## TX LINEARITY MEASUREMENT PROPOSAL (IN SUPPORT OF COMMENT #118)



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- Overview of CDAUI-8 c2c TX linearity Specifications in Draft 1.1
- Proposal to change usage of R<sub>LM</sub> & SNDR
- Proposal to change method to measure PAM4 TX levels

## **CDAUI-8 C2C CURRENT METHOD**

- Inherited from Clause 94 (100GBase-KP4) and referenced by TX SNDR & R<sub>LM</sub>
  - 94.3.12.5.1 Transmitter linearity
    - Measure TX Linearity Test Pattern to obtain V<sub>A</sub>, V<sub>B</sub>, V<sub>C</sub>, V<sub>D</sub>
    - Calculate ES<sub>1</sub> & ES<sub>2</sub> (to allow for asymmetric inner PAM4 data levels) and R<sub>LM</sub>



- 94.3.12.5.2 Linear fit to the measured waveform
  - Measure PRBS13Q
  - Calculate SNDR, p(k) using an assumption that data levels are (-1,-ES<sub>1</sub>,ES<sub>2</sub>,1)



- R<sub>LM</sub> constraint on the TX should provide reasonable implementation margin for TX while limiting impact on the RX complexity and link budget
- Current R<sub>LM</sub> specification is based on the minimum eye opening between the 4 PAM levels
- PAM4 levels are [-1,-ES1,+ES2,+1] with ES1=ES2=1/3 in the normal case
  - Current R<sub>LM</sub> spec allows these TX cases with no downside or penalties

% error on ES1 & ES2	Notes
-5%, -5%	Symmetric case with 5% smaller middle eye
+10%,+10%	Symmetric case with 5% smaller outer eyes (compressed outer levels)
-20%,+10%	Asymmetric case with 10% larger lower eye and 5% smaller upper eye
+10%,-20%	Asymmetric case with 5% smaller lower eye and 10% larger upper eye

- For a 1Vpp example, the asymmetric cases have voltage levels of [-500, -133,+183,+500] mV
- The difference between the +1/3 and -1/3 levels is 50mV

## **MOTIVATION TO CHANGE RLM & SNDR DEFINITION**



- Transmitters designed for electrical links have good vertical symmetry (ES1 ~= ES2)
  - CAUI4, 100G-CR4 & 100G-KR4 constrain vertical asymmetry by SNDR. We can do the same here.
- Current spec allows large deviations from ideal levels (up to 20% in asymmetric case)
  - COM models the reduction in ideal eye opening implied by R<sub>LM</sub>, but assumes perfect ISI cancellation by DFE
  - It is not practical for a DFE to achieve this when TX levels are distorted
  - Margin impact is proportional to the max. error on ES1 and ES2 and DFE tap weights
  - Need to constrain the maximum error on ES1 and ES2 to avoid the worst case effect
  - Assume that 5% errors in ES1 and ES2 can be absorbed by RX implementation budgets
- R<sub>LM</sub> spec allows larger deviation (+10%) on the positive side of ES1 and ES2
  - In addition to DFE's imperfect ISI cancellation, this case is further aggravated by RX circuit compression
  - Even with perfect linearity in the RX, PAM4 outer eyes are already more distorted.
- With the proposed best fit method to estimate ES1 & ES2 accurately, there is less concern about measurement errors



- Estimate ES1 & ES2 using best fit method
- R<sub>LM</sub> defined to capture maximum deviation from ideal
  - R<sub>LM</sub> = Min(3\*ES1, 3\*ES2, 2-3\*ES1, 2-3\*ES2) with limit of 0.95
  - This will allow ES1 and ES2 to assume values of +/- 5% around ideal value of 1/3
- Define ES = (ES1 + ES2)/2
- Change SNDR to use the source TX levels as [-1, -ES,+ES,+1]
- +/-5 % error in TX levels should be absorbed by RX implementation, but recommend 3dB COM margin
- Advantages
  - No impact to common TX cases with symmetric levels within +/-5% of ideal
  - SNDR now captures symmetry errors
    - Low levels of vertical asymmetry do not affect SNDR measurably
      - ES1,ES2 = (+2%,-2%) results in < 0.1dB SNDR penalty</p>