

# Asymmetric Reconciliation Sublayer

William Lo

December 19, 2018

From [http://www.ieee802.org/3/ch/public/adhoc/Lo\\_3ch\\_01\\_1218.pdf](http://www.ieee802.org/3/ch/public/adhoc/Lo_3ch_01_1218.pdf)

- Add an objective to 802.3ch

Define a power efficient mode of operation where one direction operates at 2.5Gb/s, 5Gb/s, or 10Gb/s, and the other direction operates at 10Mb/s

# Recap

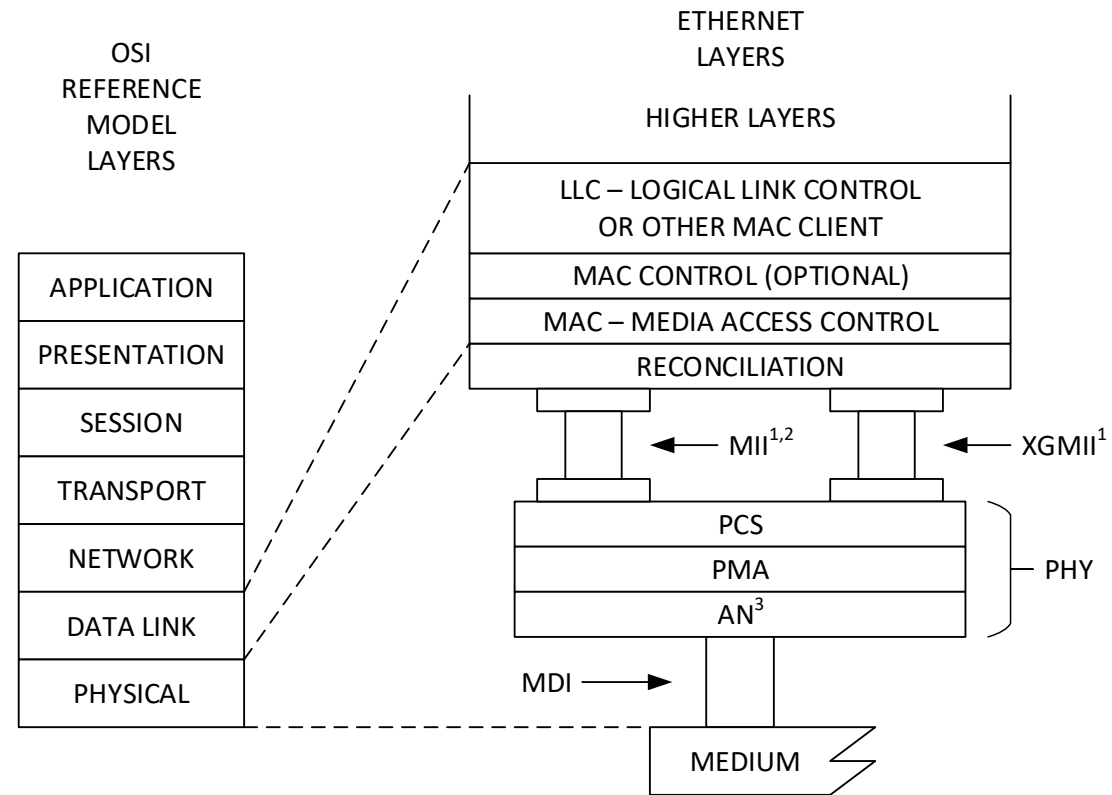
- Pick a standard Ethernet speed in the slow direction
  - i.e. 10M, 100M, 1Gb/s and not some weird speed
  - Things are well understood at standard speeds (timing, MIBs, etc.)
- Pick the slowest standard Ethernet speed that meets 90+% of volume
  - Picking some faster speed may impact power
  - Picking some faster speed may limit the solution space
  - If a faster speed is required use regular EEE
- Slow direction speed is typically less than 1Mb/s (I<sup>2</sup>C, SPI like speeds)
- Don't need both direction to be slow speed
  - Both directions can be fast
  - One fixed direction fast, other fixed direction slow.
  
- → Pick 10Mb/s in slow direction

# Recap

- Option 1:
  - XGMII in the 10Gb/s, 5Gb/s, 2.5Gb/s direction
  - MII in the 10Mb/s direction
  - Precedent for this Clause 76 – EPON. XGMII in one direction, GMII in the other
- Option 2:
  - Replicate the data on XGMII 1000x, 500x, 250x in the slow direction
- Other Options?
  - As long as the reconciliation sublayer layer does not introduce variable delays, it is a valid solution

# Discuss Option 1

- For MGBASE-T1 PHY define both XGMII and MII or its equivalent functionality as the base interface
- MII functionality is required only if asymmetrical modes implemented

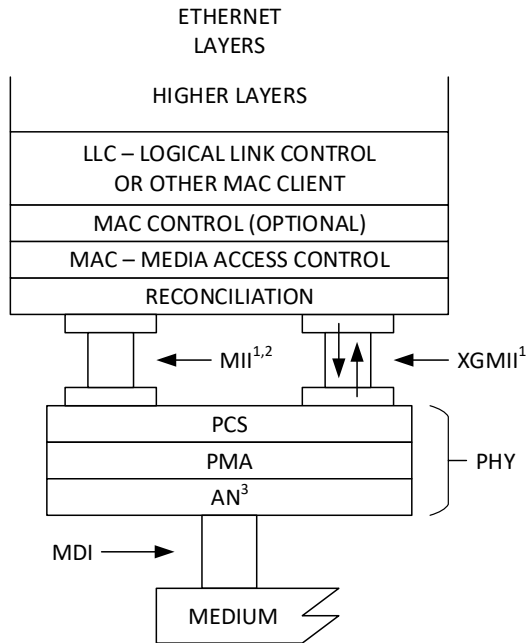


MDI = MEDIUM DEPENDENT INTERFACE  
 MII = MEDIA INDEPENDENT INTERFACE  
 PCS = PHYSICAL CODING SUBLAYER  
 PMA = PHYSICAL MEDIUM ATTACHMENT  
 PHY = PHYSICAL LAYER DEVICE  
 AN = AUTO-NEGOTIATION

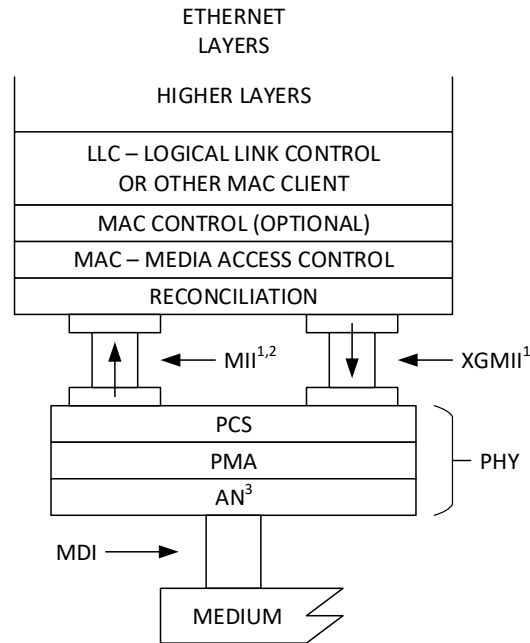
NOTE 1 - Implementation of a physical XGMII and MII is optional  
 NOTE 2 - MII or equivalent functionality is required only if the optional asymmetrical mode is implemented  
 NOTE 3 - Auto-Negotiation is optional

# Modes of Operation

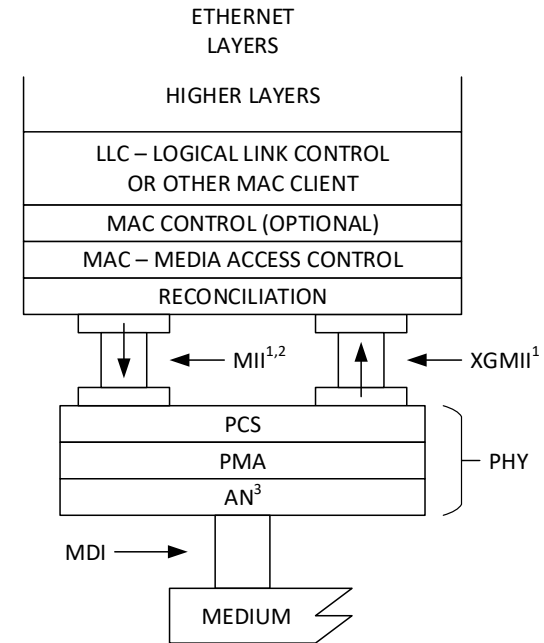
- Symmetrical Mode



- Slow RX Mode



- Slow TX Mode

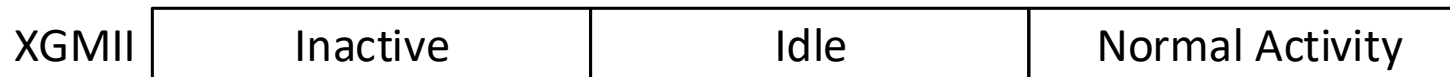
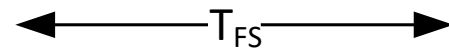
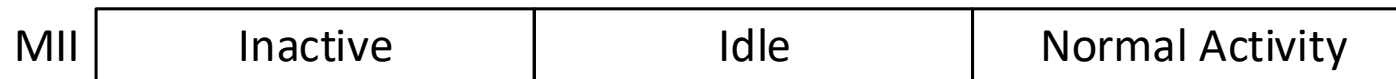


## How to Determine XGMII or MII is Active

- Define New Sequence Ordered Set On XGMII
  - /Q/00/00/04/ → Inactive XGMII
- Define New Encoding on MII
  - TX\_EN (RX\_DV) = 0, TX\_ER (RX\_ER) = 1, TXD<3:0> (RXD<3:0>) = 0010 → Inactive MII
- If both XGMII and MII are Inactive, the PHY treats it as IDLEs in the mode it is currently operating in

# How to Switch Between Modes

- $T_{FS}$  – Time for PHY to transition from fast to slow mode
- $T_{SF}$  – Time for PHY to transition from slow to fast mode





# THANK YOU