TDL #275 and #276 D2.1

Addressing comments: #108, #420, #421, #281

Make the following changes:

PSE-PD stability

33A.1 Recommended PSE design guidelines and test setup

1. Make the following changes:

In order to prevent potential oscillations between the PSE and PD, the sum of the PSE port output impedance (Zo_portZo_pse), the cable impedance (Zc), the PD input port circuitry impedance (Zpd_cirZcir_pd) and the PD EMI output filter impedance (Z_emi) should be lower than the PD power supply input impedance (Zin_ps_pd). All the above impedances are converted to the equivalent series impedance form as described by Figure 33A-1. This sub clause focuses on the PSE part.

<u>PSE PortPI</u> output impedance consists of two parts:

— PSE power supply output impedance (Zo_ps), which is a function of the load <u>at the PSE</u>
<u>PI(PPort)</u>, and
<u>the Seriesseries</u> elements (Z_ser) that connect the PSE power supply output to the <u>PSE PIport</u>.

Therefore, the total <u>PSE PI Port</u> output impedance during normal powering mode is $Zo_portZo_pse=Zo_ps+Z_ser$.

In order to maintain PSE-PD stability, the following guidelines apply:

--- Zo_ps max = 0.3 Ω_{τ} at frequencies up to 100 kHz at the highest <u>output power level Class-that</u> the PSE supports, as defined in Table 33–13. <u>At lower power levels than the highest output power level</u> PSE support, Zout_ps_max =0.3 Ω x PClass max / Pclass.

Zo_ps can be extracted from $\frac{\text{Zport}_{Zo} \text{ port}}{\text{port}_{2P} \text{ VPort}_{2P} \text{ VPort}_{2P} \text{ PSE-2P} / \text{ IPort}}$ (with an external power dynamic analyzer system) as a function of frequency and subtracting from $\frac{\text{Zport}}{\text{Zo}_{2P} \text{ port}}$ the value of $\frac{\text{Zo}_{2P} \text{ ser}}{\text{Zo}_{2P} \text{ ser}}$ (f = DC) which is limited by the value of $\frac{\text{Zser}_{2P} \text{ zo}_{2P} \text{ ser}}{\text{Zo}_{2P} \text{ ser}}$ at DC (low frequency).

The value of Zo_ps is not limited if the following conditions are met simultaneously:
a) If Zo_ps < Zo_ser

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b) <u>and Vpse VPort-2P</u> is kept to in the range of <u>VPort-2P</u> <u>VPort_PSE-2P</u> min and <u>VPort-2P</u> <u>VPort_PSE-2P</u> max as defined in Table 33–18 during dynamic load changes from 10 Hz to 100 kHz., then the value of Zo_ps is not limited.

Verification of these guidelines can be made by measuring the <u>PSE PI port</u>-output impedance from 10 Hz to 100 kHz with the maximum load per the PSEs assigned Class, as defined in Table 33–13 at short cable length, or by performing simulations.

See Figure 33A–1 for the PSE-PD system impedance allocation.

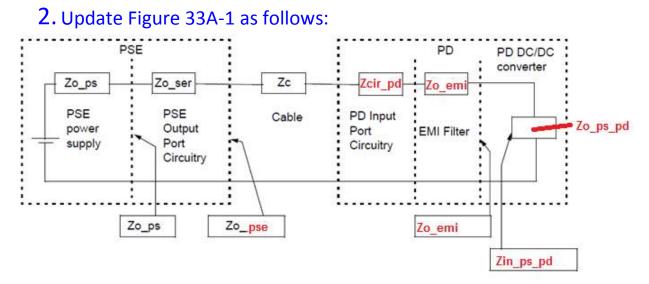


Figure 33A-1—PSE-PD system impedance allocation

See Figure 33A-2 for the test setup and Figure 33A-3 for the test requirements.

- 3. Delete Figure 33A-2 (no need to teach how to measure impedance of a port)
- 4. Delete Figure 33A-3 (the test requirements are in the text)
- 5. Make the following changes:

33A.2 Recommended PD design guidelines

PD port_PI_input impedance consists of the following two parts:

- PD PI port input circuits Zcir_pd and <u>including</u> the EMI filter (Zin_ser)Z_emi, and

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— PD power supply input impedance <u>(Zin_ps_pd)</u>Zin_ps_pd., which is fed by the output of the EMI filter (Zo_emi).

In order to maintain stability with the PSE, the PD power supply input impedance <u>Zin_ps_pd</u> (<u>Zin_ps_pd</u>) should be higher than the output impedance of the total network <u>that precedes it</u> (<u>Zo_emi+Zcir_pd+Zc+Zo_pse</u>).including the PD EMI output filter impedance fed by the channel output impedance, which is fed by the PSE port output impedance.

The worst-case scenario is when the channel length is zero (in terms of lower damping factor).

The a<u>A</u>ccess to the PD input power supply is not possible through the PD port for evaluating the various impedances <u>in the PD</u> and derivation of the above <u>individual impedances</u>. The following guidelines are recommended when measuring the PD input impedance:

— The PD power supply input impedance (Zin_ps_pd) at <u>Pclass_PD_maxmax_load of PPort_PD</u> = <u>PPort_PD max</u> as defined in Table 33–30 should be higher than 30 Ω at any frequency up to the PD power supply crossover <u>closed loop</u> frequency. If the PD power supply is consuming less than <u>its</u> <u>maximum power capability defined by PClass_PD_max</u>, <u>PPort_PD = PPort_PD max</u> as defined in Table 33–30, then Zin_ps_pd min = 30 x <u>PClass_PD max</u> <u>PPort_PD-max</u> / <u>PPort_PDPport_PD</u>.

— The PD power supply EMI filter output impedance should be Zo_emi = 2.7Ω max. If the PD power supply is consuming less than <u>PClass_PD_max_i.e. Pport_PD_PPort_PD = PPort_PD max</u>, then Zo_emi = $2.7 \times \frac{PClass_PD_PPort_PD max}{PD PPort_PD max}$.

See Figure 33A-1 for the PSE-PD system impedance allocation.

End of Baseline

The following is a clean version with out markups.

Replace 33A.1 and 33A.2 with the following:

PSE-PD stability

33A.1 Recommended PSE design guidelines and test setup

In order to prevent potential oscillations between the PSE and PD, the sum of the PSE port output impedance (Zo_pse), the cable impedance (Zc), the PD input port circuitry impedance (Zcir_pd) and the PD EMI output filter impedance (Z_emi) should be lower than the PD power supply input impedance (Zin_ps_pd). All the above impedances are converted to the equivalent series impedance form as described by Figure 33A-1.

PSE PI output impedance consists of two parts:

- PSE power supply output impedance (Zo_ps), which is a function of the load at the PSE PI, and
- the series elements (Z_ser) that connect the PSE power supply output to the PSE PI.

Therefore, the total PSE PI output impedance during normal powering mode is Zo_pse=Zo_ps+Z_ser.

In order to maintain PSE-PD stability, the following guidelines apply:

--- Zo_ps max = 0.3 Ω at frequencies up to 100 kHz at the highest output power level that the PSE supports, as defined in Table 33–13. At lower power levels than the highest output power level PSE support, Zout_ps_max =0.3 Ω x PClass max / Pclass.

Zo_ps can be extracted from Zo_port by measuring VPort_PSE-2P / IPort (with an external power dynamic analyzer system) as a function of frequency and subtracting from Zo_port the value of Zo_ser which is limited by the value of Zo_ser at DC (low frequency).

- The value of Zo_ps is not limited if the following conditions are met simultaneously:
 - a) Zo_ps < Zo_ser
 - b) Vpse is kept in the range of VPort_PSE-2P min and VPort_PSE-2P max as defined in Table 33–18 during dynamic load changes from 10 Hz to 100 kHz..

Verification of these guidelines can be made by measuring the PSE PI output impedance from 10 Hz to 100 kHz with the maximum load per the PSEs assigned Class, as defined in Table 33–13 at short cable length, or by performing simulations.

See Figure 33A–1 for the PSE-PD system impedance allocation.

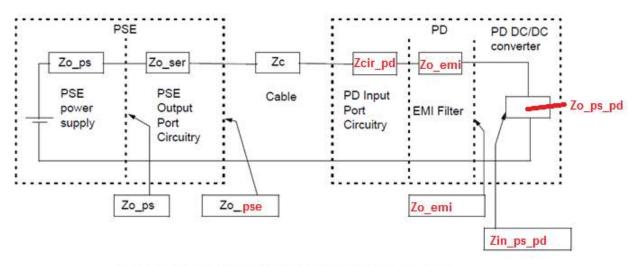


Figure 33A-1—PSE-PD system impedance allocation

33A.2 Recommended PD design guidelines

PD PI input impedance consists of the following two parts:

- PD PI input circuits Zcir_pd and the EMI filterZ_emi, and

- PD power supply input impedance_Zin_ps_pd.

In order to maintain stability with the PSE, the PD power supply input impedance Zin_ps_pd should be higher than the output impedance of the total network that precedes it (Zo_emi+Zcir_pd+Zc+Zo_pse).

The worst-case scenario is when the channel length is zero (in terms of lower damping factor).

Access to the PD input power supply is not possible through the PD port for evaluating the various impedances in the PD and derivation of the above individual impedances. The following guidelines are recommended when measuring the PD input impedance:

— The PD power supply input impedance (Zin_ps_pd) at Pclass_PD_maxas defined in Table 33–30 should be higher than 30 Ω at any frequency up to the PD power supply crossover closed loop frequency. If the PD power supply is consuming less than its maximum power capability defined by PClass_PD_max, as defined in Table 33–30, then Zin_ps_pd min = 30 x PClass_PD max max / Pport_PD.

— The PD power supply EMI filter output impedance should be Zo_emi = 2.7Ω max. If the PD power supply is consuming less than PClass_PD_max_i.e. Pport_PD, then Zo_emi = $2.7 \times PClass_PD / Pport_PD$.

See Figure 33A–1 for the PSE-PD system impedance allocation.

End of Baseline

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