# Alignment of Tx jitter specifications, COM, and Rx interference/jitter tolerance tests

Adee Ran

December 2016

## Baseline

- In clauses/annexes that use COM for channel specifications, there are 3 coupled elements:
  - Transmitter specification
  - Receiver tolerance tests
  - COM parameters
- If these elements match, then a combination of Tx+channel+Rx (all compliant) should perform as expected
- Otherwise... there is either a hole in the budget or margin left on the table
  - E.g. compliant Tx, COM parameters match, but understressed Rx tolerance test: system performance not guaranteed
  - E.g. compliant Tx, compliant Rx, but COM overestimates jitter effect: channels that fail COM would still work

# Comment #15

- There seems to be a mismatch SJ in the jitter tolerance test and the A\_DD parameter.
- Looking at the precedence in 83D:
  - The channel is specified with COM parameter A\_DD=0.05 (Table 83D–6), corresponding to 0.1 UI PtP. The transmitter specification has the same value allowed for effective DJ.
  - The SJ stress at high frequencies is 0.05 UI PtP (from Table 88–13).
  - This means the SJ stress is 50% lower than the maximum allowed for the transmitter; the test in 83D is understressed (unless the transmitter has intrinsic DJ of 0.05 UI PtP).
- In the current annex
  - The channel is specified with COM paremeter A\_DD=0.02 corresponding to 0.04 UI PtP (the transmitter specification may not match this value; as noted in another comment)
  - The SJ stress at high frequencies is 0.05 UI PtP (Table 120D-7)
  - This means the SJ stress is 25% higher than the maximum allowed for the transmitter; the test is overtstressed (even if the transmitter has no intrinsic DJ).
- The SJ stress is supposedly based on the CRU bandwidth so all frequencies should be scaled similarly."

From Table 120D-7

Table 120D–7—200GAUI-4 and 400GAUI-8 receiver jitter tolerance parameters

Parameter	Case A	Case B	Case C	Case D	Case E	Units
PCS FEC Symbol error ratio	10 <sup>-4</sup>	10-4	10-4	10-4	10-4	_
Jitter frequency	0.04	1.333	4	12	40	MHz
Jitter amplitude (pk-pk)	5	0.15	0.05	0.05	0.05	UI

#### • From Table 120D-8

Random jitter, RMS	$\sigma_{RJ}$	0.01	UI
Dual-Dirac jitter, peak	A <sub>DD</sub>	0.02	UI

#### Comment #15 = cont.

- Suggested remedy:
  - Change table 120D-7 so that the SJ is 0.04 UI PtP at high frequencies (cases C, D and E), 0.12 UI for case B, and 4 UI for case A.
- Suggested Table 120D-7 change

Parameter	Case A	Case B	Case C	Case D	Case E	Units
PCS FEC Symbol error ratio	10-4	10-4	10-4	10-4	10-4	_
Jitter frequency	0.04	1.333	4	12	40	MHz
Jitter amplitude (pk-pk)	5	0.15	0.05	0.05	0.05	UI

Table 120D-7-200GAUI-4 and 400GAUI-8 receiver jitter tolerance parameters

Table 120D–7—200GAUI-4 and 400GAUI-8 receiver jitter tolerance parameters

Parameter	Case A	Case B	Case C	Case D	Case E	Units
PCS FEC Symbol error ratio	10-4	10-4	10-4	10-4	10-4	_
Jitter frequency	0.04	1.333	4	12	40	MHz
Jitter amplitude (pk-pk)	4	0.12	0.04	0.04	0.04	UI

### Comment #29

- There seems to be a mismatch between the transmitter jitter specifications and the A\_DD parameter.
- Looking at the precedence in 83D:
  - The maximum effective DJ allowance for the transmitter is 0.1 UI PtP (Table 83D–1)
  - The channel is specified with COM parameter A\_DD=0.05 (Table 83D–6), corresponding to 0.1 UI PtP.
- In the current annex:
  - Transmitter DJ is not specified directly, but using equations 120D-9 and 120D-10 with the maximum specified J4 (0.118 UI) and JRMS (0.019 UI) yields A\_DD=0.015 and sigma\_RJ=0.011
  - The channel is specified with COM paremeter A\_DD=0.02 and sigma\_RJ=0.01.
- If the equations are correct, this means the channel specification assumes a significantly worse transmitter than what is actually allowed, and the transmitter specification may be relaxed.

#### Comment #29 – cont.

- Assuming the channels are an (informal) objective, we should not change the COM parameters.
- Suggested remedy: change the Tx jitter specifications.
  - Find J4,  $J_{RMS}$  and equations that would yield the same  $A_{DD}$ ,  $\sigma_{RJ}$  used in COM
  - I am actively looking for such a combination...
- Can we assume that J4 and J<sub>RMS</sub> cannot be at the maximum together?
  - If so this should be stated
  - I still don't have an example of values that yield the target  $A_{DD}$ ,  $\sigma_{RJ}$

# Comment #30

- As a sanity check, I calculated what would happen with
  - A purely dual-dirac jitter (no RJ) causing the specified J4, and
  - A purely random jitter (no DD) causing the specified J<sub>RMS</sub> (0.023 UI).
- In the first case, J4=0.0118 and J<sub>RMS</sub> would be sqrt(0.0118)=0.109 (more than allowed...)
  - Plugging these values to equations 120D-9 and 120D-10 yields  $A_{DD}$ =0.1059 and  $\sigma_{RJ}$ =0.1917
  - Instead of the expected A\_{DD}=0.0059 (J4/2) and  $\sigma_{\rm RJ}=0$
- In the second case, JRMS is 0.023 and J4 would be 2\*0.023\*Q(1e-4/2)=0.18
  - plugging these values to equations 120D-9 and 120D-10 yields  $A_{DD}$ =0.0106 and  $\sigma_{RJ}$ =0.004; instead of the expected  $A_{DD}$ =0 and  $\sigma_{RJ}$ =0.023.

Q4	3.8906	
Input values		
J <sub>4</sub>	0.0118	
J <sub>RMS</sub>	0.109	
Calcualted values		
A <sub>DD</sub>	0.1059	120D–7
σ <sub>RJ</sub>	0.1917	120D–8

Q4	3.8906	
Input values		
J <sub>4</sub>	0.18	
J <sub>RMS</sub>	0.023	
Calcualted values		
A <sub>DD</sub>	0.0106	120D–7
σ <sub>RJ</sub>	0.004	120D–8

#### Comment #30 – cont.

- The equations originated from comment #25 against D2.0 which has very little explanation.
- I have not found any further analysis and suspect that the equations may be incorrect...
- Looking for alternative calculation