

**M2M-Interaction in a production line –
How to combine different things**

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- Refer to <https://www.ieee802.org/1/files/public/docs2018/60802-essler-additional-use-case-0718-v01.pdf> for general requirements discussed here
- This presentation points out a specific example
... and how do deal with different communication subsystems

A photograph of a car body shop production unit. The scene is filled with numerous orange robotic arms, likely KUKA models, positioned around a car chassis. The robots are in various stages of assembly, with some holding parts. The car body is white and is mounted on a conveyor system. The background shows a large industrial facility with high ceilings and bright lighting.

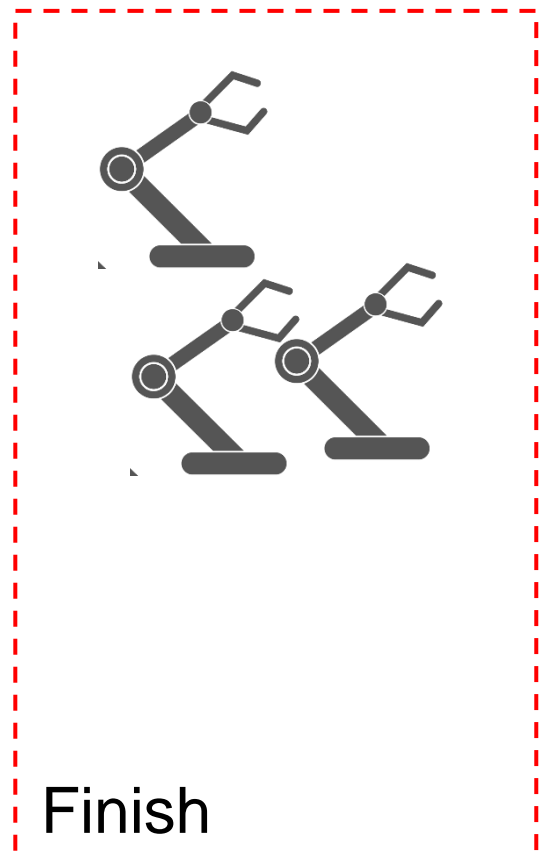
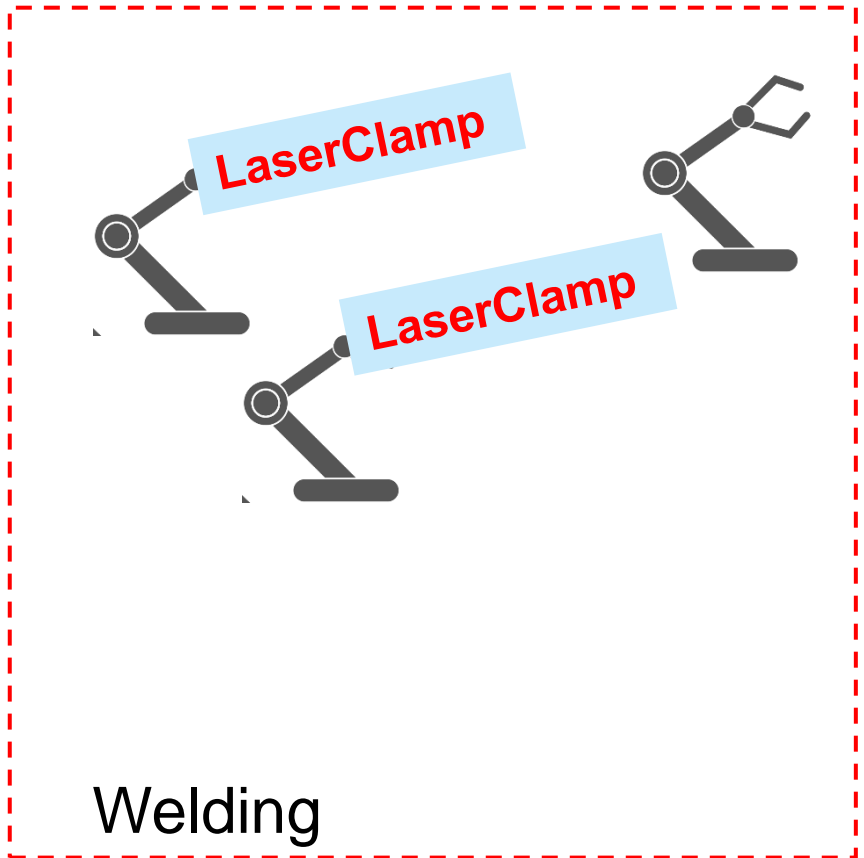
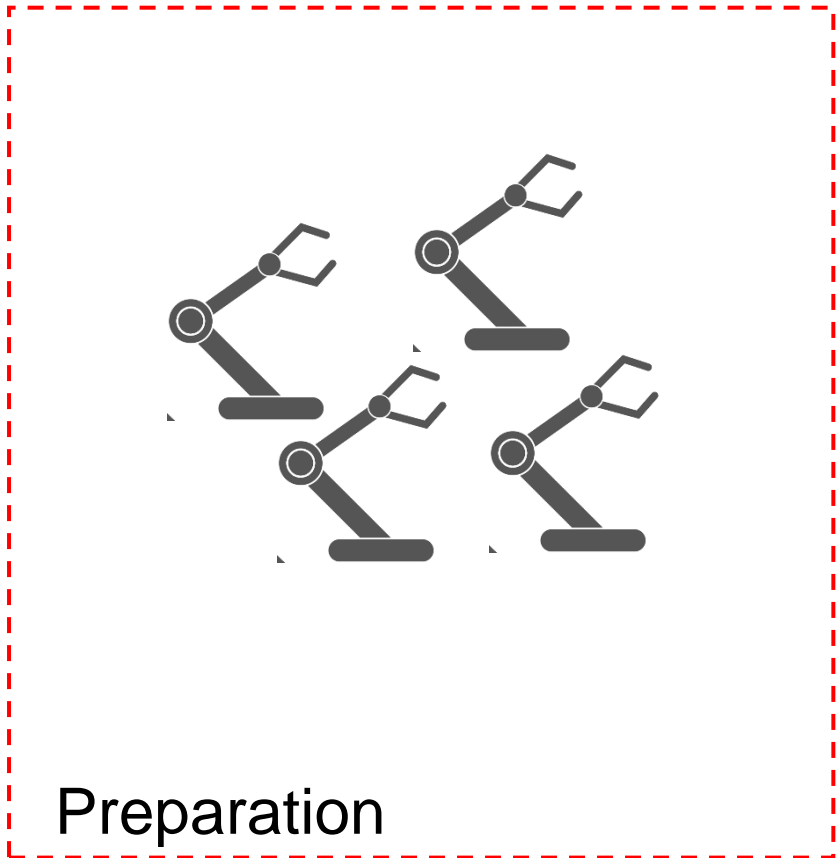
Car Body Shop production unit

- 25+ Robots and welding,...
- 10+ Machines (Transportation, ...)
- Cycle time 4..10 ms
- 250 .. 500 steps needed manufacture specific parts e.g. a door
- Elements in that unit
 - Robots
 - Welding clamps, control units
 - Other tools for glueing, clamping etc.
 - Feed in elements
 - Safety related units(Automation in production reduces fatal situations significantly)

- Synchronous cell communication is a great TSN enhancement **BUT requires coordination with machine internal actions!**
- **Machine ecosystem is organized in a different way depending on the machine type**
- **It is difficult to get a complete picture of what is going on in such a system**
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Logical production unit layout (example door production)

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Feed In



Begin with sequence of actions with time constraints

+Coordination between robots

= determination if the setup can fulfill the production rate requirements

Resiliency estimation needed to know the impact of errors

A communication interaction profile is one result

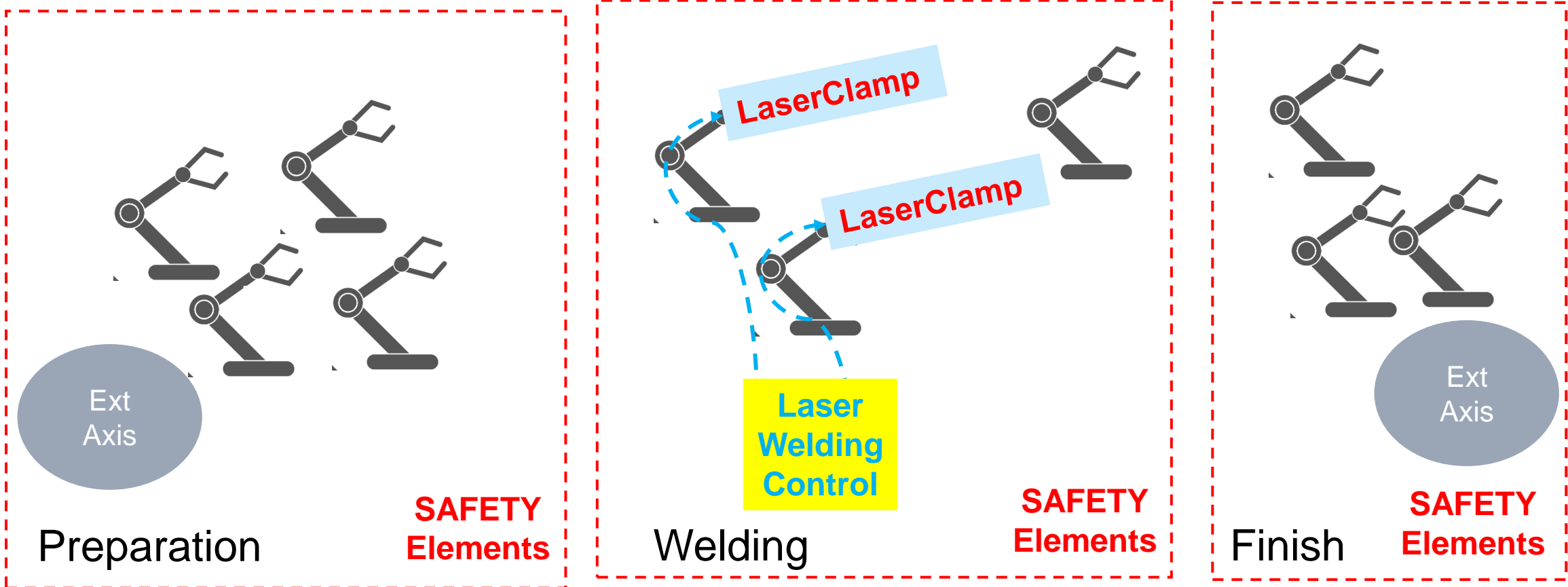
→ A calculus required that operates without detailed communication information.

Cycle time, Talker, Listener, and amount of Data are the given parameters.

- LNI 4.0 defines a general network outline with number of hops as additional parameter.

The more complete picture

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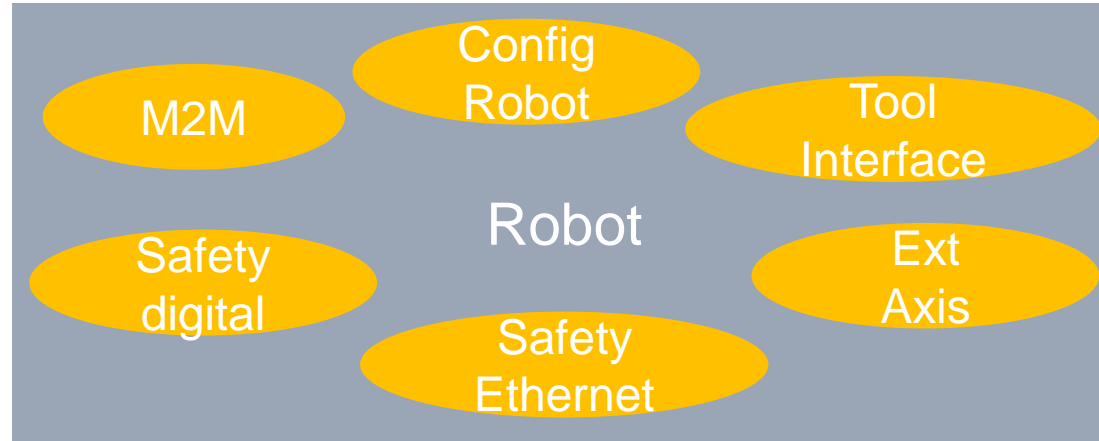


Feed In

Condition Monitoring / Power Control / Vision ...



- **The different aspects need different experts**
- Coordination is done as required
- Quite a few different communication Interfaces from a single robot



- It is not trivial to overcome proven structures
But the integration of heterogenous applications shall be with TSN

- Definition of a common platform for various application
- Model and calculus needed in the early stage
important to work with an (incomplete) offline data model
- The adjustment of the real setup can be made with a dedicated protocol
- LNI4.0 is an approach which may be combined with other elements