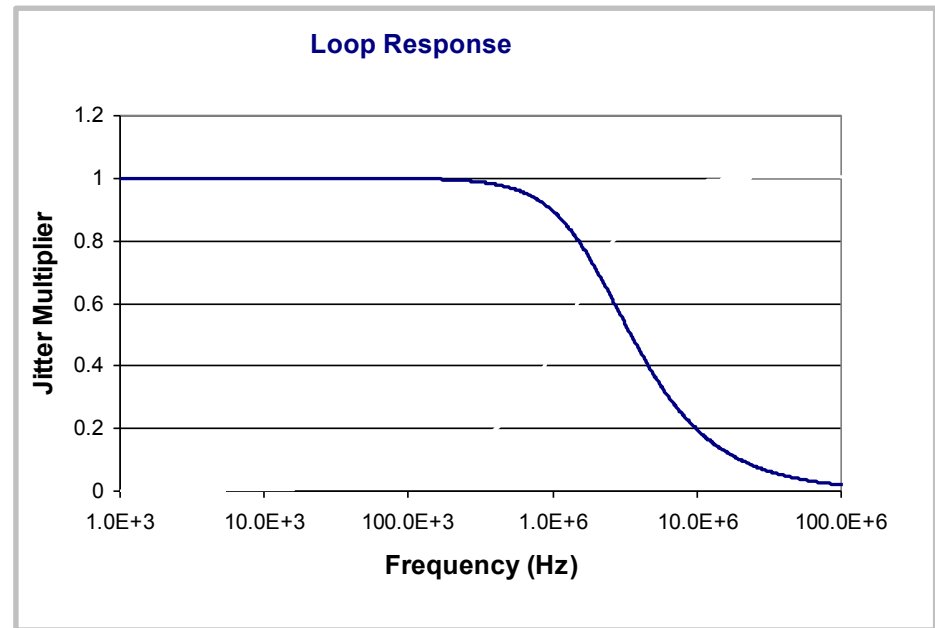


- The response of the PLL is generally a low-pass function, sometimes referred to as the jitter transfer response or JTF

$$\text{Closed loop gain} = \frac{\phi_{out}}{\phi_{in}} = \frac{A(s)}{1 + A(s)} = G(s) = |G(s)|e^{j\phi(s)}$$

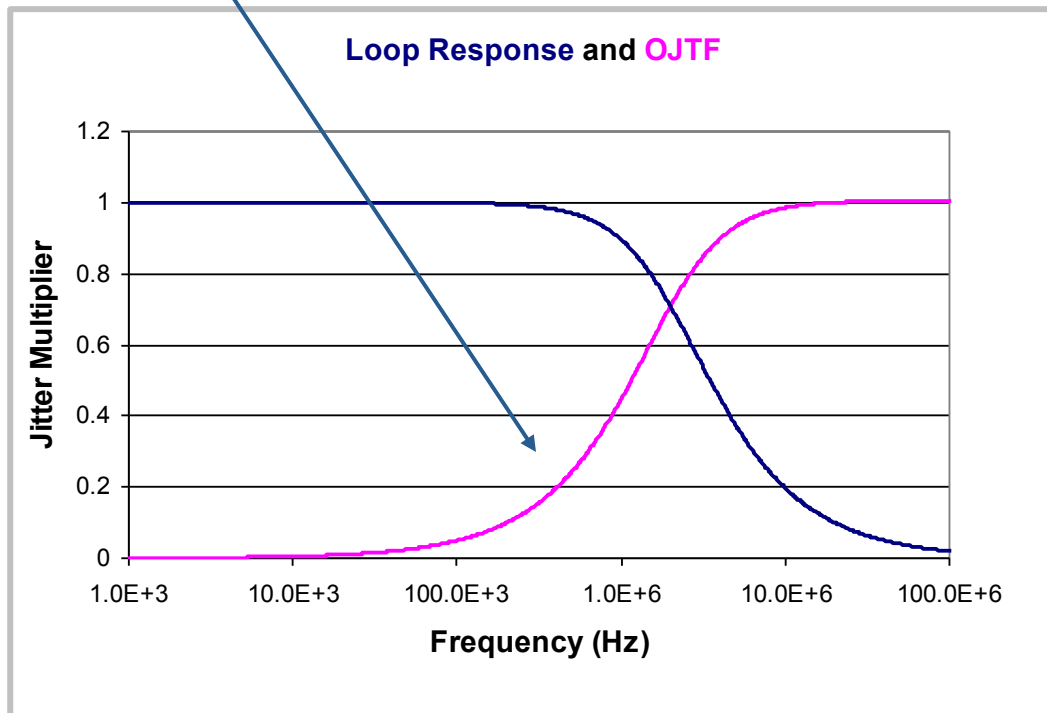


Low frequency jitter is transferred to the clock, high frequency jitter is not



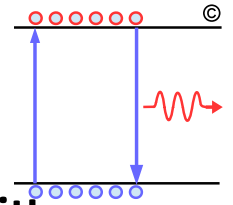
The observed jitter transfer function (OJTF, the jitter that is observed by a receiver, or on the instrument clocked/triggered by the recovered clock)

$$\text{OJTF} = 1 - G(s) = 1 - |G(s)|e^{j\phi(s)}$$

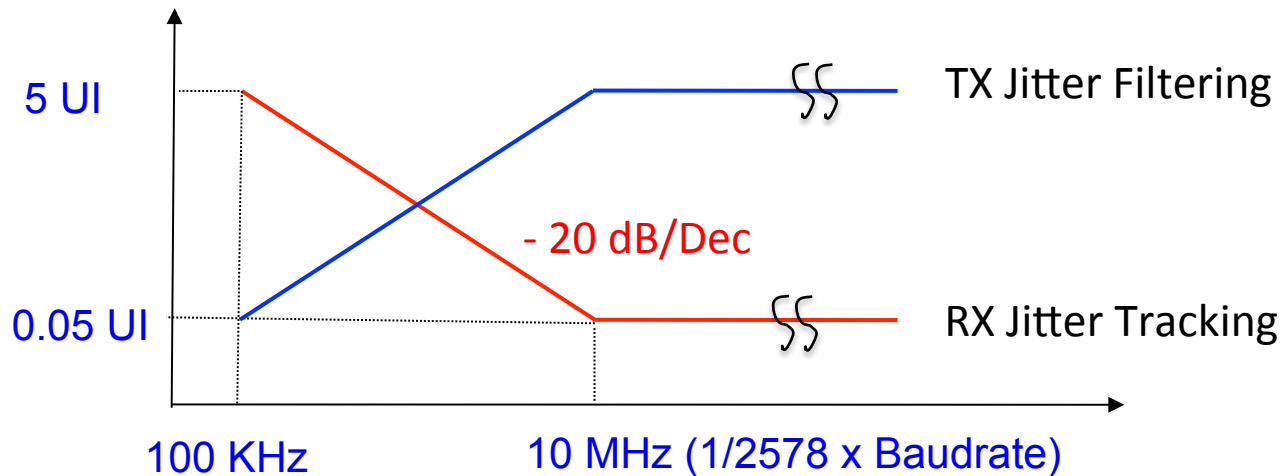


- The observed jitter is a complement to the PLL jitter transfer response
- OJTF=1-JTF (Phase matters!)
- As the jitter on the recovered clock trigger rolls off, common mode effect is reduced
- As jitter frequency gets large, eventually there is no jitter on the recovered clock and all the higher frequency jitter on the data stream is observed

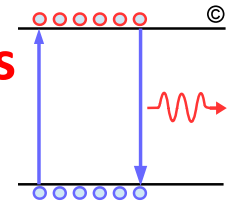
Comprehensive Jitter Methodology



- A comprehensive methodology to test transmitters and receivers for jitter was developed during 1 GFC standardization in the FC-MJS project and has become the basis for data communications system specification
- This methodology was based on systems using low cost oscillators and a reduction in power supply filtering to enable low-cost high-volume applications
 - Transmitter test assumes low frequency jitter should be tracked by a receiver, thus transmitter specs are relaxed by observing the transmitter using a reference PLL with OJTF defined as a high pass single pole filter with -20 dB/dec rolloff and -3dB corner frequency at 1/1667 Baudrate (changed to 1/2578*baudrate since 10 GbE)
 - Receiver test should complement transmitter test by verifying low frequency jitter is tolerated, example shown below is for a CRU/CDR response per CL 88.

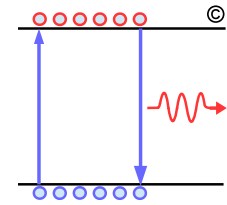


TX Jitter Filter and RX Jitter Tolerance for Several IEEE Standards



- ❑ **CL 52, 86A (40G-SR4, 100G-SR4), 83A/B (XLAUI, CAUI-10)**
 - Transmitter output measured with 4 MHz CRU (high pass jitter filter) Fbaud/2578
 - Receiver is tested with worst case stress + TX credited low frequency SJ
- ❑ **CL 68 (LRM), CL 72 (10G-KR), CL 85 (40G-CR4/100G-CR10)**
 - Transmitter output measured with 4 MHz CRU (high pass jitter filter) Fbaud/2578
 - CL 68 only tested unstress at two points (75 KHz, 5 UI) and (375 KHz, 1 UI)
 - CL 72 interference test require testing receiver with 0.115 UI at Fbaud/250
 - CL 85 interference test require testing receiver with 0.115 UI at frequency > 15 MHz
- ❑ **CL 88 (100G-LR4), CL 95 (100G-SR4), CL83D/E (CAUI-4)**
 - Transmitter output measured with 10 MHz CRU (high pass jitter filter) Fbaud/2578
 - Receiver is tested with worst case stress + TX credited low frequency SJ
- ❑ **CL 92 (100G-CR4), CL 93 (100G-KR4)**
 - Transmitter output measured with 10 MHz CRU (high pass jitter filter) Fbaud/2578
 - CL 92 interference test require testing receiver with 0.115 UI at frequency > 100 MHz and unstress SJ testing at (190 KHz, 5 UI) and (940 KHz, 1 UI)
 - CL 93 tested with 35 dB ISI channel at (190 KHz, 5 UI) and (940 KHz, 1 UI)
- ❑ **CL 94 (100G-KP4)**
 - Transmitter output measured with a CRU having 20 dB/dec low frequency response, 1.6 MHz BW, and 3 dB peaking at 6 MHz, response has peaking to accommodate 2nd order loops and potential peaking as result of DSP timing recovery latency
 - Receiver is tested unstress with following SJ components (16 KHz, 5 UI) and (160 KHz, 0.5 UI), jitter tolerance actually does not reflect the intention of 2nd order CRU
- ❑ **10G-LRM and 100G-KP4 testing receivers unstress does not guarantee interoperability**
 - 10G-KR and 40G-CR4/100G-CR10 interference tolerance does have an SJ component but does not test against potential SJ allowed by the transmitter.

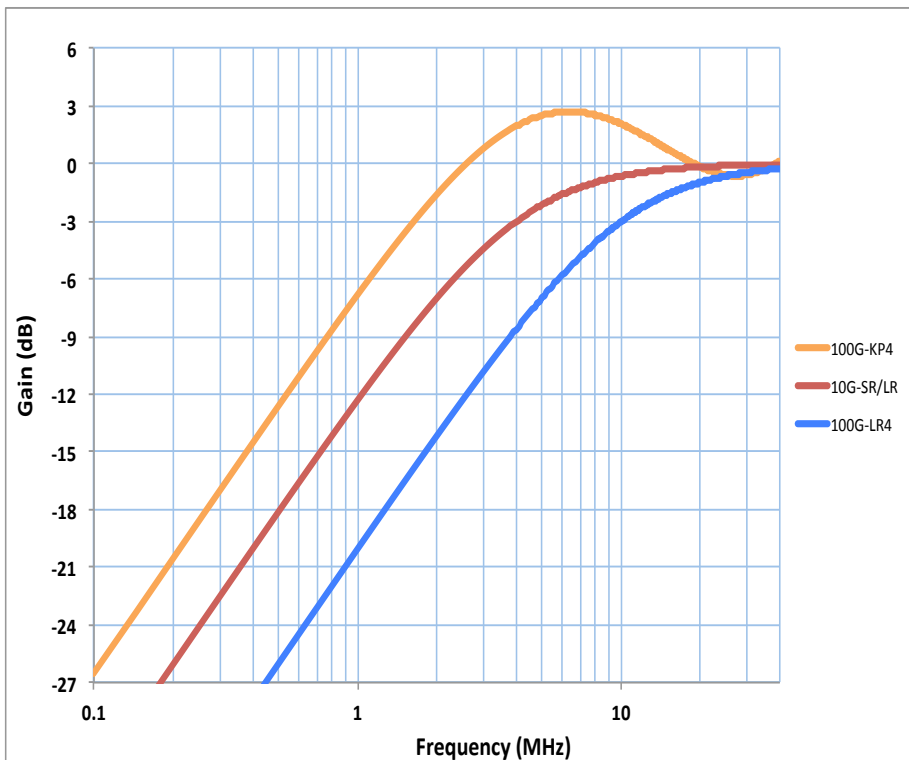
Transmitter Jitter Filter vs Receiver Jitter Tracking for Several IEEE Standards



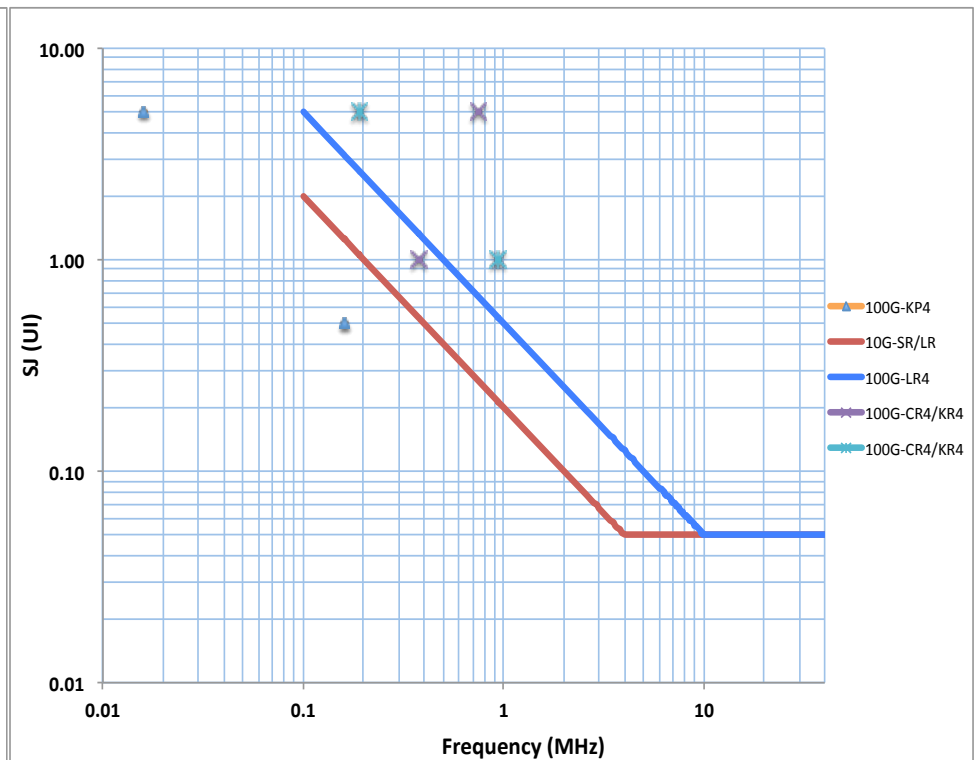
- The receiver must track the low frequency jitter golden PLL filters for observation on the scope, only 100G-KP4 defines 2nd order response as defined by:

$$G(f) = \frac{f}{f - j \times f_n e^{(j2\pi fT)}} , \text{ where } f_n = 2.12 \text{ MHz and } T = 0.0286 \mu\text{s}$$

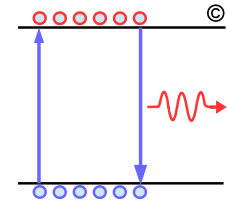
Golden PLL “TX Jitter Filter” Response



Stress Sensitivity

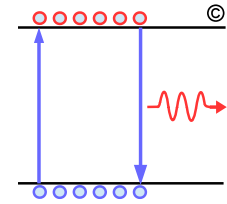


Fundamental Issue

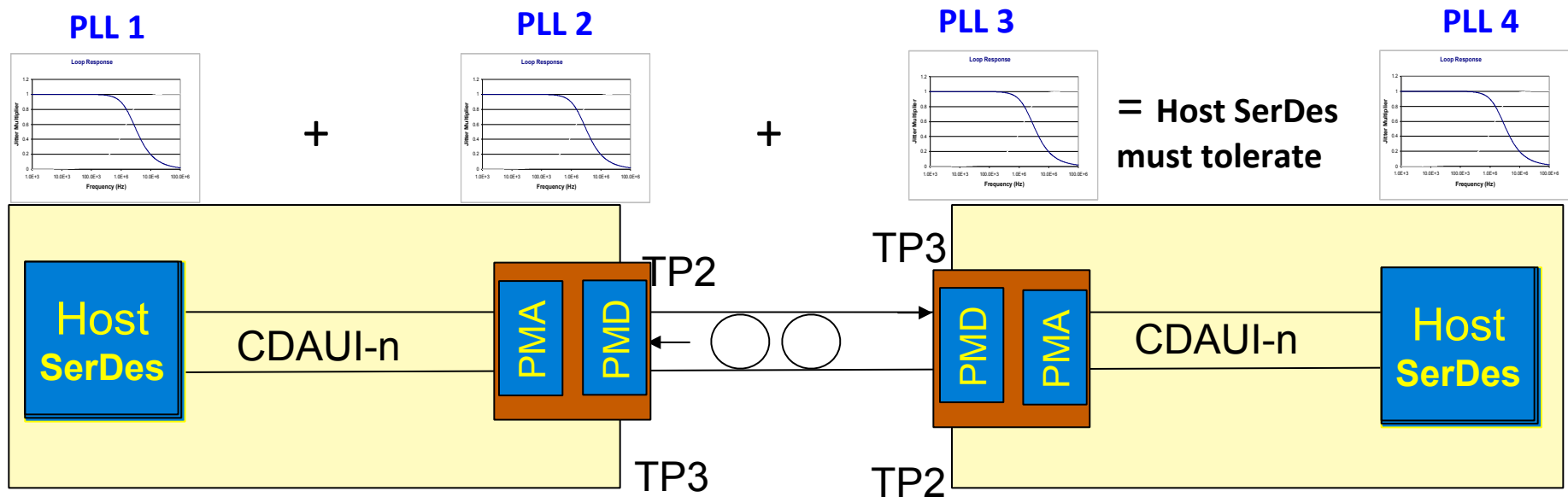


- **802.3aq (LRM) and 100G-KP4 receiver jitter tolerance introduced an inconsistent set of specifications by separating stress receiver testing and transmitter jitter tracking**
 - Transmitter jitter relief through MJS Golden PLL was maintained
 - Compliant transmitters may have low frequency jitter present, but not observed due to by the Golden PLL tracking effect
 - In IEEE the more complex receiver such as LRM and 100G-KP4 are only tested unstress at two spot frequencies as illustrated in previous slide
 - Full stress with the addition of SJ can result in broken links that is not observed with stress and SJ imposed in independent tests
 - Testing the receiver at only two discrete frequencies may not guarantee the receiver can actually tolerate transmitters with jitter tracked “masked” out by the Golden PLL
 - Transmitter tracked “masked” jitter actually propagates through the link and could break CDAUI-8 or CDAUI-16 host receiver!

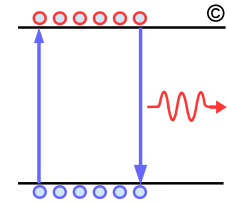
Receiver Must Tolerate all Jitter Components Propagating Down the Link



- Unless the PMA in the module has E-FIFO the host SerDes receiver PLL 4 must tolerate low frequency jitter propagated and shaped by the PLL 1, PLL 2, and PLL 3
 - The PMA in optical module may have a PLL BW < $F_{\text{baud}}/2578$ if the host PLL 1 has the same BW assuming the HOM module do not interoperate with other PMDs
 - However host SerDes PLL may need to have a BW of $F_{\text{baud}}/2578$ as the host receiver typically must support legacy PMDs.



Summary



- ❑ **Reliable link operation requires that the receiver test complements transmitter test.**
 - Any time a transmitter tested with Golden PLL which filters low frequencies jitter component that the receiver may not tolerate may result in sporadic link failures
 - Alternatively, the transmitter test could be more stringent
 - Regardless of the complexity of the receiver or the order of modulation the receiver must operate with any compliant transmitter
- ❑ **HOM receivers are more complex and their timing recovery may have higher latency which may be very difficult to support $F_{\text{baud}}/2578$ so what are the options:**
 - Ignore the legacy support in IEEE let the market sort it but at least define set of consistent transmitter and receiver test with $\text{PLL BW} \ll F_{\text{baud}}/2578$
 - Defining a $\text{PLL BW} \ll F_{\text{baud}}/2578$ will increase phase noise impacting HOM receivers
 - Define a PLL BW of 4 MHz compatible with 10G PMDs, optionally host may have a PLL BW of 10 MHz to support 100G-LR4 like PMDs
 - Define a PLL BW of 10 MHz to be fully backward compatible with existing PMDs
- ❑ **A DSP receiver with 4 or 10 MHz loop BW may have significant cost and power implication, but even worse would defining new set of standards not backward compatible or requiring PMA with E-FIFO!**