On ATS

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Introduction

Simple questions

- What is the best TSN shaper?
- Is ATS or TAS better for me?

Giving Answers is tough

- What is your topology, in detail?
- What is *all* your traffic, in detail? Path, pattern, quantitative and qualitative requirements of every stream!
- How much planning and/or computation is ok?
- Do end station applications like the network timing?
- What is your Bridge failure model? They never fail, fail-silent only, or in a malicious manner?

This Session

...

- Encourage discussion
 - Discussion ATS and other "TSN Shapers"
 - Discussion of aerospace use-cases
- \rightarrow Please just ask questions, interrupt me/add yourself to the queue, etc.

This Slide Set

- Put ATS in context
- Properties of ATS/first thoughts on aerospace traffic
- ATS Math
- Explicit Pointers/References

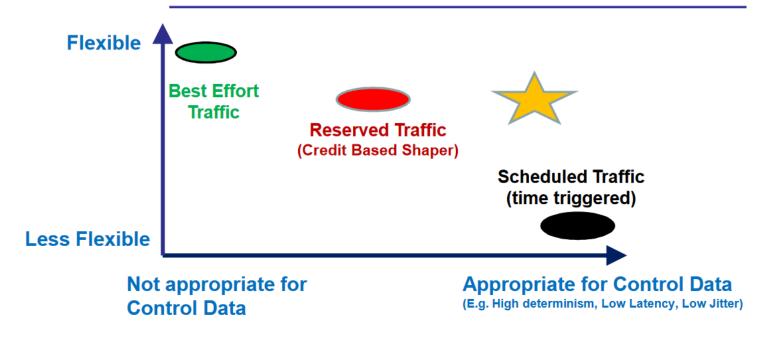
 (in addition, look for "specht", "ubs", "ats" in https://www.ieee802.org/1/files/public/docs2013 through https://www.ieee802.org/1/files/public/docs2013

...

ATS Context

Background & Motivation: UBS -> ATS

Flexible Control Traffic Class



- IEEE 802.1 TSN is currently working on proposals for additional traffic types with the desired properties: Flexible AND Appropriate for Control Data
- > AAA_2C input on requirements / desired properties.



The Standardized "TSN Shapers" → No "one size fits all"

- Different shapers are optimized for different grass in a multi-dimensional problem space
- Performance Requirem Found in many, maybe all ts, Network Layout, etc.

Shaper Std. and usage	B "TSN Swite	<mark>ches"</mark> nds	Jitter Bounds	Global Clock Sync. Dependency	Configuration Complexity	Protection & Isolation Per-stream filtering and policing (802.1Qci- 2017)
Credit-based Shaper (CBS) IEEE Std 802.1BA-2011/AVB w. MSRP	High	High	Loose	No	Low, Dynamic	Loose
Time-Aware Shaper (TAS) IEEE Std 802.1Qbv-2016 /TDM & Zero Interference/Sync. Apps		Ultra Low ported, and PSFF		Yes	High, Static	Tight
Cyclic Queuing and Forwarding (CQF) IEEE Std 802.1Qch-2016		plemented, CQF pported.	is _{ight}	Yes	Low, Dynamic	Loose
Asynchronous Traffic Shaping (ATS) IEEE Std 802.1Qcr-2020	High Focus of	Medium this slide set	Loose	No	Low, Dynamic	Tight
Strict Priority (SP) IEEE Std 802.1Q, static usage	Medium Always	Medium	Loose	No	High, Static	Loose
Strict Priority (SP) IEEE Std 802.1Q, with a priori bounds	present	Medium	Loose	No	Medium, Dynamic	Loose

Results of abstraction, individual experiences, systems/use-cases in mind, etc.:

Ask N people for the important columns, get N sets. Ask M people to insert values, get M different tables.

Upfront, first thoughts: ATS for Aerospace Traffic? Traffic Types Documentation

Both supported	Characteristic	Description			
		Traffic types comprise data streams that can either be			
Irrelevant/per stream	Deriodicity	Periodic: transmitted in a cyclic/periodic (e.g. signal transmission) or			
	Periodicity	Aperiodic: transmitted in a acyclic/sporadic (e.g. event-driven) manner Period denotes the planned data transmission interval (often also called "cycle") at the application layer.			
abstraction		#: Specify period for cyclic traffic			
NO => No significant	Typical Period	N/A: for aperiod/acyclic traffic			
NO -> NO Significant	Application Synchronized to Network	Is the application producing traffic type synchronized to the network time at the application layer? YES or NO			
delay penalty		Packet(s) are delivered to all receivers:			
		 Deadline: before a specified time, relative to cycle time. (applies to periodic data) 			
End station perception		- Latency: within a predictable timespan from the start of the transmission			
		- Bandwidth: if bandwidth utilization is within in the resources reserved by the sender			
Supported	Data Delivery Guarantee Mode	None: no special delivery requirements			
Delivery Guarantee Valu		 #: Typical quantification of the data delivery guarantee for 80% of the use cases If "deadline" mode is used, specify if the data will be delivered in the same period or not 			
Course and a d	Delivery Guarantee value	and the standard standards and the second standards and standards the			
Supported		yes: application can tolerate jitter as specified (always yes for a certain amount of latency variation of a certain am			
	Application Tolerant to Jitter	no: highly sensitive application requires negligible jitter (https://www.ieee802.org/1/files/public/docs2020			
Numbers needed!		#: Value of acceptable jitter for periodic applications /new-specht-dampers-fti-0620-v02.pdf			
		NEG: Jitter must be negligible			
Designed for 0 loss in	Tolerable Jitter Value	N/A: if data delivery guarantee mode is "bandwidth" or "none"			
		Application's tolerance to a certain amount of consecutive packet loss			
absence of errors on path	Applications Tolerant to posket loss	Yes: app can tolerate loss due to recovery mechanism in upper layer protocols or basic redundancy			
	Applications Tolerant to packet loss	No: app cannot tolerate a single packet loss			
Supported	Tolerable packet loss Value	 #: Num of consecutive packet loss tolerable to app. 0: if application is not tolerant to packet loss 			
Supported		fixed: application payload size remain fixed			
	Application payload size variability	variable: app payload varies from one packet to packet			
Payload Value (Bytes)		#: size/range of application data (payload) to be transmitted in the Ethernet frames.			
		Criticality of this data for operation of the critical parts of the system			
		high: highly critical for the operation. (DAL A, B)			
		medium: relevant but not continuously needed for the operation (Dal C, D)			
	Data Criticality	low: not relevant for operation (DAL E)			

Source: https://www.ieee802.org/1/files/public/docs2021/dp-Jabbar-Aerospace-TrafficTypes-Summary-0521-v02.pdf

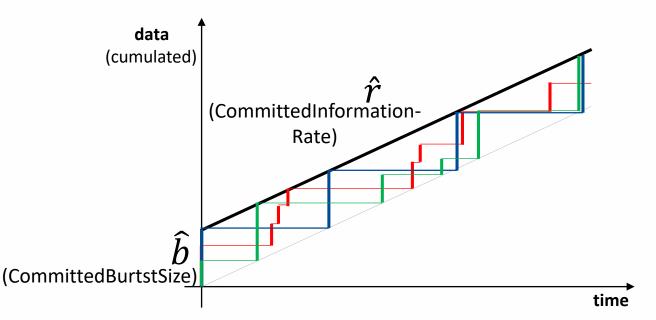
ATS Traffic Types/Streams

Token Bucket Traffic Model



Token Bucket Shaping in a Nutshell

- Buckets fills with tokens at *Flow Rate*
- Tokens consumed by Packet Length
- Delay, if not enough tokens



Traffic Types

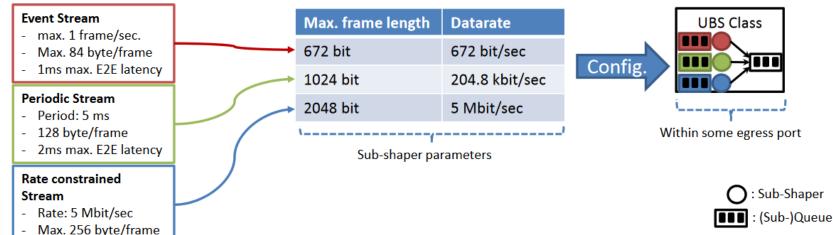
Min. Designflow

- Per stream mapping to token bucket parameters (CommittedBurstSize & CommittedInformationRate)
- 2. Delay analysis and network configuration

Aspect to *not* think too much about

- Synchronizing end station timing and network timing (which simply does not exist for ATS)
- Harmonizing periods within a converged network

Sidenote: Compared to UBS@2014, ATS "Interleaving" simplifies queuing



Automotive Control Streams

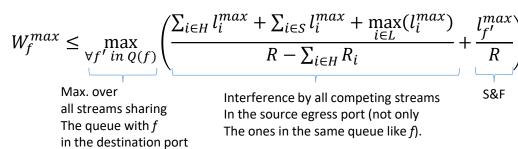
Automotive Control Streams in UBS

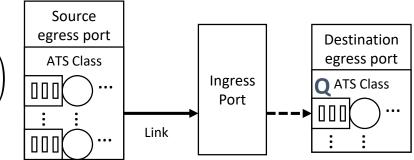
- Automotive networks need to transport control stream (cmp. [FCTC]):
 - Periodic Control Streams
 - Event-based Control Streams
- Both are supported by UBS and treated as rate constrained streams, i.e. there is no differentiation between stream types.
- Streams transferred via UBS get automotive grade E2E latency guarantees (cmp [FCTC]) even without latency-requirement-to-priority mapping (i.e. use UBS unscheduled) and at 100MBit/s link speed (cmp. [UWC])

Source: https://www.ieee802.org/1/files/public/docs2014/new-tsn-specht-ubs-automotive-1114-v01.p

ATS Latency & Configuration

Per Hop Latency Math (Simplified)





Term	Description		
W_f^{max}	Max. per hop delay of a stream f		
$\sum_{i\in H} l_i^{max}$	Sum of max. packet lengths of streams with a higher sub-priority than <i>f</i>		
$\sum_{i\in S} l_i^{max}$	Sum of max. packet lengths of streams with sub-priority equal to the sub-priority of <i>f</i>		
$\max_{i \in L} (l_i^{max})$	Maximum packet length of all streams with a lower sub-pririty than f, including lower priority traffic classes.		
l_f^{max}	Maximum packet length of streams <i>f</i> .		
R	Link speed.		
$\sum_{i\in H} R_i$	R _i Sum. of datarates of streams (i.e., CommittedBurstSize) with a higher sub- priority than f.		

Properties

- Closed expression per hop
- Sum along the path from talker to listener

Simplification

- Essential on this slide: CommittedBurstSize = Max. packet length
- Key paper:

J. Specht and S. Samii, Urgency-Based Scheduler for Time-Sensitive Switched Ethernet Networks, ECRTS 2016

• Annex V of IEEE Std 802.1Qcr-2020

Latency Bounds: Order of Magnitude

Satisfies the boundaries found in 802.1BA (AVB)

Sub Shapers – what has been shown (see also http://www.ieee802.org/1/files/public/docs2013/new-tsn-specht-ubs-perfchar-1113-v1.pdf)

Bursts can't accumulate/propagate

VS.

- Latency can be calculated for each Hop independently
- Even without sub priorities, the end-to-end latency is low:

5612.2 µs (1 CBSA Shaper) 1432.32 µs (UBS Sub Shapers)

Underlying assumptions on Streams

- Max. Rate & max. Frame Length
- no further assumptions, e.g.
 - Talker transmission behavior
 - prev. Hops/topology

Further Cases

- Readers are encouraged to analyze UBS independently and present:
 - Counterexamples, other cases
 - Analyze whether the shown math. is totally wrong or totally right
 - etc.

Latency for 1 CBSA Shaper taken from http://www.ieee802.org/1/files/public/docs2010/ba-boiger-bridge-latency-calculations.pdf

12/2/2013

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Source: https://www.ieee802.org/1/files/public/docs2013/new-tsn-specht-ubs-avb1case-1213-v01.pc

Configuration

There is a Range: How much computation/how optimized?

Y3

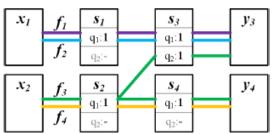
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Simple (prev. Slides)

- Trivial latency calculation and setup
- All streams in one or more *global* traffic classes (aka priority level)
- "man-made" stream-to-class association
- Simple enough for distributed dynamic reservation without overprovisioning (cmp. P802.1Qdd)

Complex

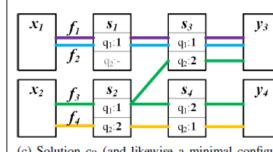
- Fine-tuning by assigning individual • per stream per hop priority levels
- Optimize for matching tough/wide-spread per stream E2E latency requirements

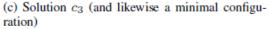


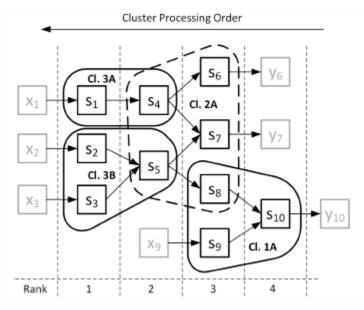
(a) Single priority level configuration c_1 (valid) violating deadline constraint CC2.

Γ	Flow	Sink	$\bar{d}\left(f,y\right)$	$\hat{d}\left(c_{i},f,y ight)$			
				$c_i = c_1$	$c_i = c_2$	$c_i = c_3$	
Γ	f_1	y_3	6.5 µs	7 μs	6 µs	6.0 µs	
	f_2	y_3	8.0 µs	7 µs	7.7 µs	6.0 µs	
	f_3	y_3	9.5 µs	7 µs	7 µs	9.0 µs	
		y_4	6.5 µs	6 µs	6 µs	5.7 µs	
	f_4	y_4	6.5 µs	6 µs	6 µs	5.7 µs	

q1:1 $q_1:1$ $q_2:2$ $q_2:1$ x_2 S_2 84 q1:1 $q_1:1$ (b) Invalid configuration c_2 (violates QC2)







Source of all figures and tables on this slide: J. Specht and S. Samii, Synthesis of Queue and Priority Assignment for Asynchronous Traffic Shaping in Switched Ethernet, RTSS 2017

ATS Robustness

Robustness, Protection and Isolation

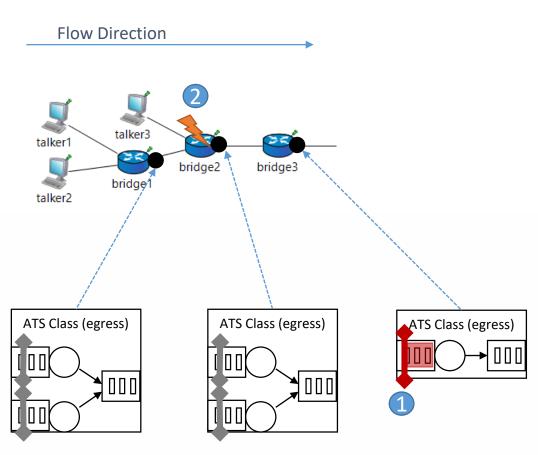
Asynchronous

- No global clock sync. dependency •
- **Policing Included** 2.
 - Token Bucket shaping
 - Delaying (shaping), not only dropping (policing) 1.
 - Re-shaping per hop: No growing disturbance/burstiness along paths 2.
 - → No need for increasing CommittedBurstSize values (avoid false-positive policing reactions)

→ Low delay impact (no need to account for traffic form interfering babbling idiots maxing out increased CommittedBurstSize limits until policing reaction)

- Possible mutual exclusion
 - Token Bucket state machines (shapers & flow meter) share similarities
 - (Re-)shaped traffic may not need extra flow meters •
 - ASIC Implementers may design for this
- **3. Traffic Isolation in (virtual) queues**
 - At least at per Port resolution
 - Mindset ٠
 - Stations can break, not only in the nice way (i.e., become babbling idiots) ٠
 - All traffic from a broken station is broken and lost (i.e., no separation in classes/streams) ٠
 - Traffic on paths without broken boxes shall not be affected by interfering broken traffic •

Separate (virtual) queuing at least on a per port resolution

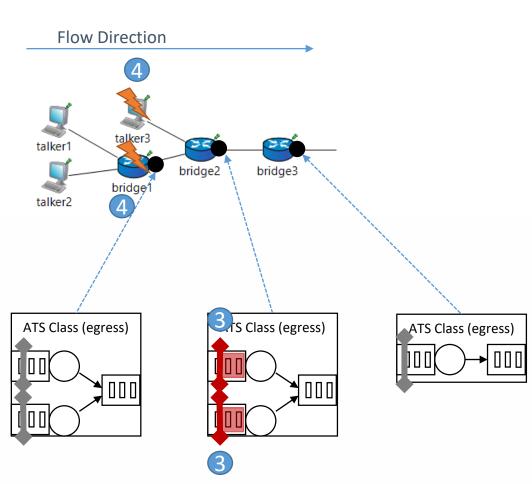


Fault isolation Logic

1.If the queue limit in *bridge3* is exceeded...

2.... only *bridge2* can be the babbling idiot.

Separate (virtual) queuing at least on a per port resolution



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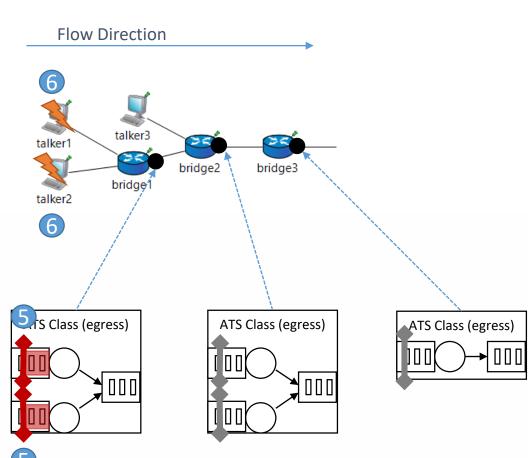
2.... only *bridge2* can be the babbling idiot.

Contradiction

3.If the queue limit in *bridge3* is exceeded and *bridge1* or *talker3* would be the babbling idiot...

4.... limits in *bridge2* would prevent the overload to propagate to *bridge3*.

Separate (virtual) queuing at least on a per port resolution



Fault isolation Logic

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Contradiction

3.If the queue limit in *bridge3* is exceeded and *bridge1* or *talker3* would be the babbling idiot...

4.... queue limits in *bridge2* would prevent the overload to propagate to *bridge3*.

... Continuing ...

5.If a queue limit in *bridge2* is exceeded, *bridge1* would be fault free and *talker1* or *talker2* would be the babbling idiot...

6.... queue limits in *bridge1* would prevent the overload to propagate to *bridge2*.

Thank you for your Attention!

Time for Questions & Answers

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