IEEE/IEC 60802
cTE introduction

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IEEE 802.1 TSN – IEC/IEEE 60802
13 September, 2021
Introduction

- The presentation ([Further Analysis of cTE Budgeting for an IEC/IEEE 60802 Network, Based on Multiple Replication dTE simulations with Variable Inter-message Intervals](#)) provided some consideration about time error budget allocation, including dTE (dynamic Time Error) and cTE (constant Time Error).

- The definition of cTE and dTE are specified in ITU-T G.8260
  - cTE: the constant component of the time error sequence, could be averaged with the time error sequence
  - dTE: the dynamic component (random noise) of the time error sequence, could be expressed by the peak-to-peak, MTIE or TDEV of the time error sequence.
Introduction

• This slide gives a simpler explanation on how to get cTE and dTE.

Step 1: Get the time error sequence, e.g., \( t_2 - t_1 - \text{meanLinkDelay} \)

Step 2: Estimate dTE (e.g., peak-to-peak) and cTE (averaging).
Factors of cTE

- The cTE could be caused by fiber asymmetry, or PTP devices.
- For PTP devices, the factors include the asymmetry of timestamp generation, internal delay compensation or others.

1: PHY needs to report its RX and TX delay to the MAC layer, and the delays or the asymmetry should be compensated to generate the timestamps at the MAC layer

2: The delay from the local clock to the timestamping clock at MAC layer should be measured and compensated.

However, even after compensation, some error could still be present, and a fully ideal compensation is not practical.
Several possible implementations

Case 1: M and S are from one chip

Case 2: M and S are from one card, but different chips.

Case 3: M and S are from different cards.

➢ cTE should be smaller for case 1, case 2, and case 3 respectively.
Summary

• The cTE specification of PTP relay and PTP end station should be carefully considered.

• A cTE value less than 5ns could be achievable for case 1, i.e.; Slave and Master ports are from one chip.
Thank you