Automotive link segment for 10SPE

Michael Kaindl, BMW Kirsten Matheus, BMW

Overview

- Goal for 10SPE automotive PHY must be to run on "CAN-like" or "FlexRay-like" cabling and connector configurations
- Bert Bergner showed measurements of 4mm pitch connectors showing the need to relax RF parameters to accommodate for 4mm pitch, see: http://www.ieee802.org/3/cg/public/July2017/DiBiaso Bergner 01a 0717.pdf
- Another set of measurements you can find under: http://www.ieee802.org/3/bw/public/buntz tazebay 3bw 01 0914.pdf
- Supplementing data from re-use of available "old" measurement data from RTPGE (measurement of a 100ohms FlexRay link out of a real automotive cable harness) to confirm this.
- Derive a possible set of parameters for the automotive P2P link segment
- This presentation does only focus on the Point-2-Point link segment.
 However, we believe the analysis applies to the passive linear multidrop link as well. This needs to be confirmed.

Part 1

 Re-visit of supplementing measurement data from http://www.ieee802.org/3/bw/public/buntz tazebay 3bw 01 0914.pdf

Device under test/measurement setup

• 2x0,35mm² 100 ohm jacketed cable in harness (approx. 3600mm) with inline connector (FlexRay).

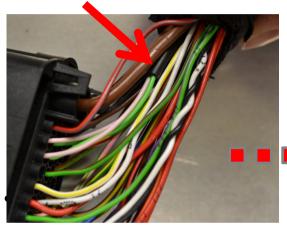


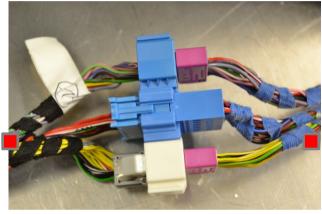
Device under test/measurement setup

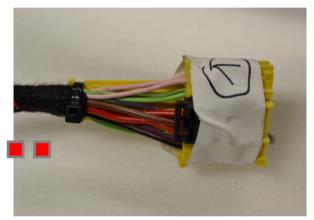
Connector1/jacketed cable

inline

Connector2







Test adapter

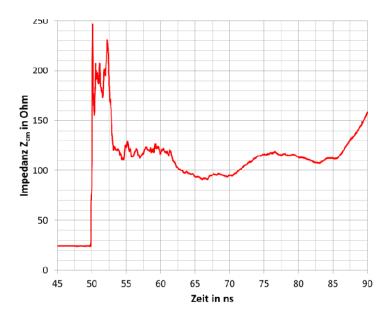
(as these were older measurements the test adapter is maybe not perfect...)

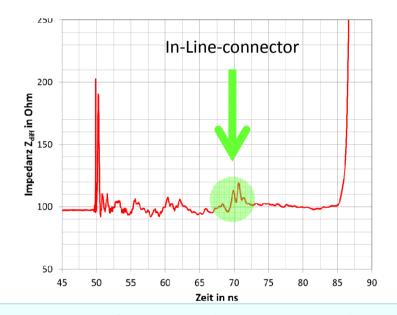
- Direct connection to GND plane.
- SMA heads soldered to Pins which are plugged into harness header.
- Complete harness on GND plane.
- No special treating of harness and assemblies to achieve high symmetry



TDR results Z_{cm} and Z_{diff}

as harness is placed 50mm above GND plane Z_{CM} is nearly constant





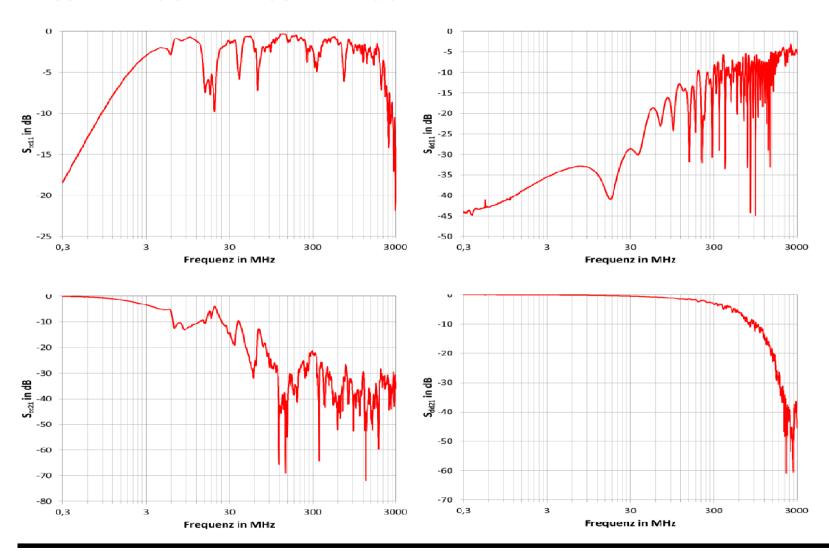
Z_{DM} may vary from 80ohms to 120ohms.

→ according RL influence to consider.

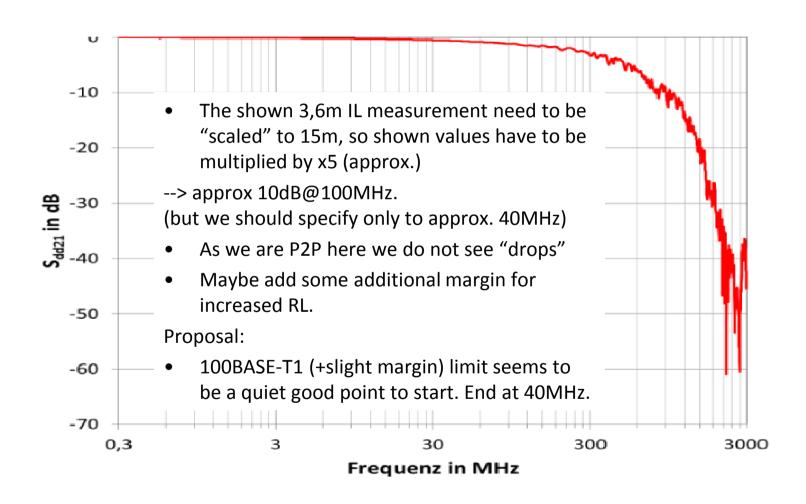
$$RL = 20 * log_{10} \left(\left| \frac{Z_2 - Z_1}{Z_2 + Z_1} \right| \right)$$

RL = 14dB (from DC)

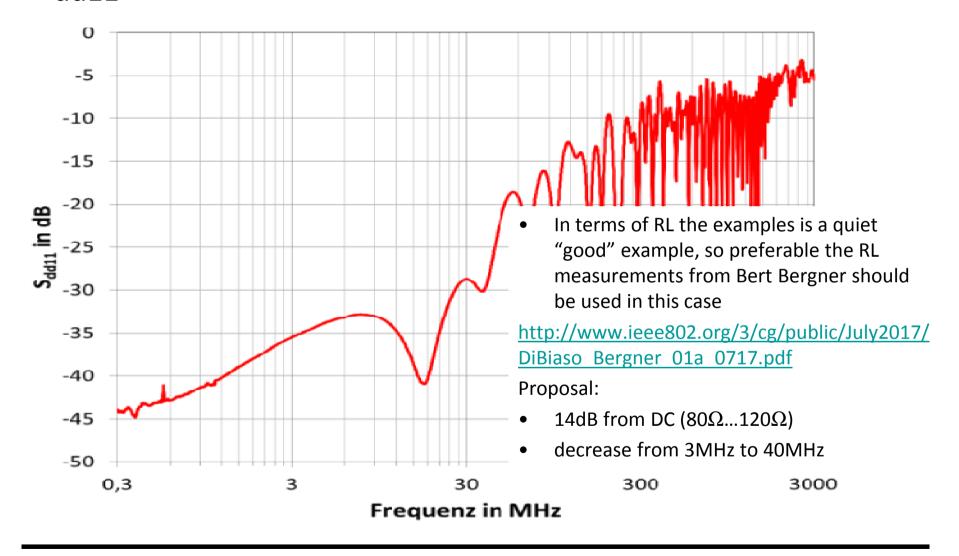
S_{cc11}, S_{dd11}, S_{cc21}, S_{dd21}



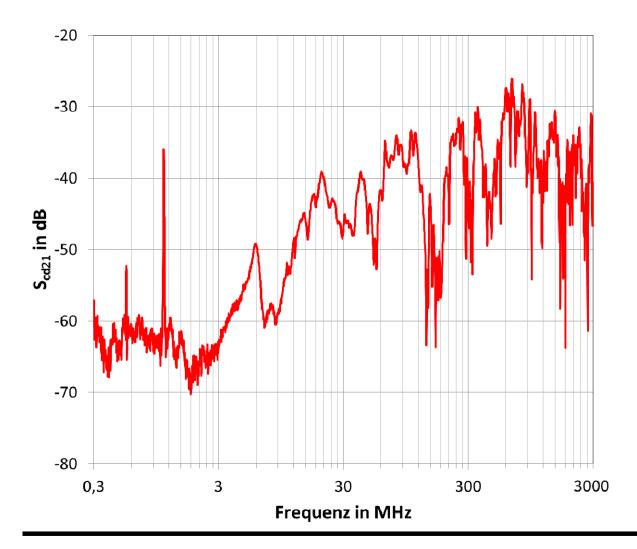
S_{dd21} (IL)



$S_{dd11}(RL)$



S_{cd21} (TCTL)



- This is just an example, mode conversion may not be worst case.
- Bert Bergners
 measurement have to be
 taken into account as
 well.

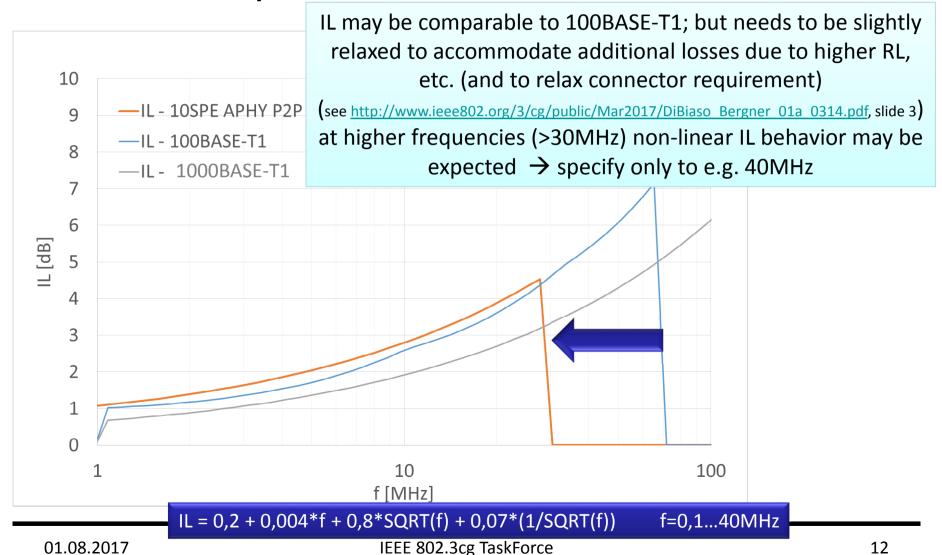
Proposal

- 30dB up 20MHz seems to give some reasonable margin.
- Above 20MHz decrease of MC is expected

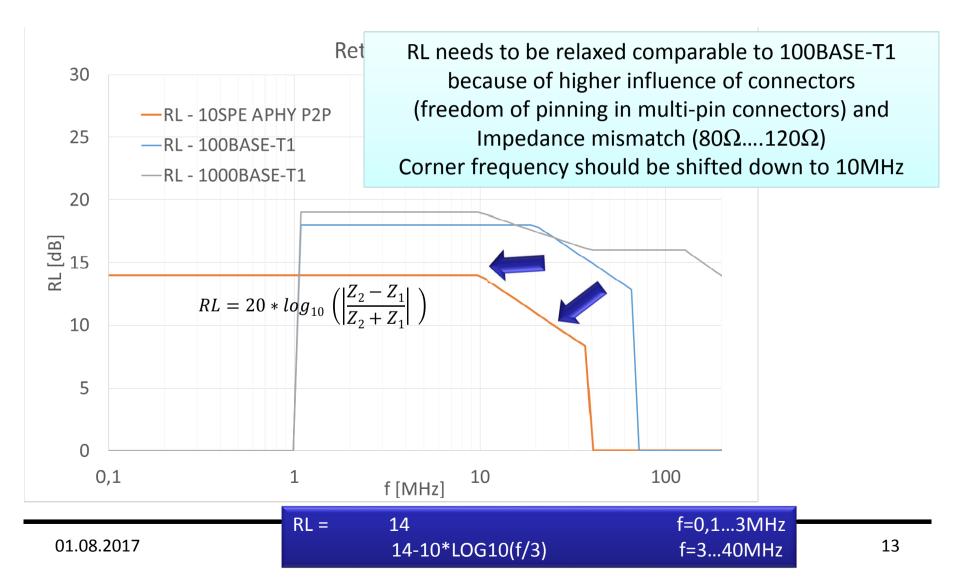
Part 2

- proposal for automotive P2P link segment
- (always with comparison to 100BASE-T1/1000BASE-T1)

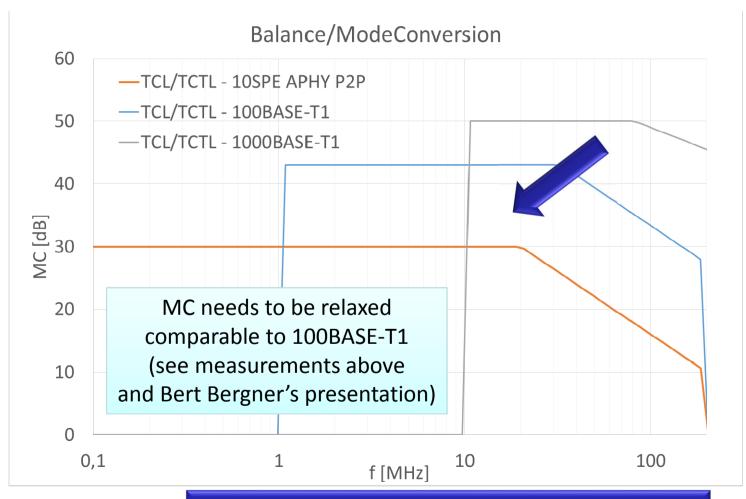
Look on RF parameter – comparison to 100BASE-T1/1000BASE-T1



Look on RF parameter – comparison to 100BASE-T1/1000BASE-T1



Look on RF parameter – comparison to 100BASE-T1/1000BASE-T1



Modeling of diagrams

For information here the used formulas for the shown diagrams for a potential 10SPE automotive PHY P2P link segment:

$$\begin{array}{lll} IL = & 0.2 + 0.004*f + 0.8*SQRT(f) + 0.07*(1/SQRT(f)) & f = 0.1...40MHz* \\ RL = & 14 & f = 0.1...3MHz & *coefficients are derived from matching to 100BASE-T1 curve} \\ & 14-10*LOG10(f/3) & f = 3...40MHz & \\ MC = & 30 & f = 0.1...20MHz & \\ & 30-20*LOG10(f/30) & f = 20...200MHz & \\ \end{array}$$

In addition, impedances of Z_{DM} = 80...120ohms are seen (this may not match to RL now...)

remark: MC = ModeConversion (in-pair) and CrossConversion (between pairs)

Conclusion

- The influence of the vehicle environment can not be neglected.
- Additional measurements of different OEMs and different connector/cable systems (which maybe are intended to be used for 10SPE automotive PHY) within a cable harness or a vehicle would be greatly appreciated to provide a better data basis.
- Based on the available data a baseline proposal could be made next meeting cycle
- This proposal is for the Point-2-Point link segment. We expect that it is suitable also for the passive linear link.
- 2. These inputs are intended to support semiconductor manufacturers in their investigations, if this indeed the case.