

IEEE 802.3cg 10 Mb/s Single Twisted Pair Ethernet

CHARLOTTE: ELEVATOR/ESCALATOR USE CASE, TOPOLOGY AND FAILURE MODES

Introduction (elevators, global)

- Current network solutions:
 - Volume: mainly RS485-, CAN- and simple proprietary solution-based products
 - Sporadic: copper twisted pair point-to-point Ethernet ($\leq 100\text{m}$)
- On the worldwide market:
 - Currently: ≈ 850.000 new installations / year: each having avg. 20 serial port interfaces
 - 2020: $\approx 1.000.000$ new installations / year
- Requirements of near-future systems (functional safety, voice and video streaming) can not be met using these networks
- Product's life (market-dependent):
 - life-span is 15-20 years
 - life-time is 15-30 years, replaced/modernized afterwards
- We can estimate that half of the 20 million nodes per year market could be Ethernet-based in ten years' time

Example of current network (ISO OSI)

- L1: RS485, ≤ 250 kbps (slew-rate limited), ≤ 4000 f (≈ 1200 m), half duplex/multidrop (≤ 128 PHY)
- Single 18-23AWG stranded shielded twisted pair (copper), with termination
- L2: Manchester, CSMA/CA (p-persistent), 16-bit CRC
- L3-L7: proprietary protocol
- Several types of connectors (pitch in the range of 3-5.08mm)
- Separate wires in the same cable/connector for power and configuration/discovery
- Network may be branched: 1 backbone, single-level branches off of it (each branch with ≤ 128 PHY)

Future network: bird's eye view

- Specific architecture:
 - Machine-room: high communication speed
 - Hoistway/landings: daisy-chain of switches serving smaller branches
 - Travelling-cable: point-to-point, long reach
 - Car: multiple devices, in confined space (short-reach)
- High level of flexibility with regards to hardware:
 - Cable
 - Connector (inline and IDC)
 - Details: twist, stripping etc.
- PHY
 - Commercial solution preferred
 - Till then solution should be possible to be implemented in $\leq 100\text{MHz}$ Cortex-M4/7 without FP, with ADC/DAC and native DSP (or similar)

Future network: details

- Elevators: two models used as building blocks
 - Model A: branches (or very simple real systems)
 - Model B: trunk
 - Model A+B: real systems of wide range (distance and number of nodes)
- Self-synchronizing or support for a drift inherent to crystals (200ppm over whole temperature range)
- Framing should allow the following message classes to be supported (in decreasing order of importance):
 - Isochronous: safety monitoring (10/s, max jitter 1ms)
 - Immediate: safety events ($\leq 20/s$, delivery within 1ms)
 - Ad-hoc (on-demand): events ($\leq 200/s$, delivery within 10ms without safety)
 - Realtime: audio and video (properties are TBD)
 - None (idle): burn unused bandwidth for telemetry, file transfer (no guaranteed service)

Future network: environment

- Systems:
 - Elevators: Two models
 - Model A: ≤ 16 nodes, ≤ 100 m
 - Model B: ≤ 16 nodes, ≤ 1000 m
 - Model A+B: 200(+) nodes, 1000(+)m
 - Escalators: Simple network with few (≤ 10) nodes and medium reach (≤ 50 m), model A
 - Powerwalks: Simple network with few (≤ 10) nodes and medium reach (≤ 100 m), model A
- Environmental conditions
 - Industrial conditions, with temperature range of $-20^{\circ}\text{C} - +65^{\circ}\text{C}$
- Electrical requirements
 - Overvoltage and ground fault protection ± 40 V
 - Short- and open-circuit protection
 - Electrostatic discharge protection (EN 61000-4-2) 15kV
 - Fast transient protection (EN 61000-4-4) 2kV

Future network: what is not considered (needed)

- Intrinsic safety
- Hot-plugging

Future network: model A (branches)

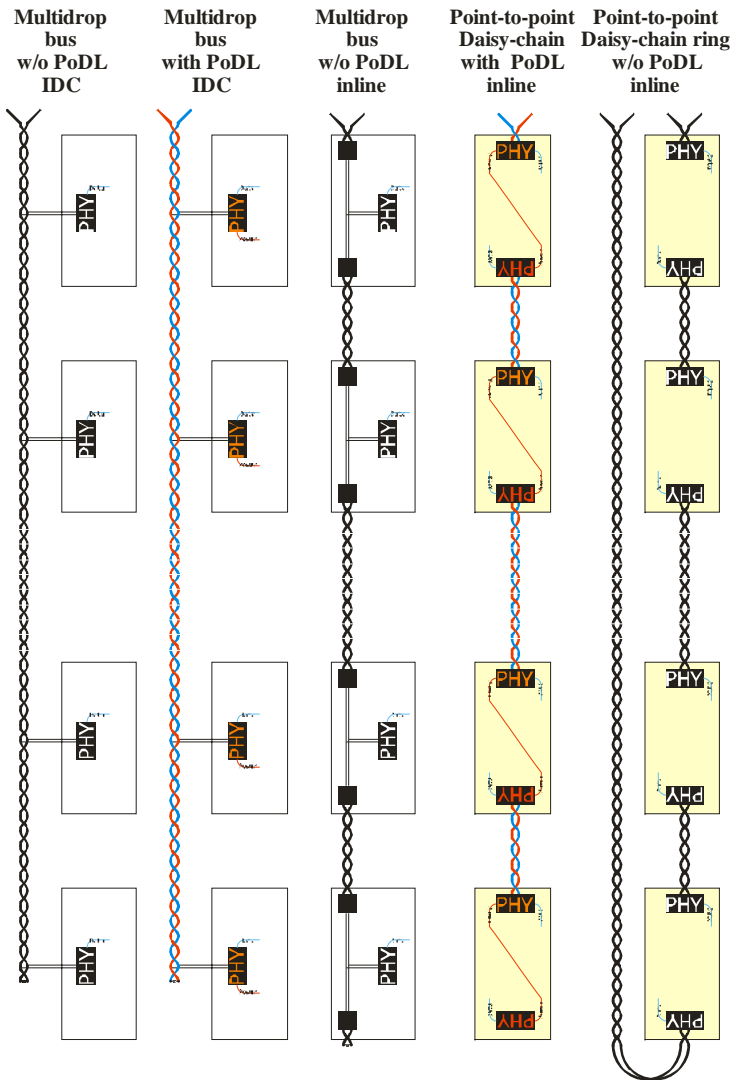
- Architecture: Single bus, 1 PHY/node (multidrop)
- Type: single shielded copper TP
 - As target is new device market (or when not, cables are replaced during modernization), there is high level of flexibility adopting external specs on cable and possibly on connectors
- Segment length: $\leq 100\text{m}$
- Nodes: ≤ 16 nodes
- PoDL (Σ for 16 nodes): $\leq 50\text{W}$ (avg.), $\leq 100\text{W}$ (peak), 24-48DC
- Other factors:
 - Native topology discovery: desired (through software): installation-time automatic node self-configuration (based on node order and possibly approximate distance)
- Possible use:
 - Hoistway/andings segments
 - Small car

Future network: model B

- Same as model A, with exceptions:
 - Length: long- ($\leq 1000\text{m}$) and intermediate-reach (50-100m)
 - Point-to-point may be possible
 - PoDL not needed
- Possible use:
 - Long reach: travelling-cable: constant mechanical wear (known bending radius)
 - Intermediate reach: hoistway/landings (backbone for model A segments)
 - Cable may need to be weight-bearing (complete or part of own weight) with or without IDC

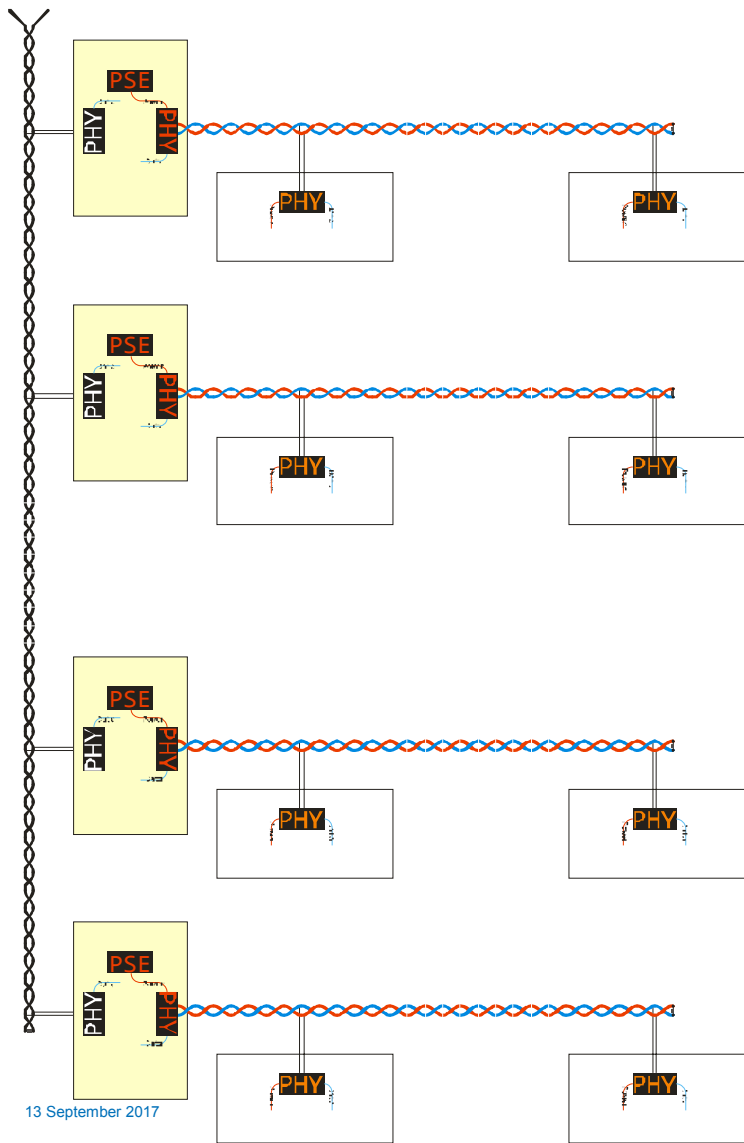
Future network: hybrid (complete network)

- Simplest elevators (volume):
 - A+B without segments
- Anything above:
 - A+B with appropriate amount and type of segments
 - Number of A segments is determined by system factors:
 - Floor distances (hoistway/landings image)
 - Powering requirements
 - Services (audio, video)
 - Need for redundancy

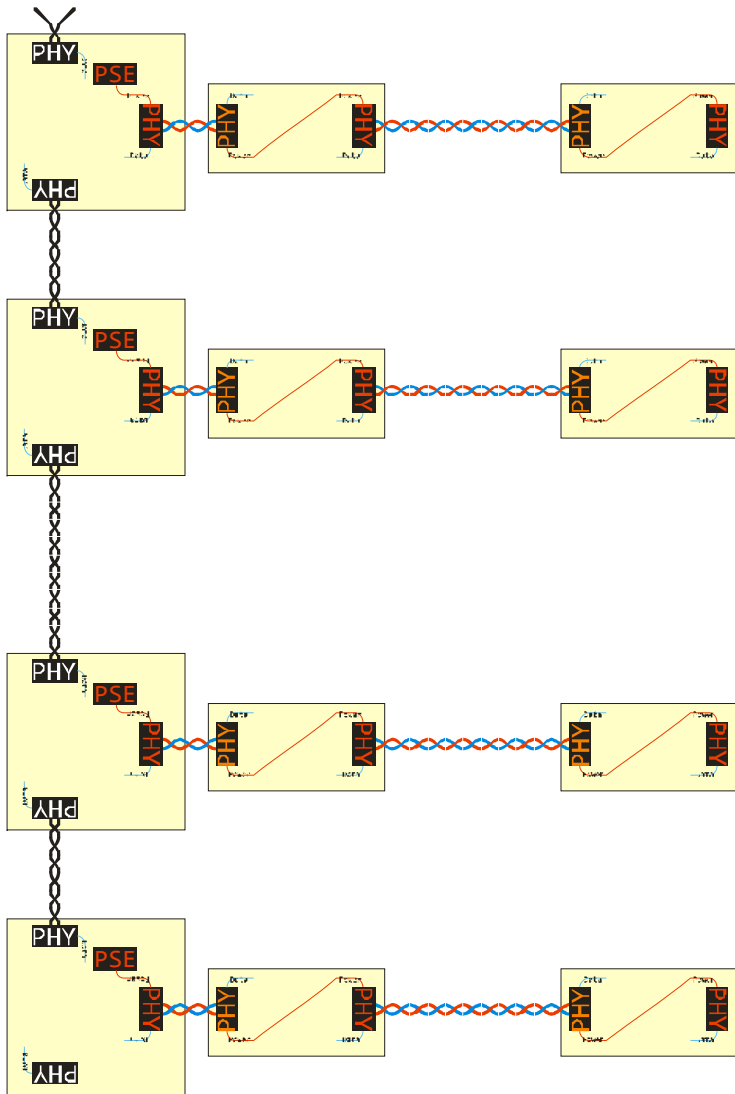


Legend:

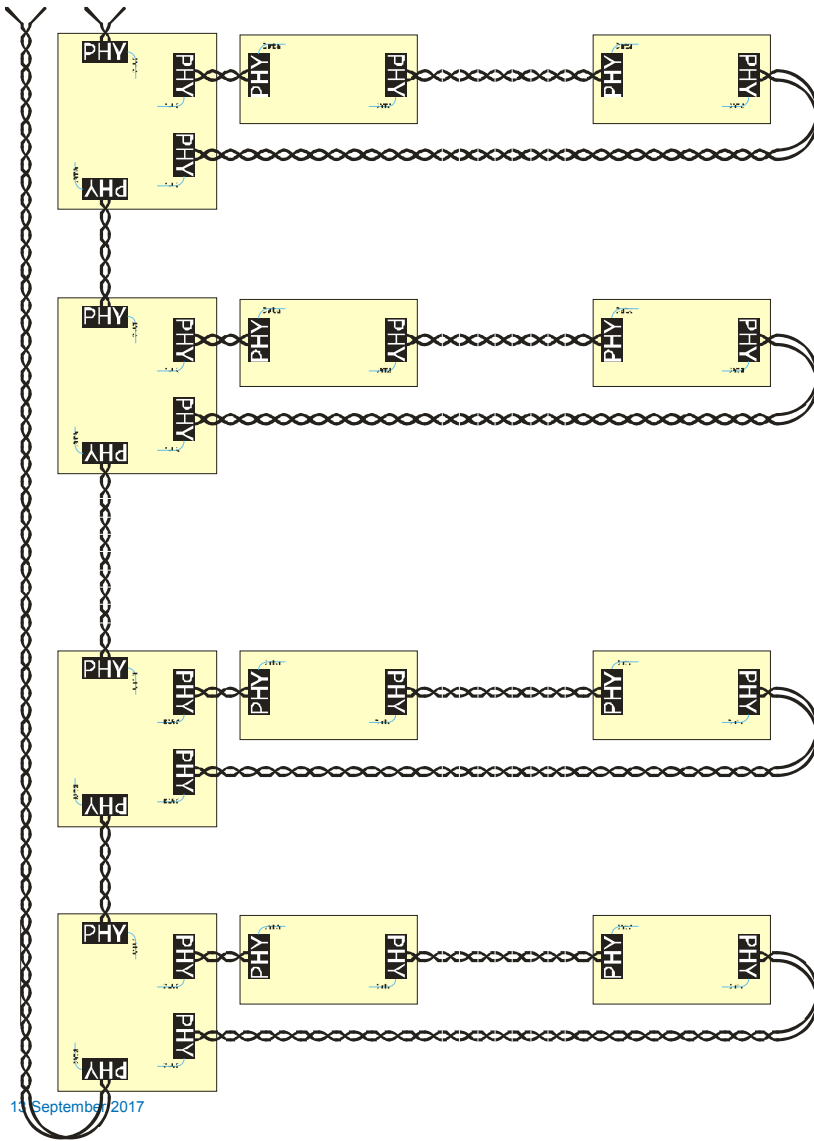
- Connector:
 - 1, 2, 4 and 5: Insulation Displacement Connector (IDC)
 - 3: Inline
- PoDL
 - 2: with multidrop
 - 4: with point-to-point
- PHY/PSE:
 - White: no PoDL
 - Red: PoDL producer (source)
 - Orange: PoDL consumer
- Cable:
 - Blue-red: Carrying data and power (24-48VDC)
 - Black: Data only



- Multidrop
- Model B backbone with no PoDL
- Model A branches with PoDL
- PSE on branch master (switch)
- Connectors: IDC (but can also be inline)
- Number of nodes is an example



- Point-to-point
- Model B backbone with no PoDL
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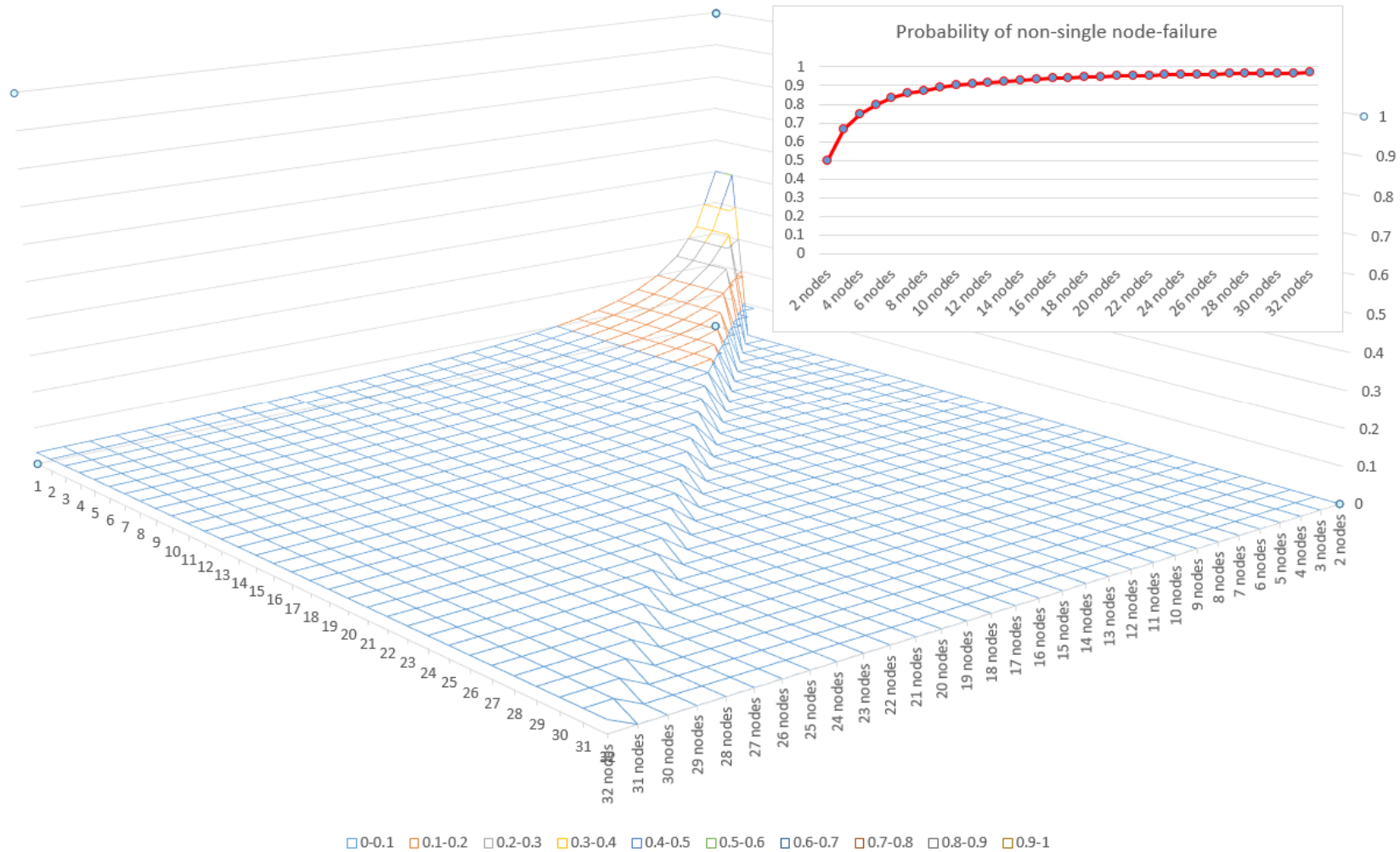
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Comparison of reliability

- Simulations have been run to compare performance of point-to-point and that of multidrop
- Failure mode included
 - Node L2+ failures (switching entity/host processor failure)
and/or
 - PHY failures rendering only local node unable to send/receive (no bus short/bias)
- Simulations try to show the following 2 factors:
 - Surface: probability distribution of the number of node going offline due to a single failure
 - Line: probability of given networks lose more than 1 node due to a single failure
- Failures are equiprobable and memoryless

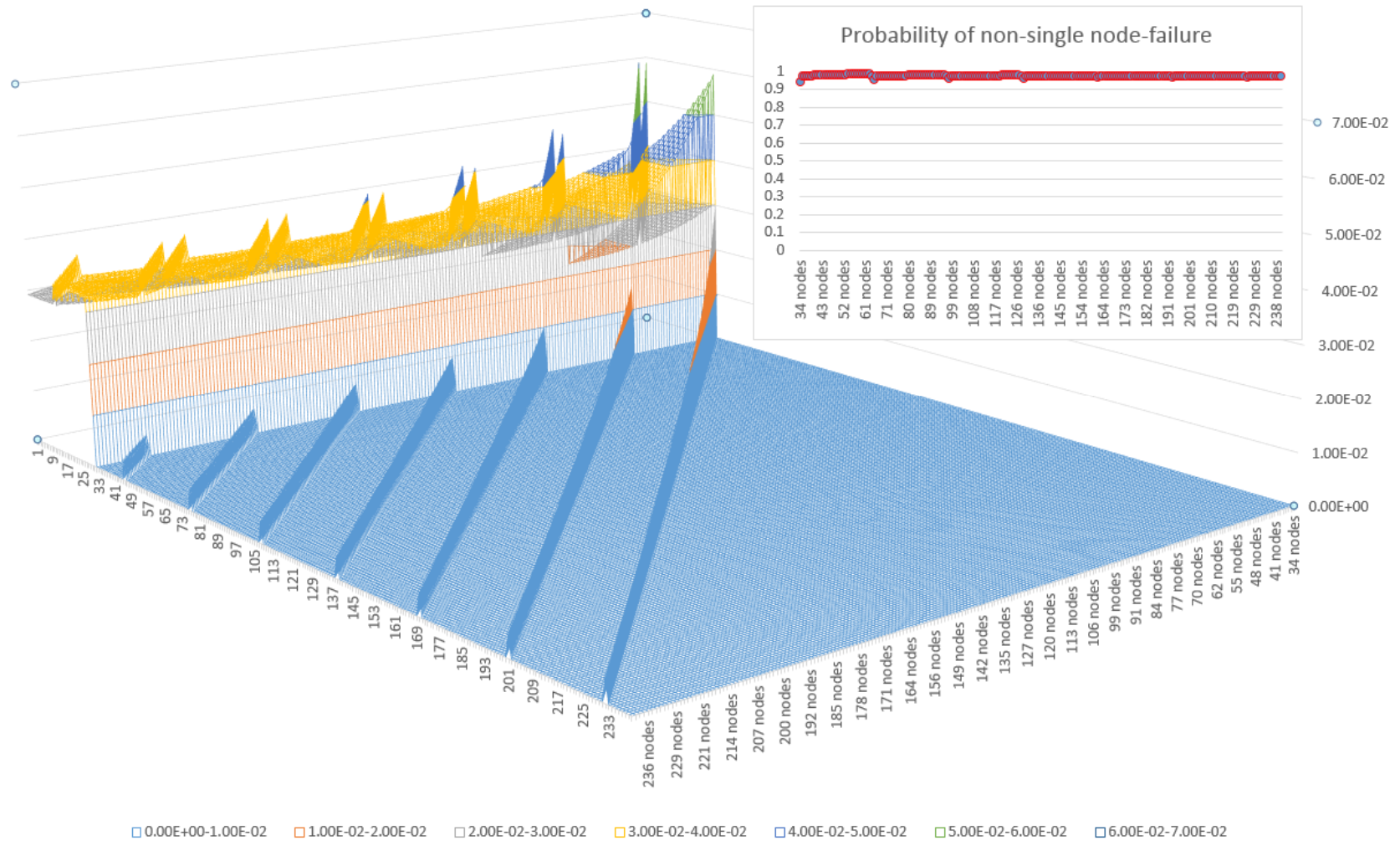
1-level point-to-point bus

Probability distribution of the effect of a single node failure



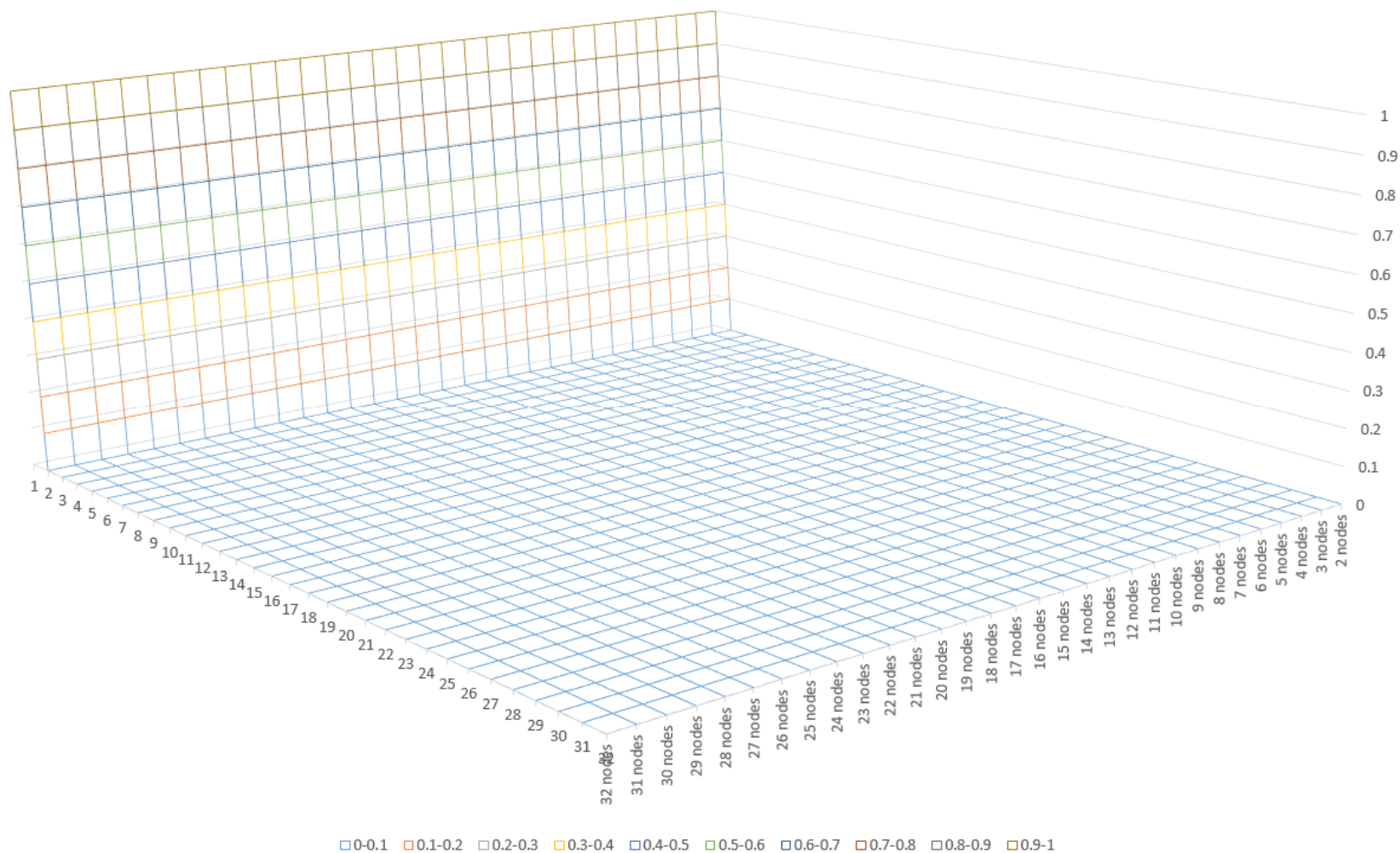
2-level point-to-point bus

Probability distribution of the effect of a single node failure



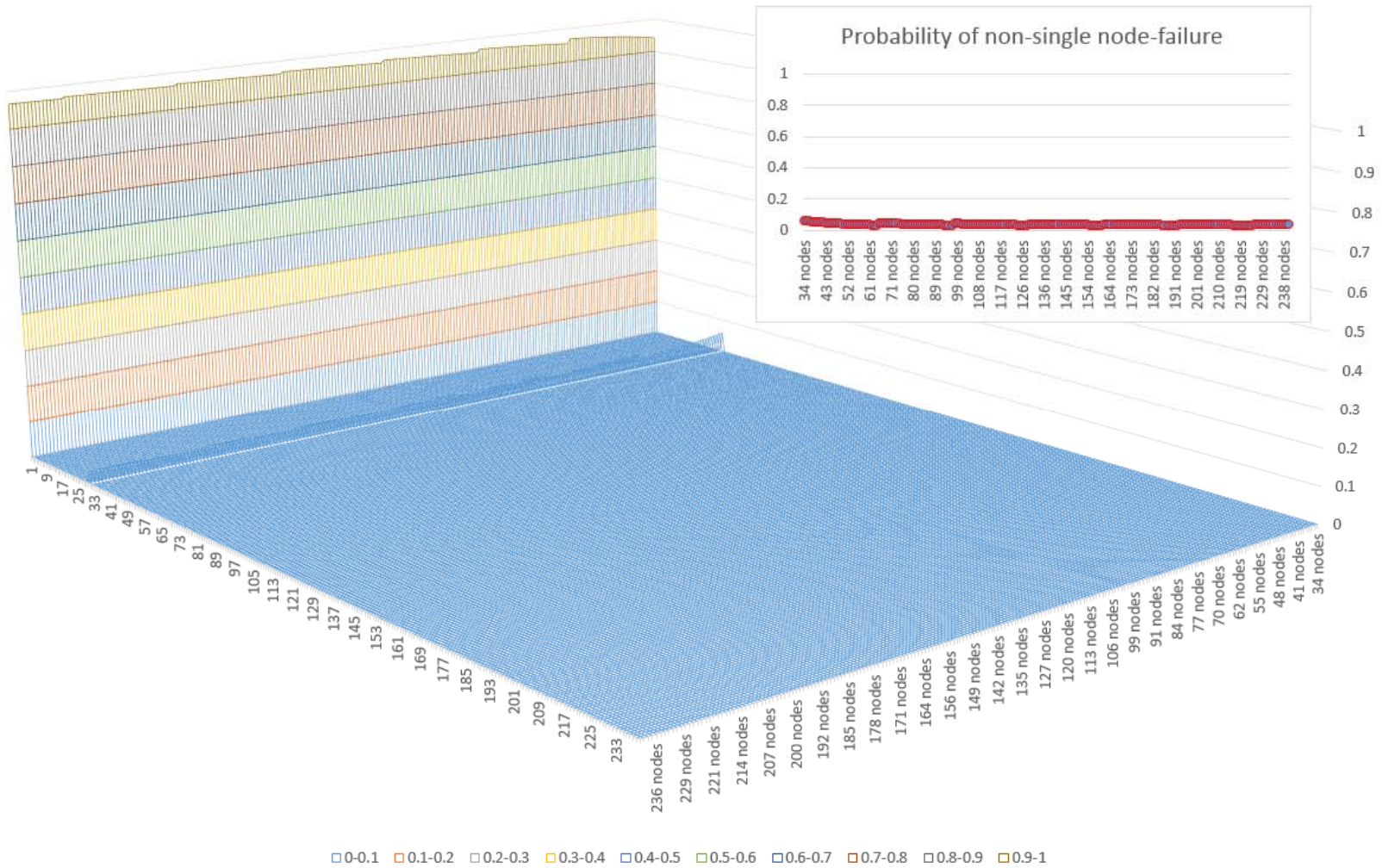
1-level multidrop bus

Probability distribution of the effect of a single node failure



2-level multidrop bus

Probability distribution of the effect of a single node failure



Interpretation

In these specific networks (topology) and under the above-mentioned conditions, multidrop seems to have more graceful degradation (loss of functionality) when nodes randomly fail

Thank you for your kind attention

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