# 60802 Time Sync Ad Hoc 7<sup>th</sup> November Meeting

David McCall – Intel Corporation

Version 1

#### Agenda

- Update on Monte Carlo Simulations
- Agenda for Plenary Session Ad Hoc & 60802 Time Sync Slots

#### Monte Carlo Simulation Status Update

- Five threads...
  - Add variability of T<sub>residenceTime</sub> and T<sub>pDelayTurnaroud</sub>
    - Done see next slide for questions for the group
  - Add mNRRsmoothingA from single-hop simulation to multi-hop simulation
    - Mostly done
  - mNRR Clock Drift tracking & compensation
    - Extension of single-hop simulation
  - mRR Clock Drift tracking & compensation (mRR from accumulation of mNRR)
    - Requires change to Clock Drift modelling see slide 6
  - mRR from successive Sync messages
    - Requires same change to Clock Drift modelling

### Variability of T<sub>residenceTime</sub> and T<sub>pDelayTurnaroud</sub>

- Previously modelled as residenceTime & pDelayTurnaround, which are technically the maximum permitted interval
- Now modelled with variability factors and uniform distribution...

Parameter	Default	Unit	Notes
pDelayTurnaround	10	ms	
PDTmax	1		Each T <sub>pDelayTurnaround</sub> is between PDT <sub>max</sub> and PDT <sub>min</sub> x pDelayTurnaround
PDTmin	0.2		
residenceTime	10	ms	
RTmax	1		Each T <sub>residenceTime</sub> is between RT <sub>max</sub> and RT <sub>min</sub> x residenceTime
RTmin	0.2		

#### Variability of T<sub>pdelay2pdelay</sub> & T<sub>sync2sync</sub>

Parameter	Default	Unit	Notes
pDelayTurnaround	10	ms	
PDTmax	1		Each T <sub>pDelayTurnaround</sub> is between PDT <sub>max</sub> and PDT <sub>min</sub> x pDelayTurnaround
PDTmin	0.2		
residenceTime	10	ms	
RTmax	1		Each T <sub>residenceTime</sub> is between RT <sub>max</sub> and RT <sub>min</sub> x residenceTime
RTmin	0.2		

• Question for group: are the default limits for  $T_{residenceTime}$  and  $T_{pDelayTurnaroud}$  reasonable?

#### Tracking & Compensating for RR Clock Drift

- Similar to End Station Error, only modelled at final hop...but...looking back at previous RR values for final hop entails modelling entire chain of messages for that hop.
- Noisy signal, so requires looking further back at older messages...and same optimal combination of N & A as for mNRR measurement applies...all of which need to be modelled.
- Going further back in time means assumption that Clock Drift remains constant is...shakey.
- Same applies for mRR from Sync messages

#### Revised Model for Clock Drift

- Model for each interval, and...
- Account for sudden changes in rate of change
  - If there is a transition, then model in two parts

#### 60802 Time Sync Ad Hoc – Next Steps

#### Key:

Can progress now
Contribution required
Dependant on other items

- Messaging & Algorithms
  - Align pDelay & Sync messaging; reduce variability of  $T_{pdelay2pdelay}$  &  $T_{sync2sync}$  investigation of possible mechanism
    - Contributions requested
  - NRR & RR drift measurement & compensation Monte Carlo & Time Series simulations to determine efficacy and robustness
- Clock Filters & Control Loops
  - Continued discussion based on latest Time Series simulation results
- Sync Message Timestamping (using synced ClockSlave to timestamp)
  - Assessment (simulations?) based on results of Clock Filters & Control Loops discussion.
- Rate Ratio Measurement (best method via NRR accumulation or direct via Sync messaging)
  - Analysis of Rate Ratio measurement via Sync messaging, similar to [2]. Subsequent Monte Carlo simulation and assessment.
- Normative vs. Informative
  - **Discussion** on normative requirements for error generation
    - Possible discussion of normative requirements for error tolerance if NRR and/or RR drift measurement & compensation is adopted.
  - Everything else is informative. Some will be obvious. Others may require discussion.
- Unified Proposal
  - Dependant on progress of above subject areas.

## Backup