

P802.1Qca D0.6 Tutorial

Explicit Path Control

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Outline



- Introduction
- Explicit Trees
 - Tree structures
 - Explicit ECT Algorithms
- Getting the trees
- Getting the VIDs
- Getting the MACs
- Summary

Presentation Objectives



- Explore the operation of explicit tree establishment as described in P802.1Qca D0.6 through examples
- Focus on the Explicit ECT Algorithms
- Explore the features provided
 - Simplifications are possible

Note that this presentation and
 http://www.ieee802.org/1/files/public/docs2013/ca-farkas-d0-4-operation-v01.pdf
 essentially say the same just from a little bit different angle

Disclaimer



- > The operation presented here is not the final standard!
- > There are open items and items under debate

Highlights

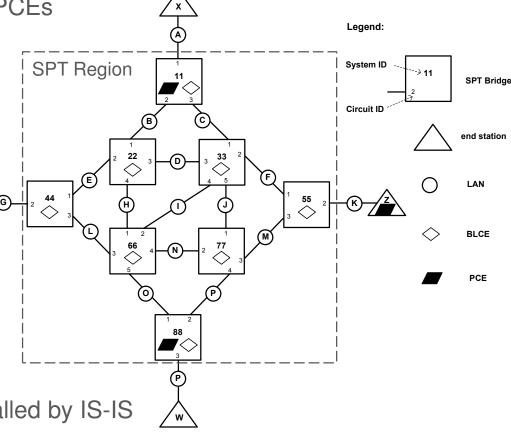


- > 802.1Qca is an extension to IS-IS
- It is control plane
- Main goal: establishment of explicit trees
 - -802.1Qca D0.6 is suitable for more generic explicit graphs
- An explicit tree is an undirected loop free graph
- Explicit trees do not require hardware changes!
- Forwarding is made directed (unidirectional) by MAC
- Forwarding can be made directed (unidirectional) by VID
- The algorithm the PCE uses for path computation is not specified by 802.1Qca

Explicit Trees



- > An Explicit Tree (ET) is controlled by a Path Computation Element (PCE) via IS-IS
- A PCE is a higher layer entity in a bridge or an end station
- An SPT Region may have multiple PCEs
- A Bridge Local Computation Engine (BLCE) is hosted by each bridge for (constrained) shortest path or MRT computation
- An ET is controlled by one PCE
- An ET is either fully specified or completely loose
- A fully specified ET is computed and described by its owner PCE, and then installed by IS-IS
- A completely loose ET only comprises the End Points and the ET is computed by the BLCEs, installed by IS-IS
- Loose and strict hops can be only mixed in a p2p path (as per D0.6)

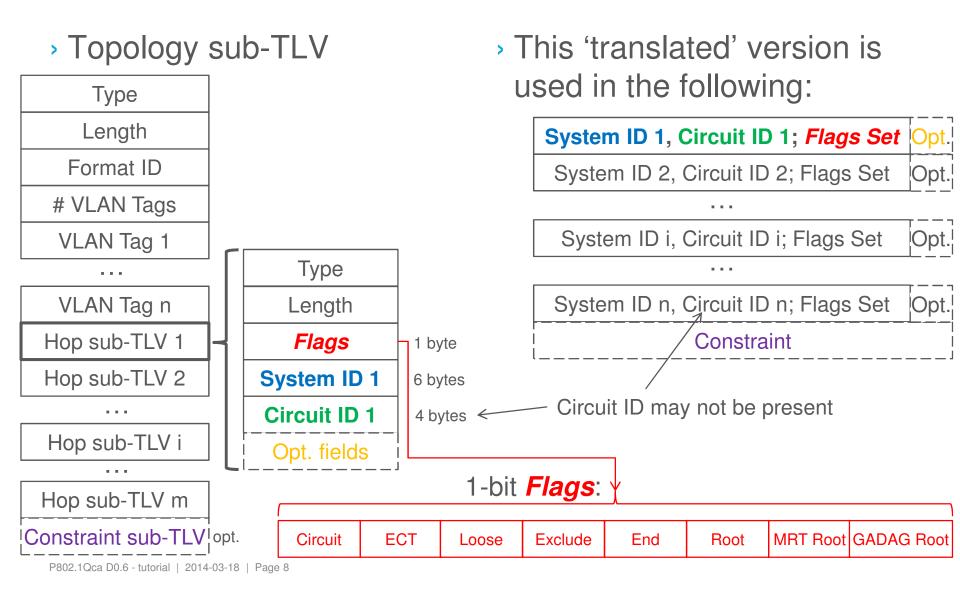




Getting the Trees

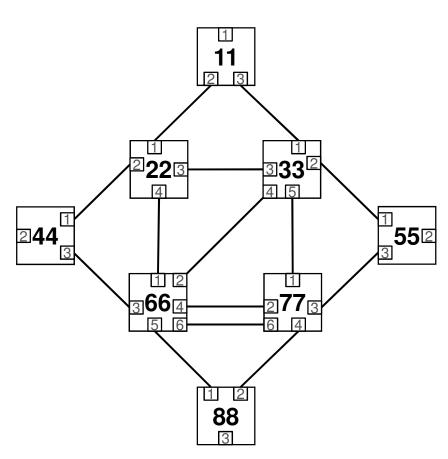
Topology Description





Example SPT Region Used in The Following



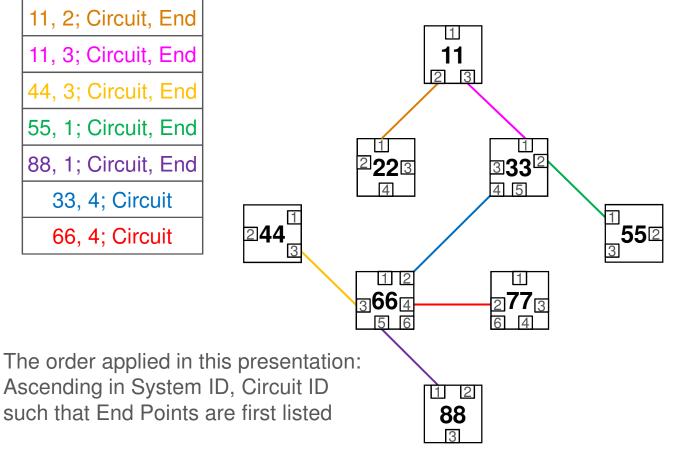


A Fully Specified Spanning Tree



arbitrary order

11, 2; Circuit, End 11, 3; Circuit, End 44, 3; Circuit, End 55, 1; Circuit, End 88, 1; Circuit, End 33, 4; Circuit 66, 4; Circuit

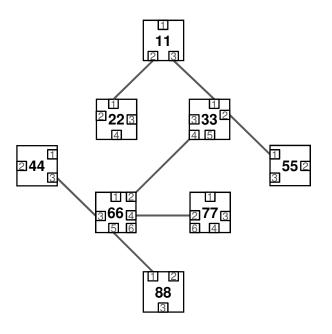


Tree Structures



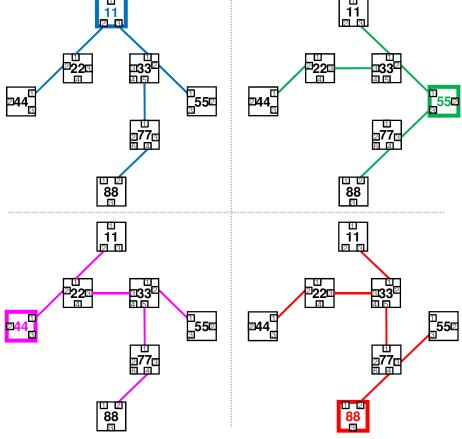
Ad-hoc tree

 A single tree in an arbitrary structure, e.g.



Template trees

A set of trees following a template;
 e.g. each edge bridge roots an SPT such that Bridge 66 is excluded



> (802.1aq SPB template = each bridge roots an SPT)

Explicit ECT Algorithms



- 1. Static Explicit SE ECT Algorithm
- 2. Loose Tree LT ECT Algorithm
- 3. Loose Tree Set LTS ECT Algorithm
- 4. Maximally Redundant Trees MRT ECT Algorithm
- Maximally Redundant Trees with GADAG MRTG ECT Algorithm
- 6. Maximally Disjoint Paths MDP ECT Algorithm

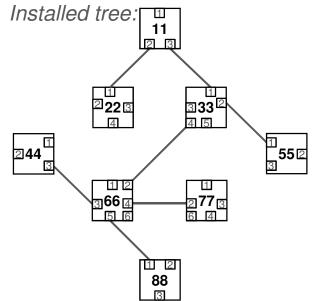
Static Explicit ECT Algorithm



- A single static explicit tree that does not contain any loose hops
 - This is the "fully nailed down" one
- The descriptor fully specifies the tree
 - → no loose hops
 - → no IS-IS update on its own → static
- > The owner PCE can only update the tree
 - PCE has to detect topology change
 - PCE computes new tree
 - Algorithm is only the PCE's business
 - PCE floods new descriptor
- SPT Bridges have no other task but install the appropriate FDB entries

Descriptor flooded by PCE:

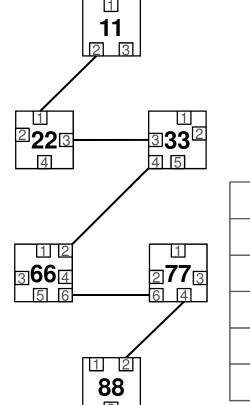
11, 2; Circuit, End		
11, 3; Circuit, End		
44, 3; Circuit, End		
55, 1; Circuit, End		
88, 1; Circuit, End		
33, 4; Circuit		
66, 4; Circuit		



Static Explicit ECT Algorithm – cont'd



- Exact order has to be followed if Circuit ID is not present in the descriptor of a p2p path
- Circuit ID is always used in case of multipoint-to-multipoint ET
- Circuit ID is always used in case of parallel links (e.g. 66 ⇔ 77)



exact order

11; End			
22			
33			
66, 6; Circuit			
77			
88; End			

arbitrary order

11, 2; Circuit, End			
11, 2, Gircuit, End			
88, 2; Circuit, End			
22, 3; Circuit			
33, 4; Circuit			
66, 6; Circuit			

Loose Tree ECT Algorithm

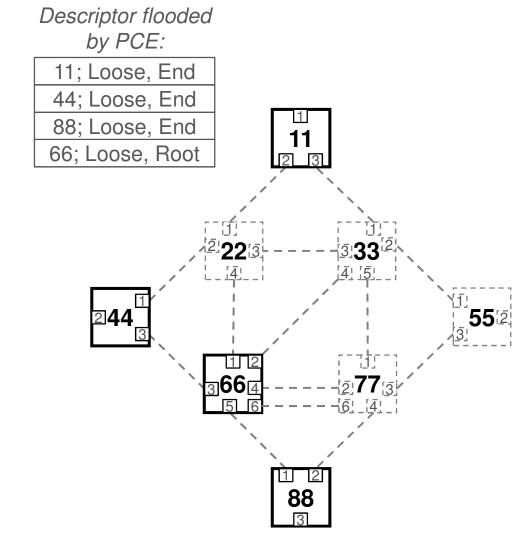


- > A single explicit tree that includes one or more loose hops
- A loose multipoint-to-multipoint ET must always be entirely loose, i.e. the descriptor can only comprise the End Points; each of them is a loose hop
- BLCEs compute the tree
 - → Root has to be specified by the Topology sub-TLV
- Constrained routing is used if Topology sub-TLV conveys constraint, e.g. Admin Group or Exclude Hop
- Loose hops are restored by IS-IS
- Loose and strict hops can be mixed in a p2p path (as per D0.6)
- > see examples in the following slides

Loose Tree ECT Algorithm Example 1: A Completely Loose Tree



The tree to span 11, 44, 88, and 66; such that 66 is the Root

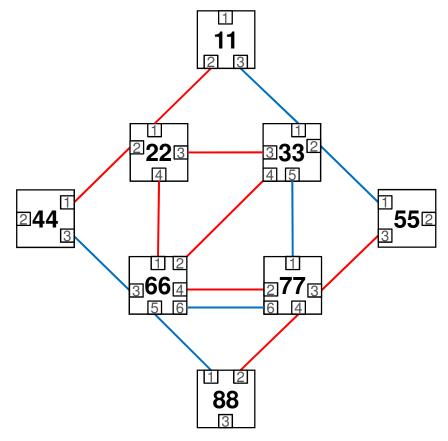


Loose Tree ECT Algorithm Example 2: Administrative Groups



The color of the link represents the Administrative Group it

belongs to



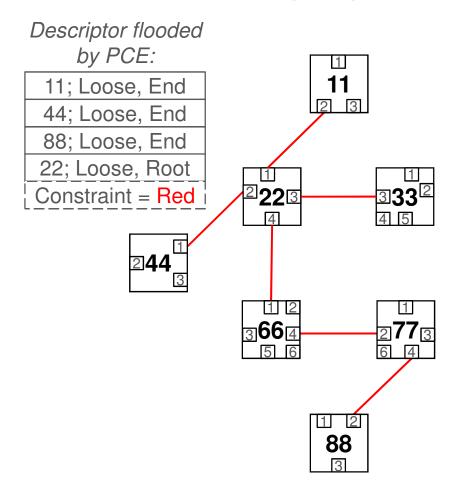
Loose Tree ECT Algorithm Example 2: Constrained Routing



The Topology sub-TLV conveys an Administrative group

sub-TLV (Type = 3), which specifies the Red group

The descriptor specifies that the tree to span
11, 22, 44, 88,
such that 22 is the Root



Loose Tree Set ECT Algorithm



- A set of completely loose explicit trees, which set comprises an individual tree for each end point specified by the descriptor of the explicit tree
- Each tree is computed by the BLCE of SPT Bridges
- Each tree is restored by IS-IS in case of a topology change
- These are template trees
- The LTS ECT Algorithm can be used
 - If only a subset of edge bridges are to be connected by template trees
 - If the template trees are not SPTs because a constraint has to be applied on them, e.g. Admin Group or Exclude Hop

LTS ECT Algorithm Example: Excluding a Bridge

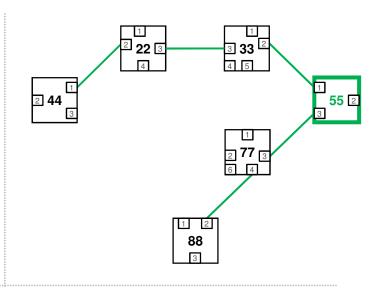


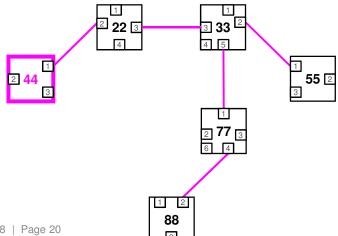
Bridge 66 is an Exclude Hop

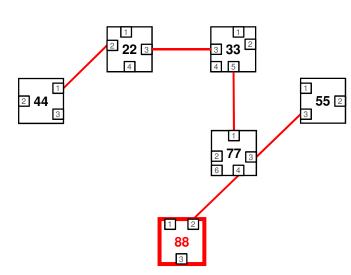
Descriptor flooded by PCE:

44; Loose, End 55; Loose, End 88; Loose, End

66; Exclude







Maximally Redundant Trees ECT Algorithm



- Maximally Redundant Trees (MRTs) are completely loose trees for each MRT Root
- The MRTs are computed together with the corresponding GADAG by the BLCE of SPT Bridges
 - → Completely distributed operation
- MRTs are cautiously restored by ISIS-PCR
- > Two options
 - Each SPT Root is an MRT Root as well
 - No Topology sub-TLV; in fact no 802.1Qca sub-TLV
 - Base VID is associated with the MRT ECT Algorithm in the SPB Base VLAN-Identifiers sub-TLV; and that's all
 - 2. MRT Roots are specified by Topology sub-TLV
- > This is Mode A of http://www.ieee802.org/1/files/public/docs2014/ca-farkas-mrt-0114-v01.pdf

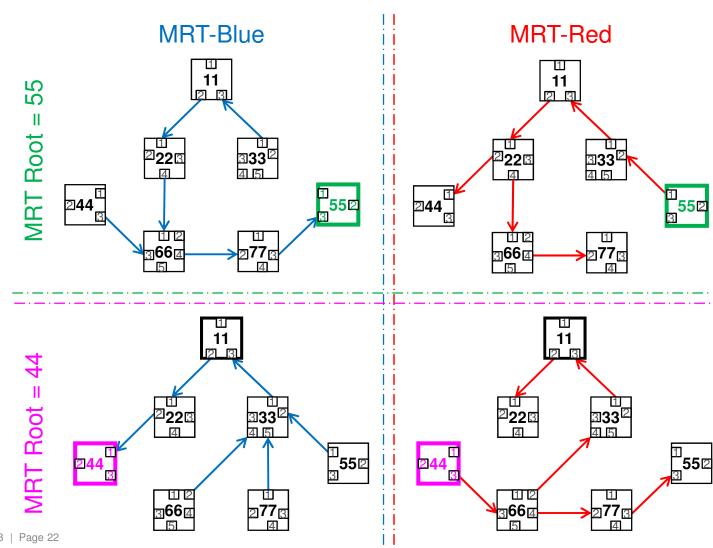
MRT ECT Algorithm Example: MRT Roots Specified



- > MRT Roots:
 - 44 and 55
- > 88 is not included

Descriptor flooded by PCE:

11; Loose, End, MRT Root 44; Loose, End, MRT Root 55; Loose, End, MRT Root



Maximally Redundant Trees with GADAG ECT Algorithm



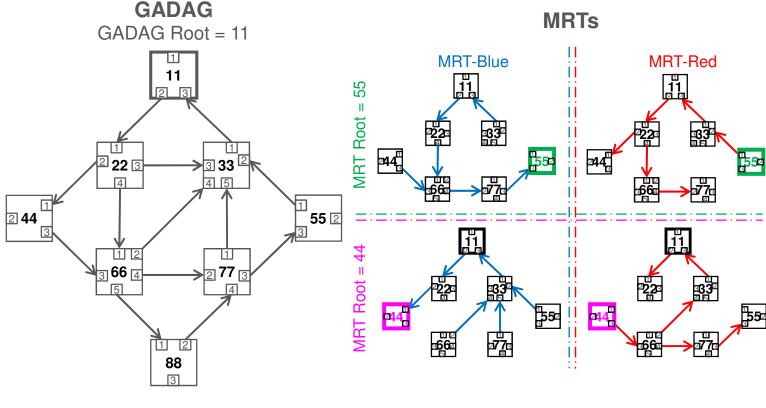
- GADAG is computed centrally by GADAG Computer, e.g.
 PCE
 - → Centralized GADAG computation
- GADAG Computer floods GADAG descriptor
 - MRT Roots are also specified by the Topology sub-TLV specifying the GADAG
- MRTs are then computed by the BLCE of SPT Bridges based on the GADAG
 - → Distributed MRT Computation
- MRTs are cautiously restored upon reception of a new GADAG from the GADAG Computer
- > This is Mode B of http://www.ieee802.org/1/files/public/docs2014/ca-farkas-mrt-0114-v01.pdf
 - (Mode C can be implemented by the Static Explicit ECT Algorithm)

MRTG ECT Algorithm Example



Descriptor flooded:

11, 2; Circuit, End **GADAG** Root 22, 2; Circuit 22, 3; Circuit 22, 4; Circuit 33, 1; Circuit 44, 3; Circuit, End MRT Root 55, 3; Circuit, End MRT Root 66, 2; Circuit 66, 4; Circuit 66, 5; Circuit 77, 1; Circuit 77, 3; Circuit 88, 2; Circuit



Maximally Disjoint Paths ECT Algorithm



- Maximally Disjoint Paths (MDPs) are a pair of point-to-point paths
- > The paths are computed as specified by 45.3.5
- The loose hops are cautiously restored by IS-IS



Getting the VIDs

VID Direction



- A VID can be made associated with a particular explicit tree by the inclusion of the corresponding VLAN Tag in the Topology sub-TLV (preceding the Hop sub-TLVs)
- Each VID is bidirectional by default
 - Each End Point bridge both Transmits (T) and Receives (R) on a
 VID
 - It is the default behavior → No filed for it in the sub-TLVs
- Different behavior can be configured by setting the VIDs T/R flags in the Hop sub-TLV of the End Point bridge

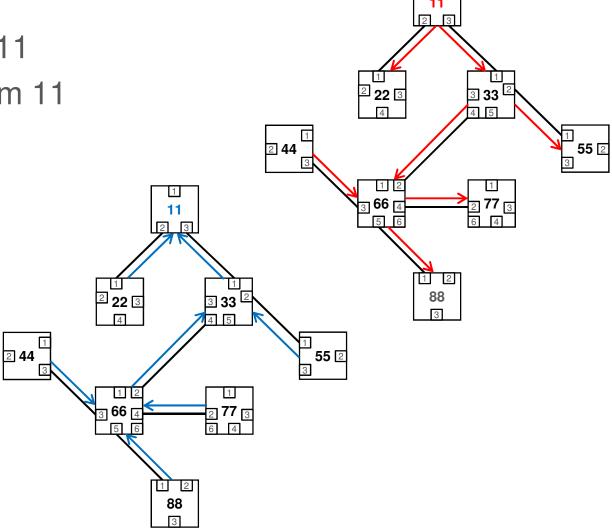
Directed VIDs Example



- VID1 is directed to 11
- VID2 is directed from 11

Descriptor flooded:

11, 2; Circuit, End	VID1: R	VID2: T		
11, 3; Circuit, End	VID1: R	VID2: T		
44, 3; Circuit, End	VID1: T	VID2: R		
55, 1; Circuit, End	VID1: T	VID2: R		
88, 1; Circuit, End	VID1: T	VID2: R		
33, 4; Circuit				
66, 4; Circuit				





Getting the MACs

MAC Gives Direction

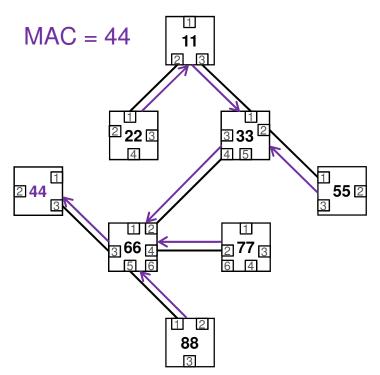


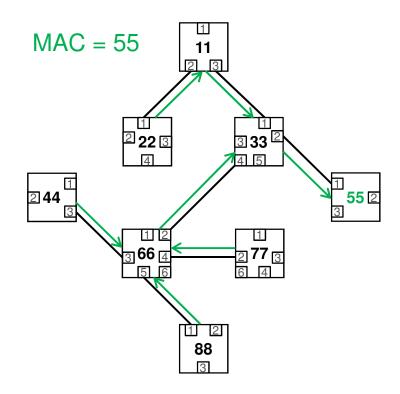
- Learning VID
 - VID → SPBV-MSTID
 - MAC learnt from data frames
- Non-learning VID
 - VID → SPBM-MSTID
 - MAC associated with a VID is learnt from SPBV MAC Address sub-TLV
 - MAC associated with an I-SID is learnt from SPBM Service Identifier and Unicast sub-TLV

Directed by MAC Example



The topology provided by the FDB entries to an Individual MAC is a destination rooted tree within the region (irrespectively of the means the bridges become aware of the location of the MAC)







Summary

It Is Simple



- A very few pieces (= IS-IS TLVs) of the puzzle provide the full picture!
- SPT Bridge declares:
 - VID for explicit path control
 (VID → an explicit ECT Algorithm in the SPB Base VLAN-Identifiers sub-TLV)
 - MACs it Transmits / Receives
 - > VID scope: SPBV MAC Address sub-TLV
 - > I-SID scope: SPBM Service Identifier and Unicast sub-TLV
- PCE provides the Explicit Tree for the VID (Topology sub-TLV)
- → Brides get all this information → install FDB entries