

Hierarchical CUC/CNC management model

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Overview

Problem statement: It seems that neither IEEE standards nor “IEC/IEEE 60802 D1.1 TSN Profile for Industrial Automation” is prescribing any reference management model which deals with the hierarchical CUC/CNC scenario.

Goals:

- Abstract system models for configuration and monitoring in hierarchical CUC/CNC scenario.
- Identify requirements, gaps and potential remedies.
- Application examples.

Previous/Parallel work:

[4], [6], [7], [8], [9], [10], [12], [13], [14], [15], [16].

- **Disclaimer** – All models in this presentation may be known to the working groups.

Summary (v1)

Step 1 (Framework):

- Streamline configuration and monitoring planes.
- Based on generic and reusable system models.
- Model driven networking (try to avoid additional protocol).
- Identify gaps such as, missing abstractions and data models.

Step 2 (Primary Application):

- Holistic view of system configuration and monitoring planes.

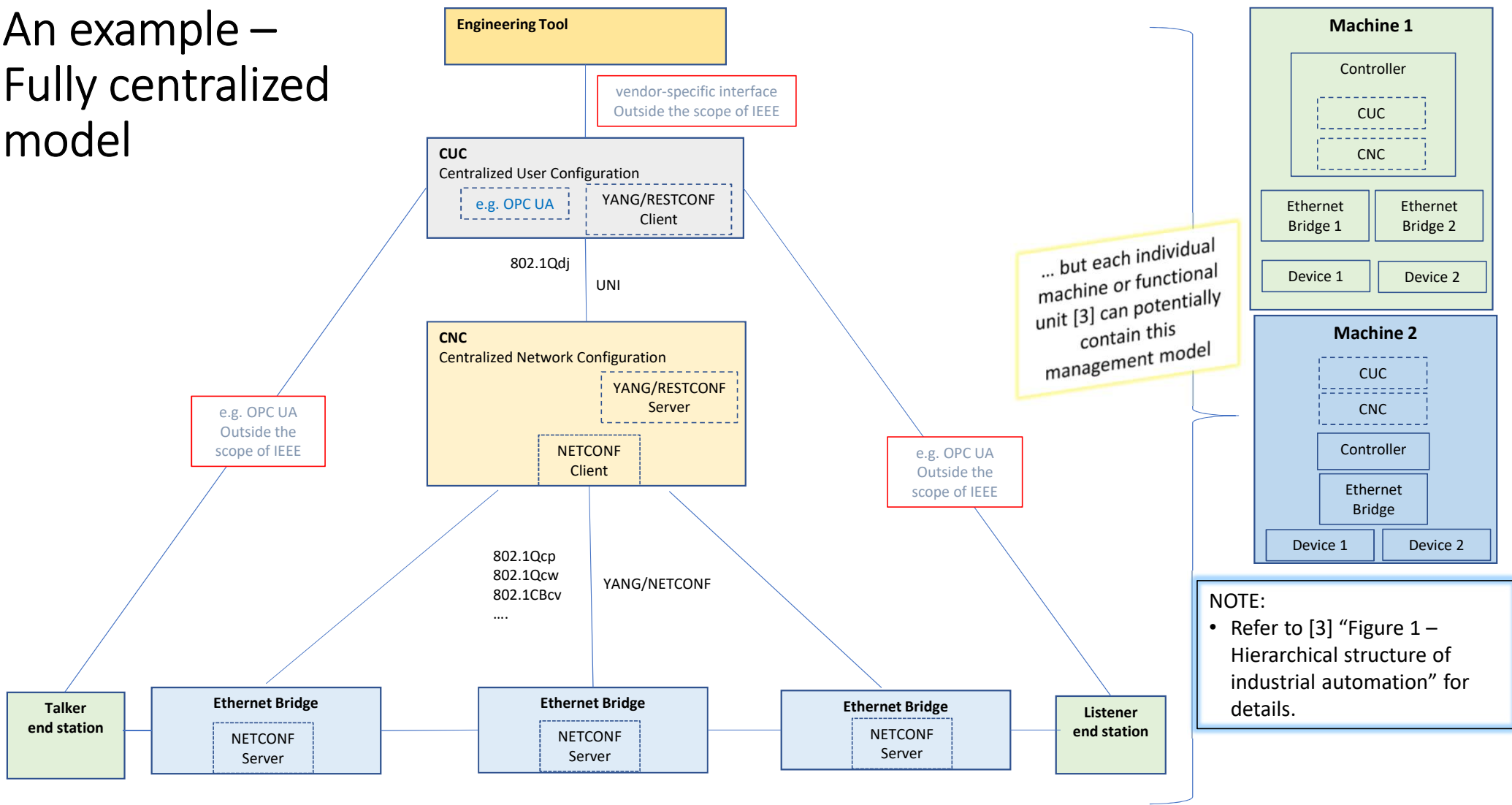
Summary (v2)

- Incorporated P60802 working group inputs and suggestions.
- [TSN Adapter domain](#) [12] and its relation to inter-TSN domains communication.

Step 3 (Other Applications):

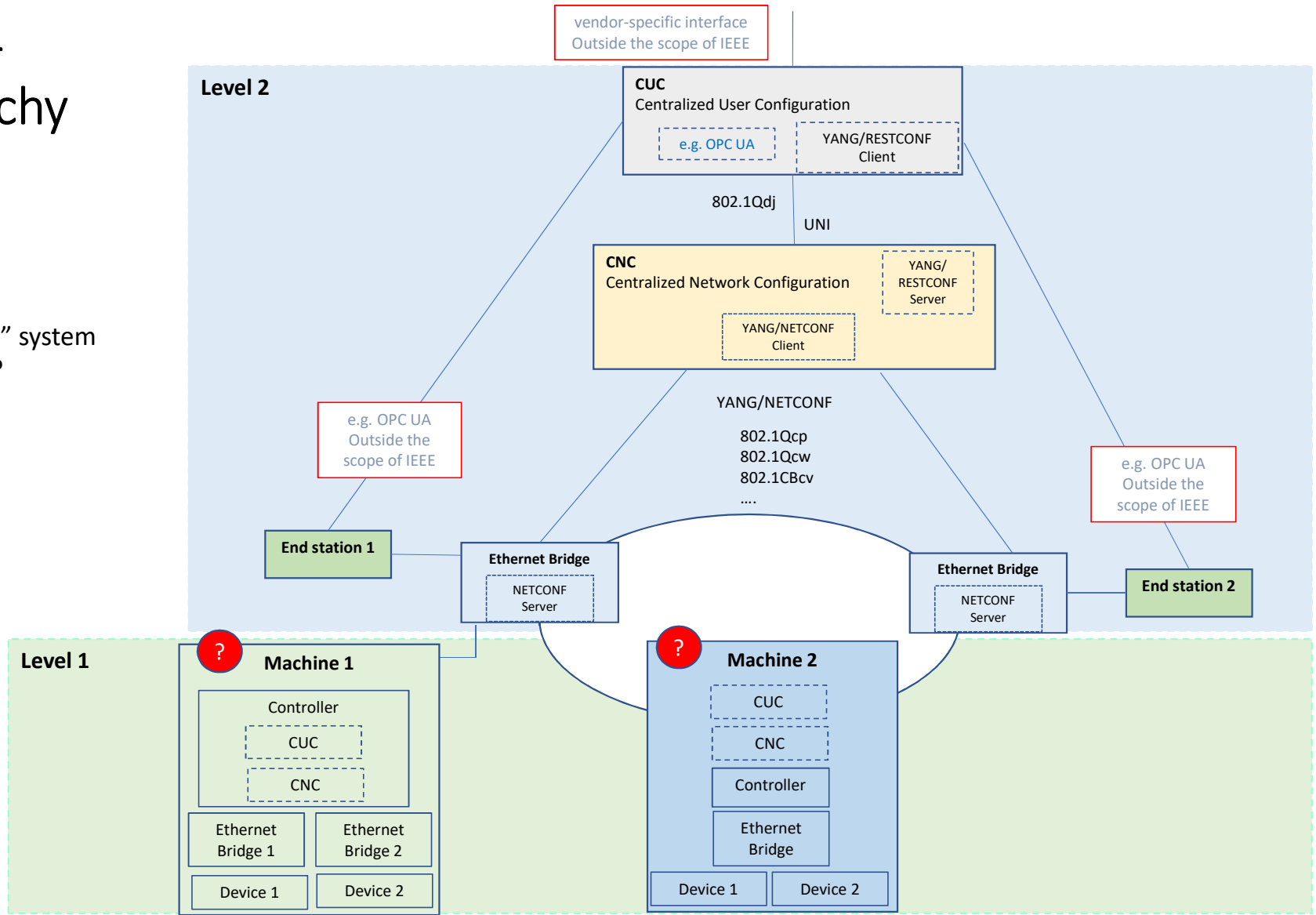
- How the end-station and the bridged-end-station system concepts can help us to deal with the concerns like:
 - TSN domain vs gPTP domain.
 - Composing inter-TSN domains communication.
 - TSN domains and configuration models.

An example – Fully centralized model



An example – 2-level hierarchy

Q. How to model “Level 1” system with respect to “Level 2”?



Generalized view – N-level hierarchy

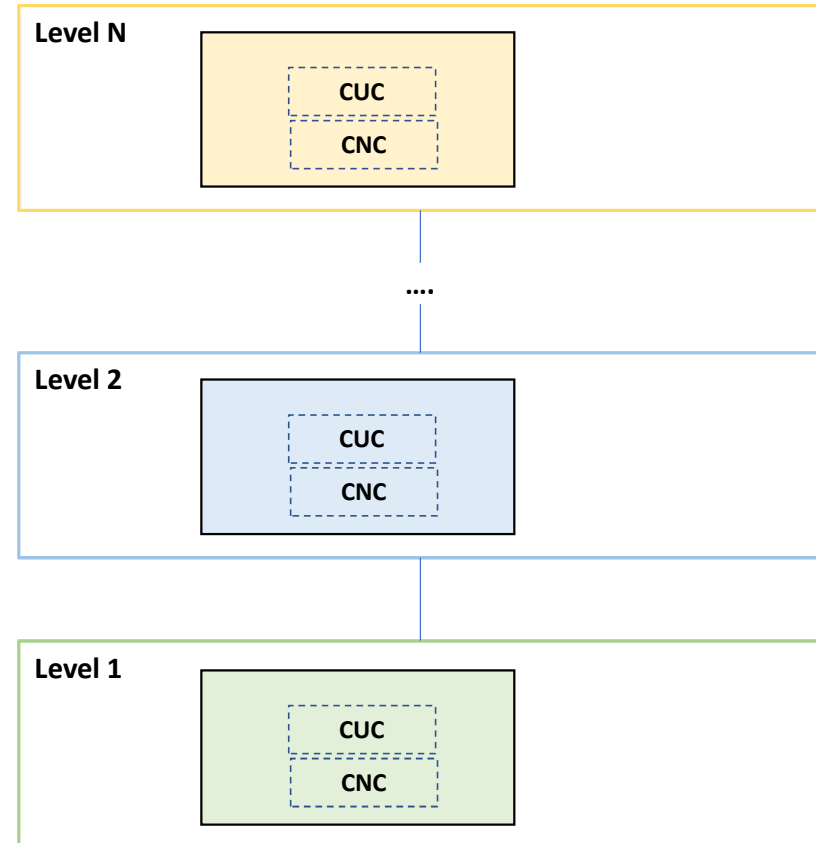
Problem:

- CUC/CNC
 - scope,
 - network view,
 - capabilities,
 - policies may varies between levels....

Aim:

- N-level system hierarchy is aiming for consistency and 1st level of interoperability (refer to [3] – Figure 3) in configuration and monitoring planes.
- Boundaries are logical in nature.
- Separation of concerns at each level.

Q. How to model “Level K-1” system with respect to “Level K”?

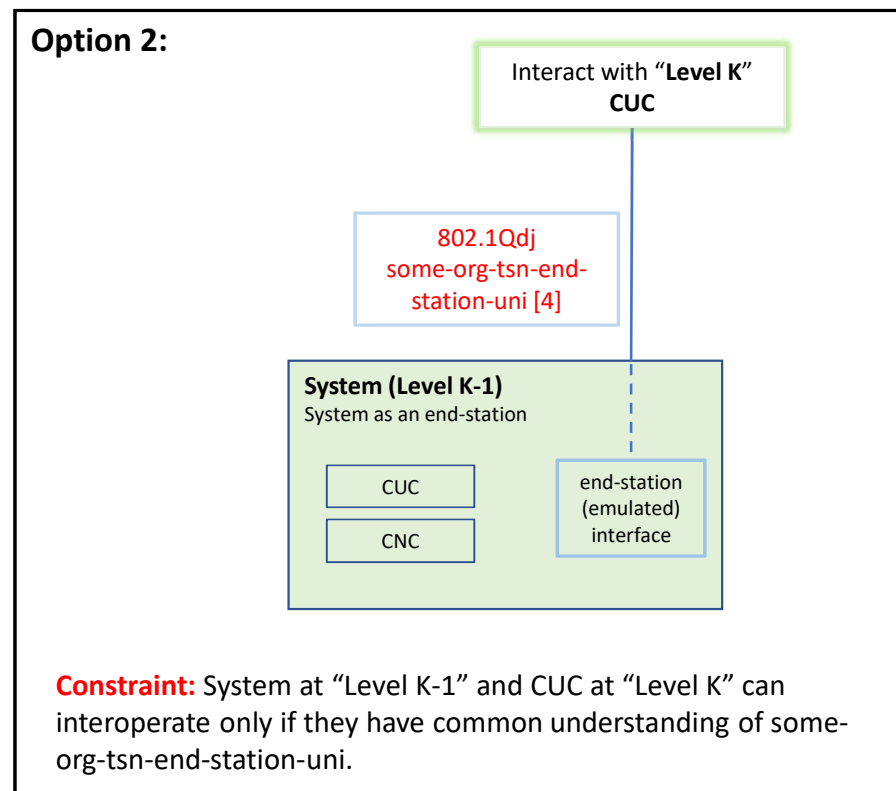
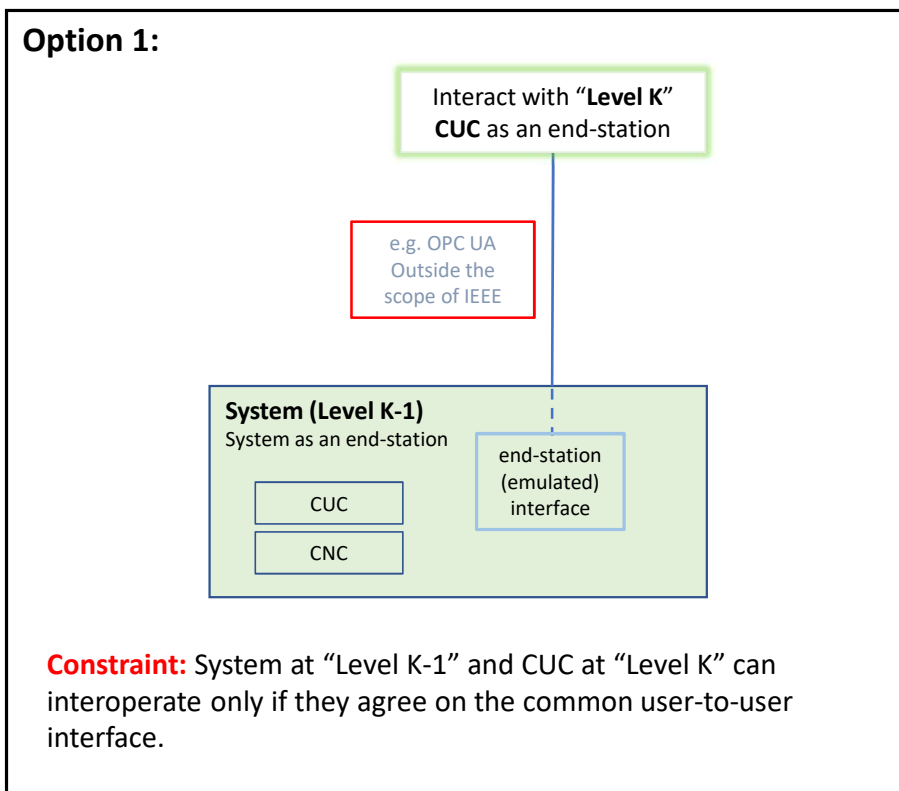


How to model “Level K-1” system
with respect to “Level K”?

- Depending on the system personality resides at “Level K-1”.
System can be model as
 - An end-station [8] or
 - A bridged-end-station.

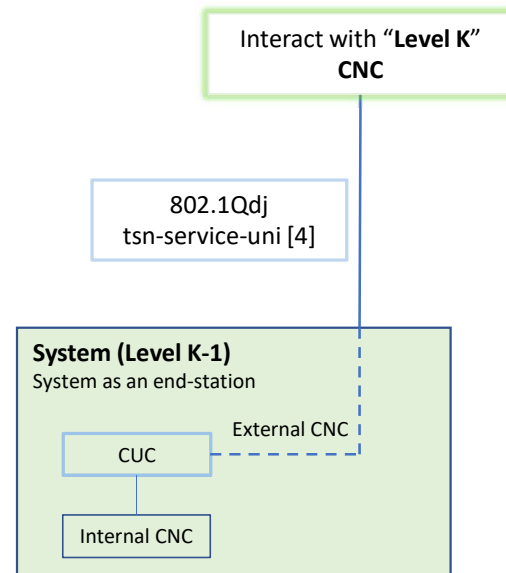
System as an end-station (1)

- System acts as a single monolithic entity.
- Options:
 - Model as an end-station with respect to “Level K” CUC (option 1 and 2).
 - Model as “Level K-1” CUC with respect to “Level K” CNC (option 3).



System as an end-station (2)

Option 3:

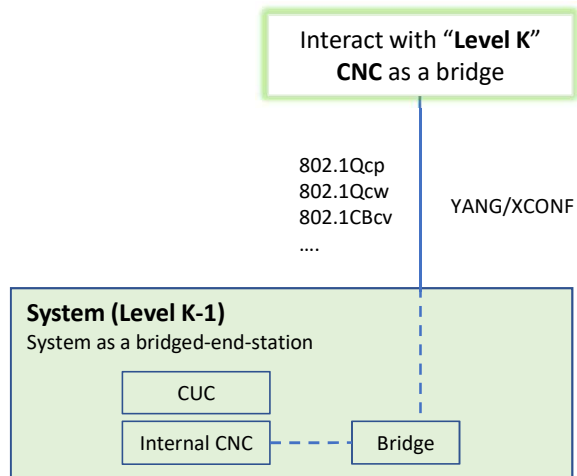


- "Level K-1" CUC differentiate between internal and external CNC.
- Assumptions:**
- CNC at "Level K" is capable of accepting requests from multiple CUC and resolve aspects like resource conflicts accordingly.
 - 802.1Qdj working group will take care of YANG model - tsn-service-uni.

System as a bridged-end-station (1)

- System acts as a single monolithic entity with respect to internal details but acts as a Bridge for pass-through traffic.
- Options for end-station entity:
 - List of “system as an end-station” plus [ieee802-dot1q-tsn-end-station-uni](#) [4].
- Options for Bridge entity:
 - System expose Bridge(s) directly via YANG/XCONF (option 1 and 2)
 - Constrained based exposure (option 3 and 4).

Option 1 (single Bridge):

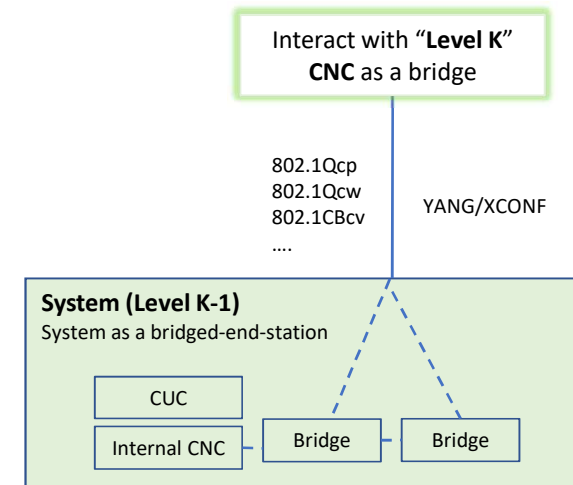


- Superimposed end-station models from the “system as an end-station” + [ieee802-dot1q-tsn-end-station-uni](#) to get the complete picture.

Constraints:

- Direct access to Bridge management interface may not be feasible.
- Bridge personality is control via internal and external CNC which may trigger such as resource ownership issues, conflicting configuration requirements ...
- External CNC may invalidate certain assumption(s) made internally.

Option 2 (Multiple Bridges):



- Same as Option 1 (Single Bridge)

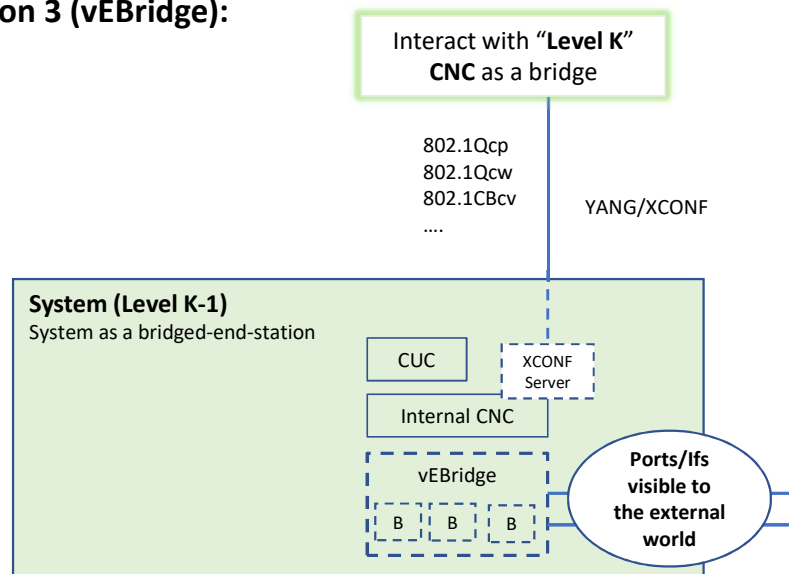
Additional constraint:

- Invalidate bridged-end-station abstraction due to the exposure of multiple internal bridges.

System as a bridged-end-station (2)

vEBridge → virtual External Bridge

Option 3 (vEBridge):



- Superimposed end-station models from the “system as an end-station” + ieee802-dot1q-tsn-end-station-uni to get the complete picture.

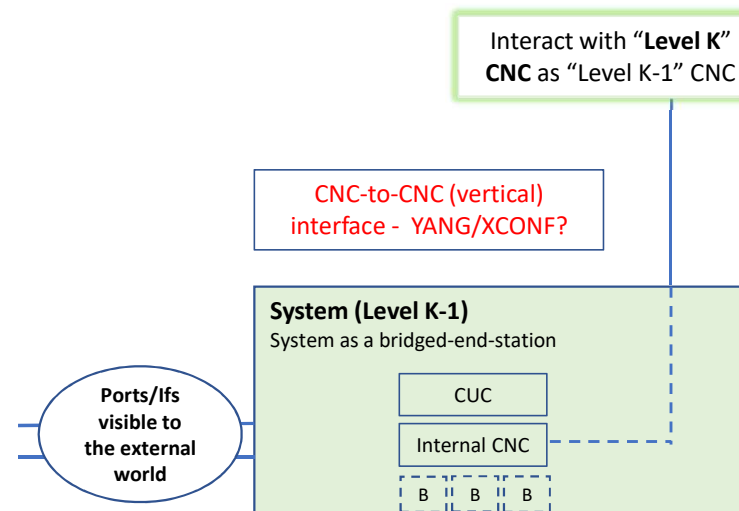
Assumption:

- Controlled Bridge(s) visibility via the concept of vEBridge.
- Internal CNC should implement the concept of vEBridge to avoid ownership issues.

Constraints:

- System internally manage the composition of vEBridge.
- Concept of vEBridge?
- YANG model for vEBridge?

Option 4 (CNC-to-CNC):



- Superimposed end-station models from the “system as an end-station” + ieee802-dot1q-tsn-end-station-uni to get the complete picture.

Assumption:

- Internal CNC control the visibility of internal infrastructure via YANG model.

Constraints:

- CNC-to-CNC (vertical) interface [6] – YANG model/XCONF but also satisfy the above assumption.

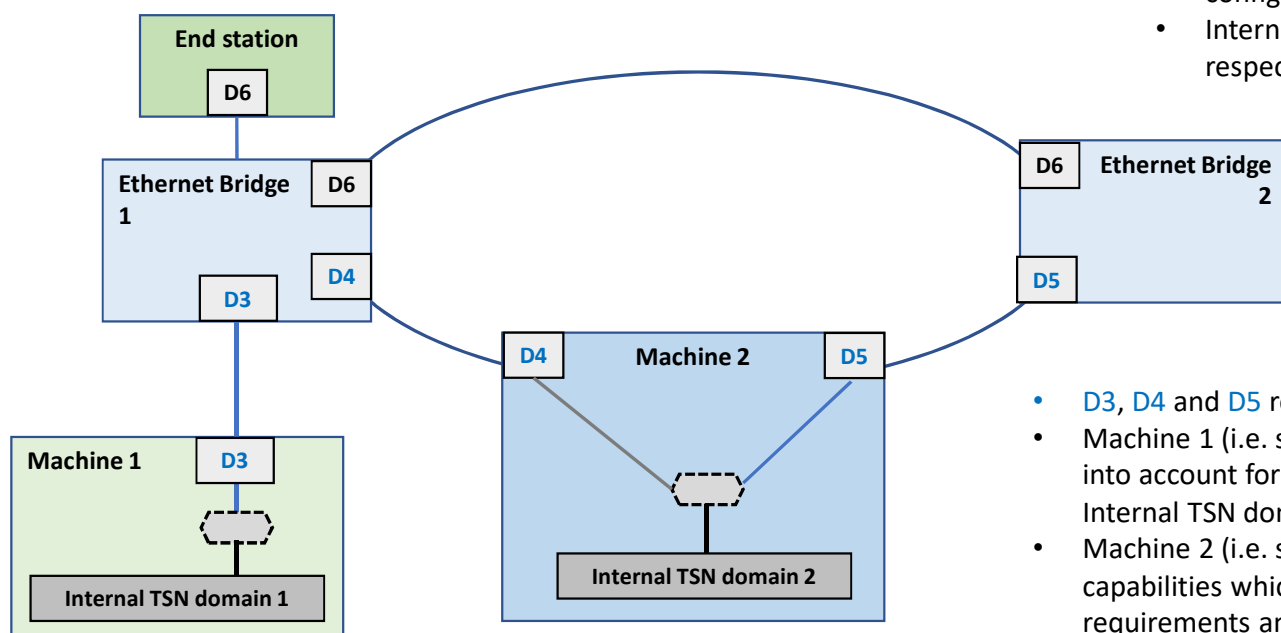
Q. There is any existing IEEE standard which address the concept of vEBridge.

Q. There is any on-going work on defining an vertical interface between “Level K CNC” and “Level K-1 CNC” with controlled visibility of internal resources.

TSN Adapter Domain

- TSN Adapter domain [12] is point-to-point in nature (logically).
- TSN Adapter domain basic purpose is to facilitate inter-TSN domains communication.
- It provides a tool to encapsulation an internal TSN domain(s) and concisely presents the interworking capabilities.

- Enhanced system composability (i.e. separation of concern per domain).
- It is possible to assign multiple TSN Adapter domains on a single physical point-to-point link as long as this link satisfy the individual TSN Adapter domain requirement(s).
- TSN Adapter domain re-emphasize the role of policy driven configuration [16].
- Internal (private) TSN domain(s) are black boxes [10] [15] with respect to the outside world.

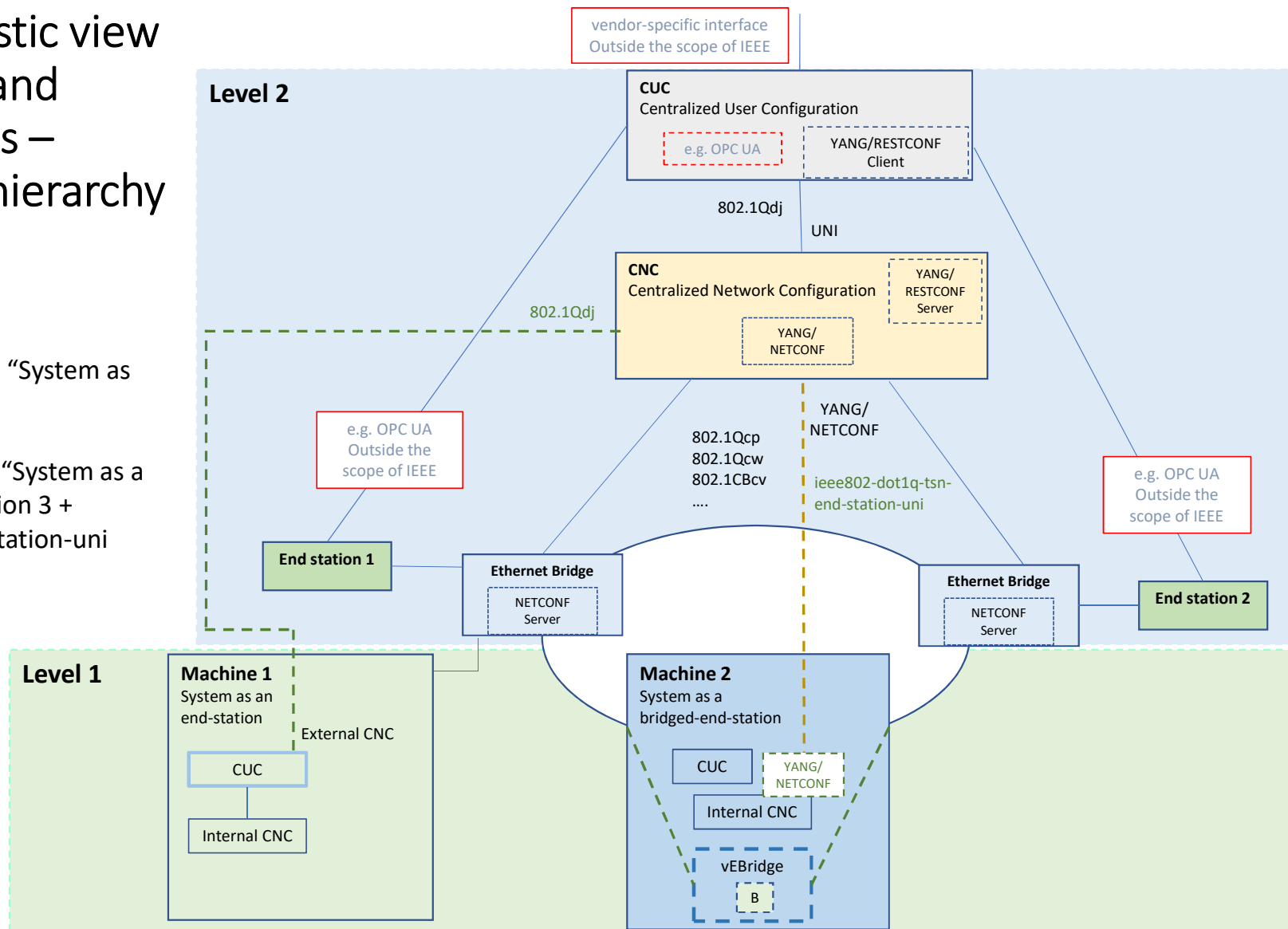


- D3, D4 and D5 represents TSN Adapter domains.
- Machine 1 (i.e. system as an end-station) advertise D3 capabilities which take into account for example, the application requirements and the constraints of Internal TSN domain 1.
- Machine 2 (i.e. system as an bridged-end-station) advertise D4 & D5 capabilities which take into account for example, the application requirements and the constraints of Internal TSN domain 2.
- It should be possible in a system to merge TSN Adapter domains. For example, D4, D5 and D6 are mergeable, if their requirements and capabilities are compatible.

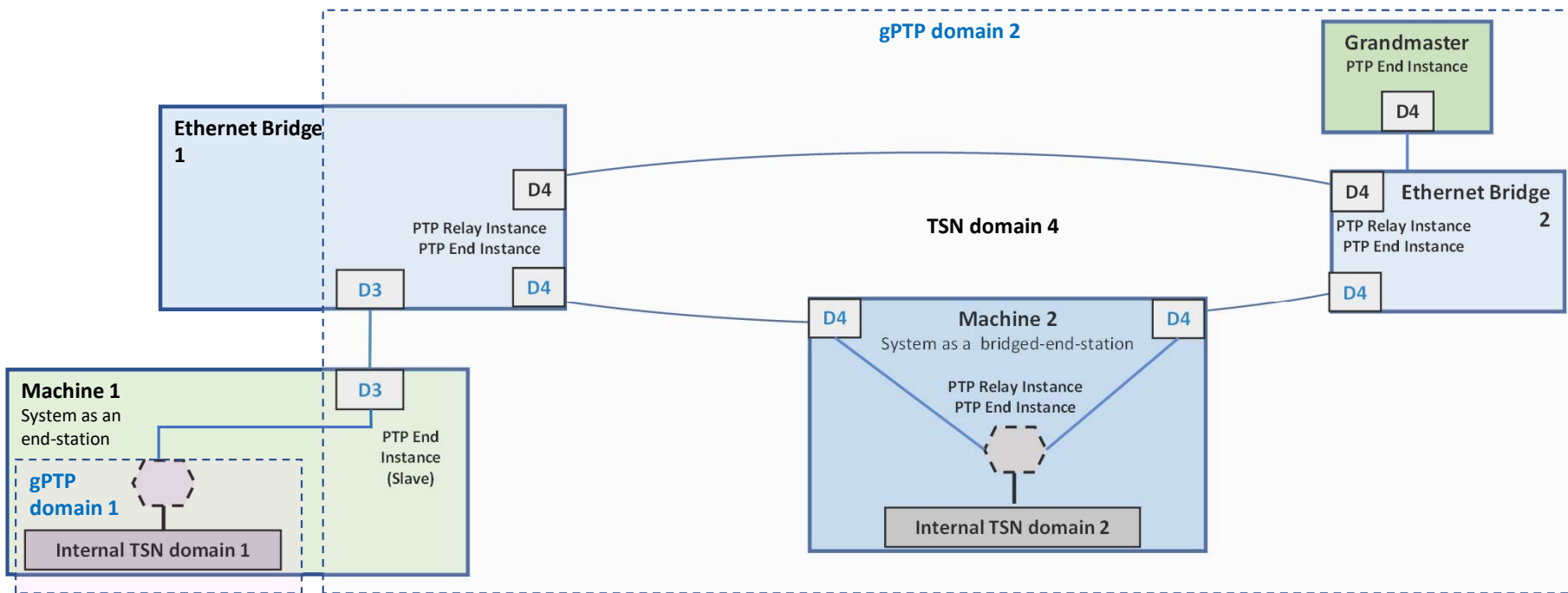
Application examples

An example: Holistic view of configuration and monitoring planes – Updated 2-level hierarchy

- Machine 1 is modelled as “System as an end-station” option 3.
- Machine 2 is modeled as “System as a bridged-end-station” option 3 + ieee802-dot1q-tsn-end-station-uni

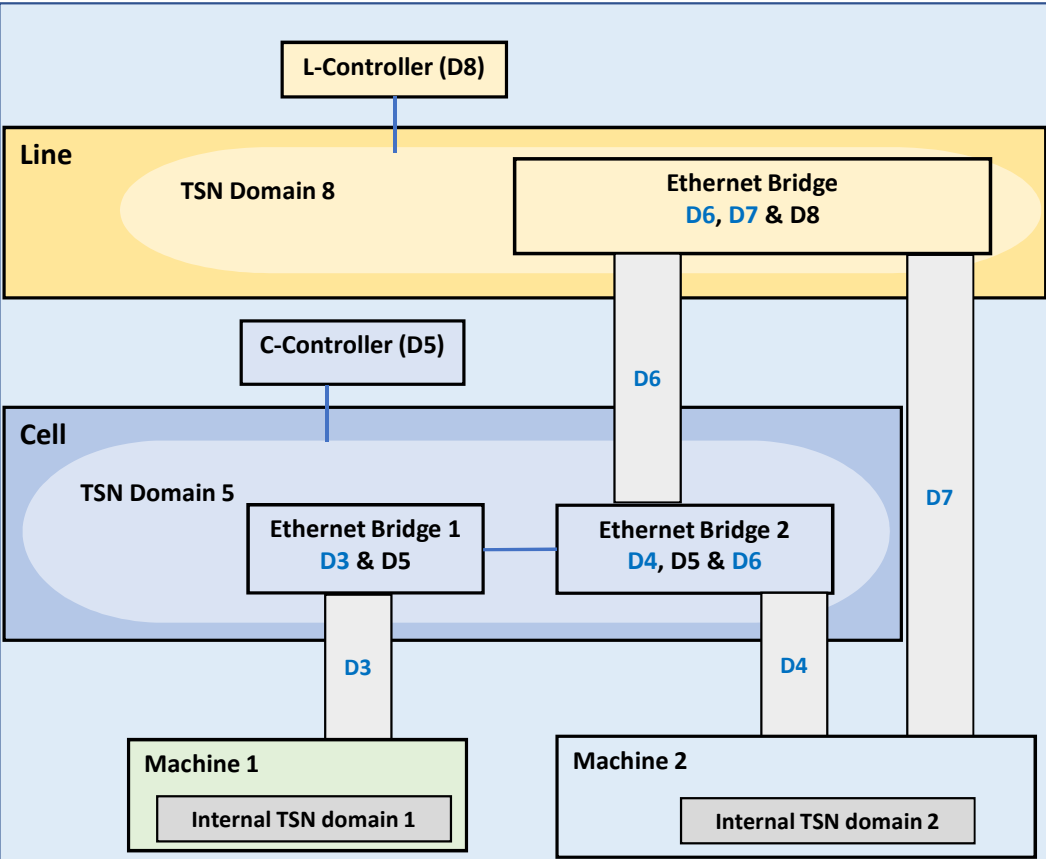


An example – TSN domain vs gPTP domain

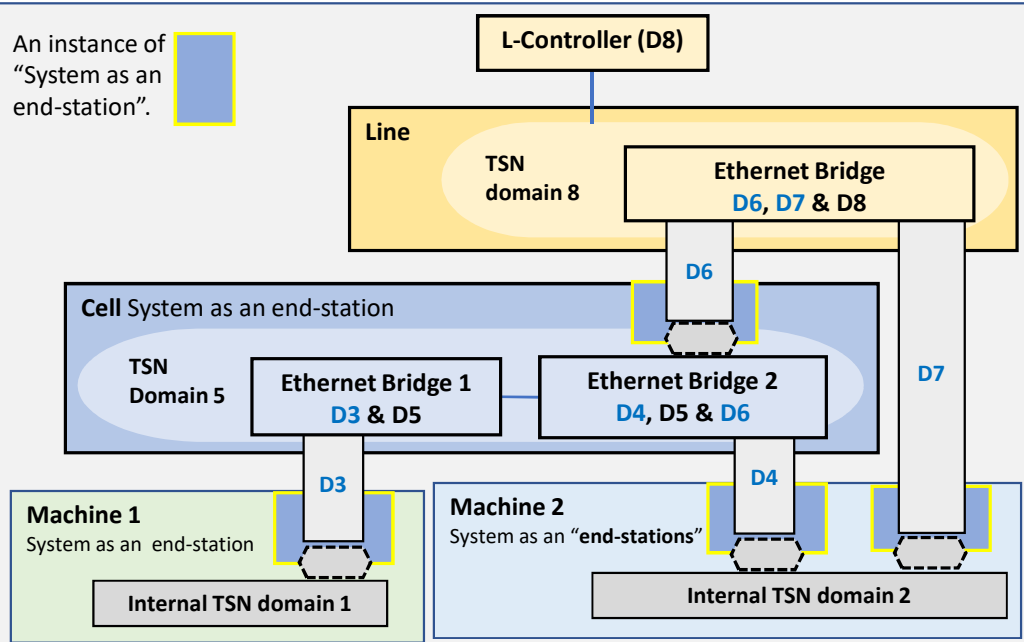


- The extent of a gPTP domain is either greater than or equal to a TSN domain [13].
- TSN domain 2, 3 and 4 are using the timing information from gPTP domain 2.
- Externally observable behavior of “system as an end-station” or “system as bridged-end-station” running gPTP is the same as any other compliant end-station or bridged-end-station.
- Bridges will need a gPTP End Instance besides PTP Relay Instance to support features e.g. 802.1Qbv.
- Machine 2 internally relay the timing information from gPTP domain 2 to TSN domain 2 (black box).
- TSN Adapter domain (D3) is used to highlight a mismatch in requirements/capabilities which necessitate the use of dedicated gPTP domain, e.g. Machine 1 internal timing functionality is non-modifiable except external interface.

An example – Composing inter-TSN domains communication

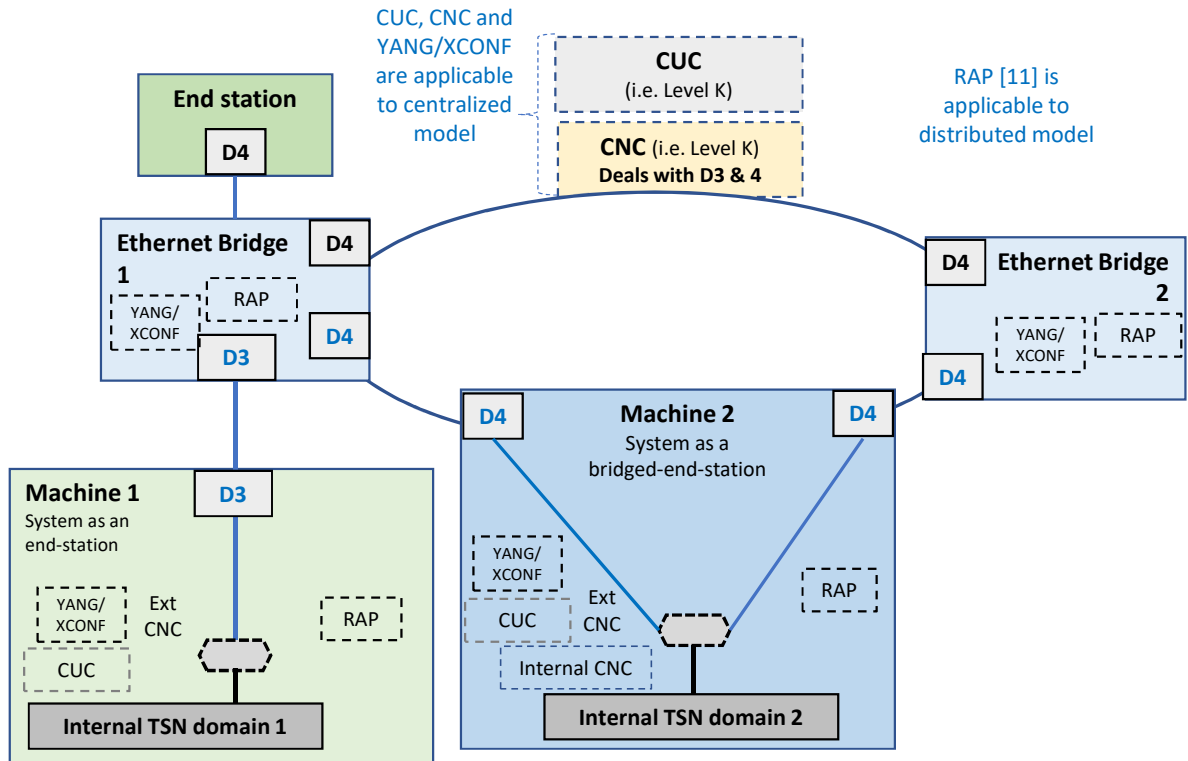


- All inter-TSN domains communication are via Adapter TSN domain(s).



- Machine 1, Machine 2 and Cell when acting as a “System as an end-station” advertise their system capabilities to higher level based on the application requirements and the constraints of Internal infrastructure.
- System will pass the first level of verification, if D3, D4, D6 and D7 satisfy the system requirements.
- Level violation (Line to Machine 2) is intentional to demonstrate different views.

An example – TSN domains and configuration models



- Internal (private) TSN domain(s) and its configuration model(s) are black boxes [10] [15] with respect to the outside world.
- The diagram assumes that
 - requirements/capabilities advertise by Machine 2 are compatible with TSN domain 4.
 - CNC at Level K can deal with multiple TSN domains (i.e. D3 and D4).
- **Centralized Model:** If higher level network (i.e. Level K) is based on fully centralized model, then the YANG/XCONF can be used to communicate end-station/bridged-end-station personality to “Level K” CUC and CNC.
- **Distributed Model:** If higher level network (i.e. Level K) is based on fully distributed model (i.e. no CUC/CNC at level K), then the protocol like RAP [11] can be used (in principle as is) to communicate end-station/bridged-end-station personality to “Level K” entities (i.e. Ethernet Bridge, end-station).

Q. RAP – streams handling in the presence of multiple TSN domains (i.e. D3 and D4)?

Conclusions

1. “System as an end-station” recommendation: Option 3.
2. “System as a bridged-end-station” recommendations: Option 4.
 - Bridge entity: CNC-to-CNC (vertical) interface.
 - End-station entity: “System as an end-station” option 3 or ieee802-dot1q-tsn-end-station-uni [4].

Gaps:

- Realization of an entity [8] [14] which presents whole system as an end-station or a bridged-end-station. Compatibility is required for externally observable behavior only.
- CNC-to-CNC (vertical) interface [6] and corresponding YANG data model **with controlled visibility of internal resources**.
- Concept of vEBridge and corresponding YANG data model.

Notes:

- P802.1Qdj [5] (**limited info - work in progress**).
- ieee802-dot1q-tsn-end-station-uni [4] (**limited info - work in progress**).
- P802.1Qdd [11] (**work in progress**).

Thank you

References

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