# Proposals for PBB-TE Segment Protection

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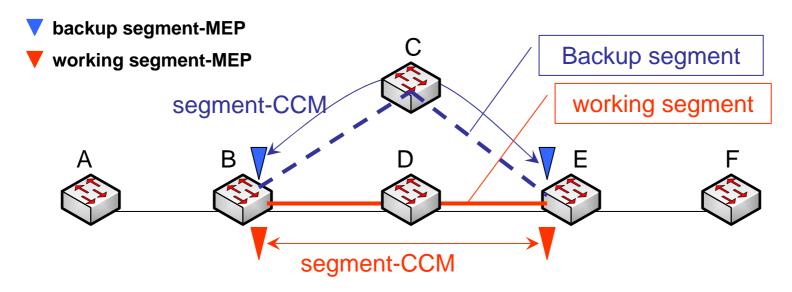
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- Segment protection detecting method
- Segment-BEB model for segment protection

### Background review

- ➤ In "new-sultan-segment-protection-requirements-1108-v01\*", several experts illustrated the requirements of segment protection.
- ➤ In "new-martin-PBB-TE-segment-prot-1108-v00\*", Mr. David W. Martin presented segment entity definition, integrity issues and some segment protection options.

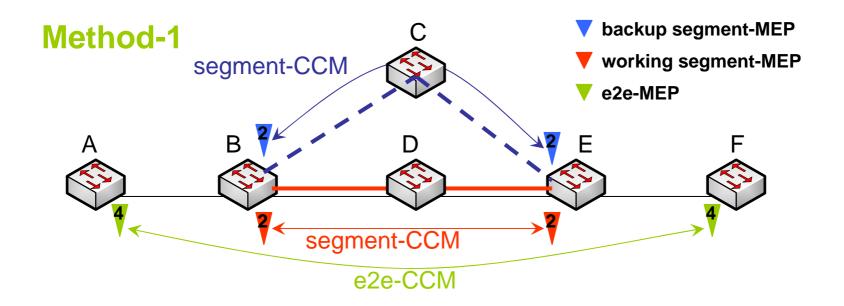
## Segment protection detecting method

#### Segment protection detecting method



- Create segment-MEPs (enhanced MIPs) at endpoints of both working and backup segment.
- Segment CCMs use ESP 3-tuple datapath <ESP-DA, ESP-SA, ESP-VID>, not <B, E, ESP-VID>. So MIPs will forward segment-CCMs follow e2e datapath
- Segment-CCMs are sent respectively to working segment and backup segment from segment-MEPs
- How to distinguish e2e or Segment CCMs on node B,E?

#### How to distinguish e2e or segment CCM? (1)



- Use different MD level for e2e-MEPs and segment-MEPs, e.g. the MD level of e2e-MEPs is 4 and segment-MEPs is 2
- Please note the SA and DA of segment-CCM are A and F, not B and E

#### How to distinguish e2e or segment CCM? (2)

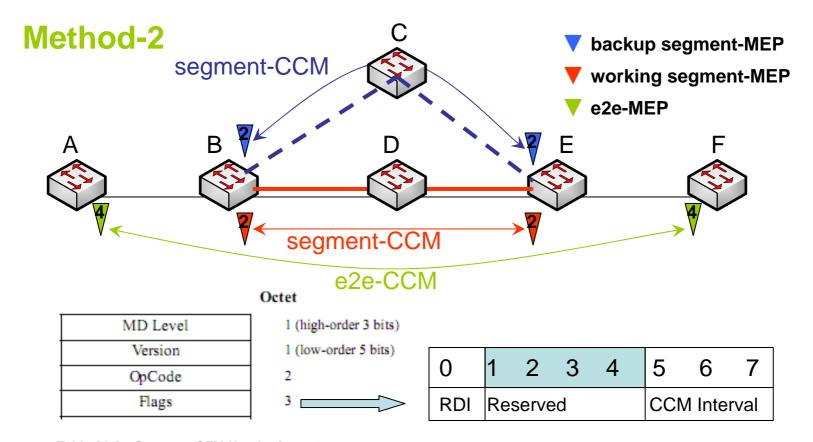
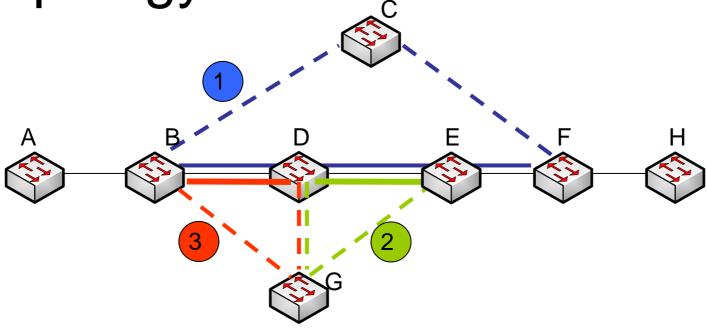


Table 21-3—Common CFM Header format

- Use reserved bits in Common CFM Header
- Segment-CCMs write the bits, e2e-CCMs don't write the bits.

Topology issue



- >SegProt1 can coexist with SegProt2 (nested)
- >SegProt1 can coexist with SegProt3 (tangent)
- ➤ How can SegProt2 coexist with SegProt3 ? (cross)

## Conclusion of segment protection detecting method

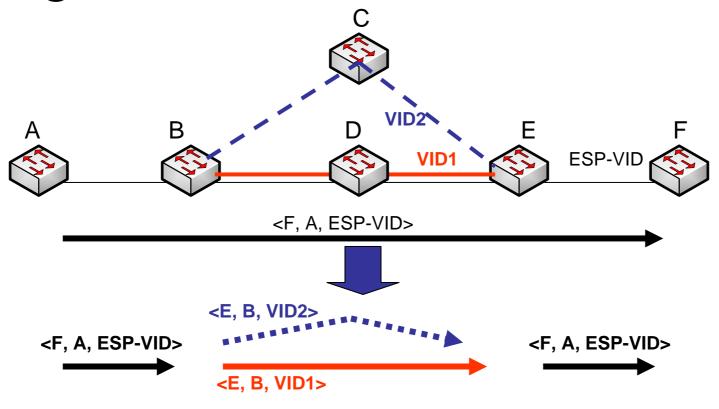
#### Summary

- ■The Ethernet header of segment CCM uses <ESP-DA, ESP-SA, ESP-VID>
- ■e2e and segment CCM can be distinguished by the endpoint of segment

Benefits	Limitations
<ul><li>■Do not affect e2e CCM and common data frames</li><li>■Support tangent and nested cases</li></ul>	■Need to revise 802.1ag
■Frame size is not increased	

## Segment-BEB model for segment protection

### Segment-BEB model



- Update BCBs at the endpoints of the segment to new BEBs. We just call it "Segment-BEB" here.
- Original <ESP 3-tuple> of a frame will be mapped to a new <ESP 3-tuple> within the segment and will be recovered when it leaves the segment

## Segment-BEB model (cont'd)

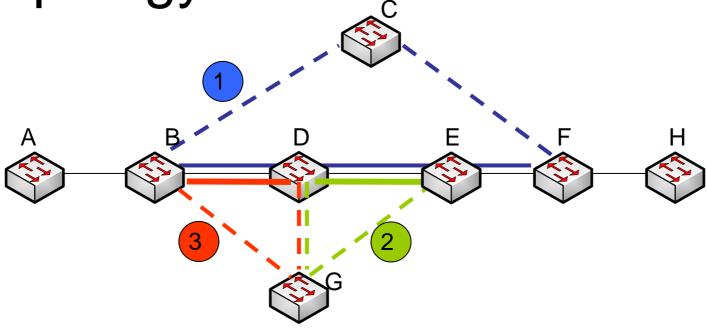
• Frame at segment ingress/egress

B-DA B-SA B-TAG I-TAG S-TAG C-TAG PAYLOAD B-FCS

- Frame within segment \_\_\_\_\_\_

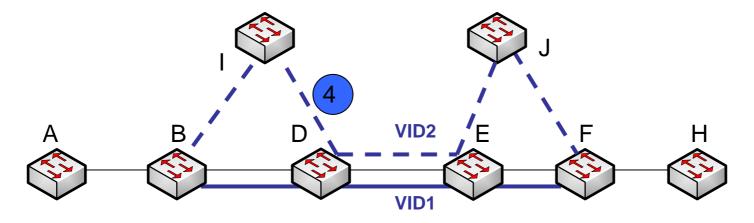
  SB-DA SB-SA SB-TAG I-TAG S-TAG C-TAG PAYLOAD SB-FCS
- VID2 ≠VID1
- If we regard <ESP 3-tuple> as a "label", it's like "label-switch"
- Since a segment is a totally new TESI, segment protection is just the same as e2e protection.

Topology issue



- >SegProt1 can coexist with SegProt2 (nested)
- >SegProt2 can coexist with SegProt3 (cross)
- ➤ How can SegProt1 coexist with SegProt3? Use a SegProt priority? (tangent)

## Topology issue (cont'd)



- ➤ Nodes D and E are shared by the backup and working segment of SegProt4
- The segment BEB model can support this scenario because VID2  $\neq$  VID1.

### Conclusion of segment BEB model

#### Summary

Update BCBs at the endpoints of the segment to Segment-BEBs to support <ESP 3-tuple> mapping

Benefits	Limitations
■Needn't define a new protection mechanism	■Need more BVLAN-ID  ■Must change the header of protected ESP frames within the segment
■Support cross and nested cases	
■Frame size is not increased	