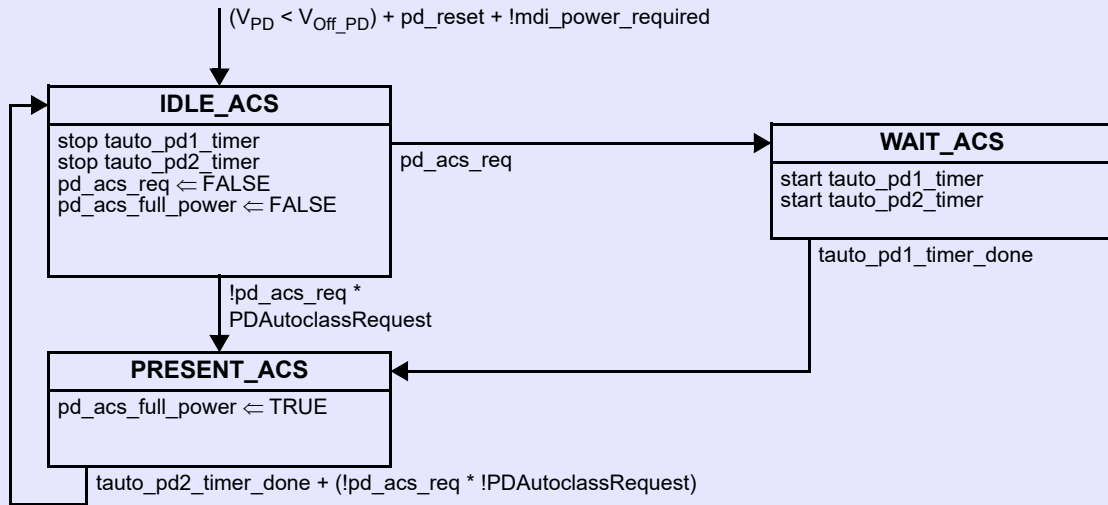


# P802.3bt D3.0 – Fixes to the Autoclass state diagram v105

## Info (not part of baseline)

There are mistakes in the Autoclass PSE and PD state diagram:



**Figure 145-27—Single-signature PD Autoclass state diagram**

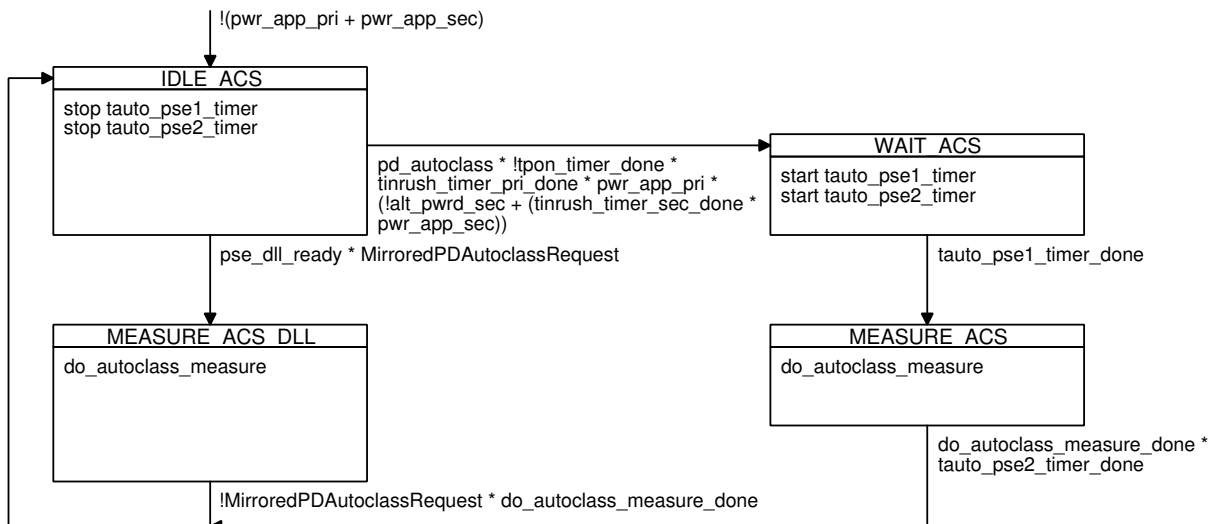
Because `pd_acs_req` is set to `FALSE` in the `IDLE_ACS` state (which is executed continuously until  $V_{PD} > V_{Off\_PD}$ ), the PD instantly forgets it has to do Autoclass based on Physical Layer. By clearing `pd_acs_req` in `WAIT_ACS`, we no longer can have a single `PRESENT_ACS` state because we can't distinguish the exit conditions.

On the PSE side there is a loop / race condition coming out of `MEASURE_ACS`. The `MirroredPDAutoclassRequest` gets reset to `FALSE` by the PD, but that takes time. When the PSE has concluded a measurement, it will go back to `IDLE_ACS` and immediately flip back into `MEASURE_ACS`. The solution is to make the PSE wait in `MEASURE_ACS_DLL` until the PD has cleared the `MirroredPDAutoclassRequest`.

As part of a wider problem in the DLL state diagrams: it is necessary to set 'Mirrored\_\*' variables prior to proceeding to states where those variables are read. If there hasn't been an incoming LLDPDU yet, the Mirrored variables have an undefined value and this causes undefined state diagram behavior.

## 145.2.5.7 State diagrams

Replace Figure 145-14 as follows:



**Figure 145-14 — PSE Autoclass state diagram**

### 145.3.3.7 Single-signature PD state diagrams

#### Info (not part of baseline)

We now also need to reset `pd_acs_req` in the main state diagram to prevent an issue with PD resets happening after `DO_CLASS_EVENT_AUTO` but prior to `INRUSH`.

Add the following statements to the **IDLE** state in Figure 145–26:

```
pd_acs_req ← FALSE
```

Replace Figure 145–27 as follows:

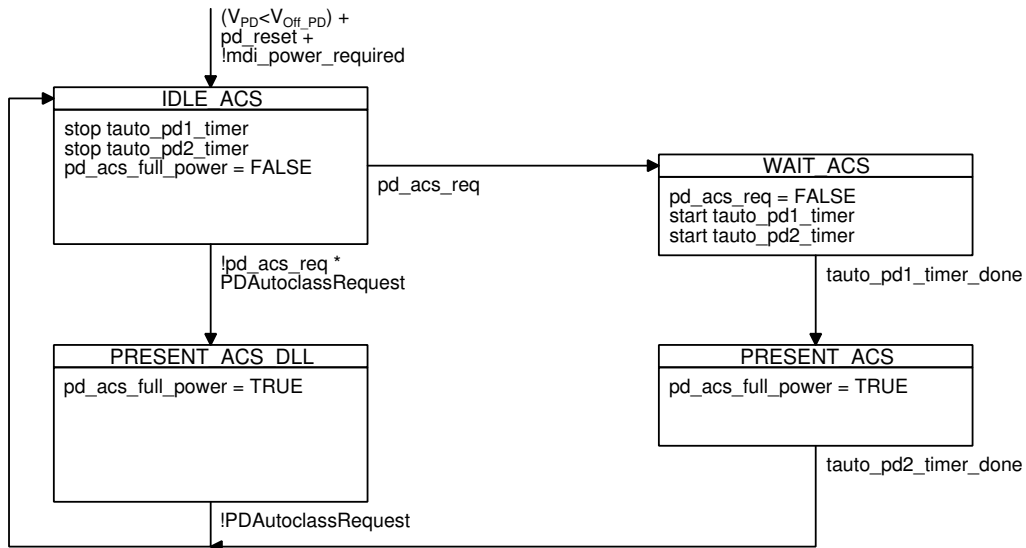


Figure 145–27 — Single-signature PD Autoclass state diagram

### 145.5.3.4.5 State diagrams

Replace Figure 145–42 as follows:

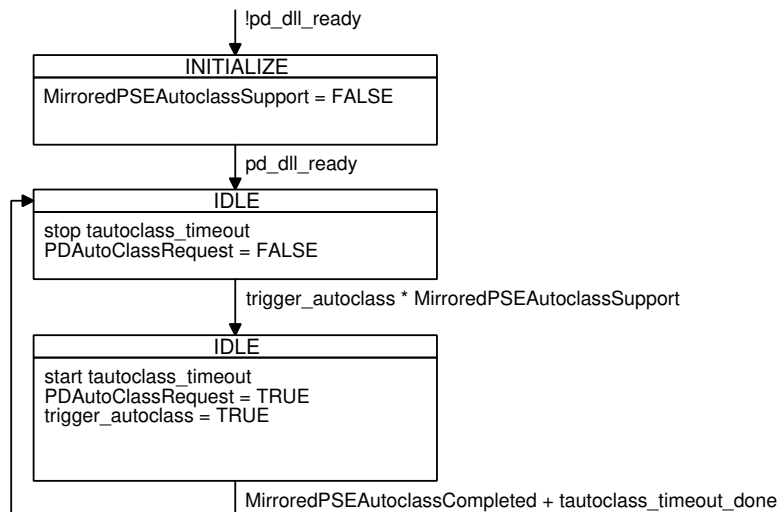


Figure 145–42 — PD DLL Autoclass control state diagram