

Capability Models for Nodes and Dynamic Behavior of CNCs & CUCs

Rodrigo Ferreira Coelho [Siemens AG]

Agenda

1. Need for end station and bridges capabilities model
2. Behavior of CNCs and CUCs (Dynamics)

Need for End Station and Bridges Capabilities Model

Motivation

- Nodes need not to support the same capabilities, e.g. some may not support: arbitrary time aware offset, constant IPG
- Information needed to configure the network: both off-line (engineering tool) and on-line (CNC)
- Knowing the capabilities of the end stations and bridge is a pre-requirement for consistent configuration of the domain
 - How can CNC plan streams if it doesn't know what capabilities are supported/ configured for each node in the stream path?
- Available in a machine readable format

Motivation

Need

- Means to describe supported/ configured **relevant capabilities of each node** in the domain to allow for the **CNC to correctly plan streams**

Also previously addressed in <https://www.ieee802.org/1/files/public/docs2021/new-specht-dev-caps-and-limits-1121-v01.pdf>

Profiles

Capability/Limitation	IEEE 802.1 Stds References
Guaranteed maximum gate control list size	12.29.1.5 of IEEE Std 802.1Q-2018
Supported transmission selection algorithms	None
Guaranteed FDB capacity	None
Guaranteed frame buffer capacities	None
Guaranteed end station transmission performance (e.g., minimum frames sent back-to-back)	None

802.1 Profile Projects

Similar to the previous slide, with the following additions:

- Resolution is higher (e.g., different markets), which may mitigate the risk for oversizing to certain extent.
- Adding requirements for elements not standardized in a core Standard (e.g., buffer capacities) is an issue, because defining such elements is typically beyond the scope of profile projects and needs to be done in technical core Standards first.

Missing Station Capabilities for Resource Engineering, Johannes Specht

11

Unified Models

Capability/Limitation	IEEE 802.1 Stds References
Guaranteed maximum gate control list size	12.29.1.5 of IEEE Std 802.1Q-2018
Supported transmission selection algorithms	None
Guaranteed FDB capacity	None
Guaranteed frame buffer capacities	None
Guaranteed end station transmission performance (e.g., minimum frames sent back-to-back)	None

Unified Models for Device Capabilities and Resource Limits in core 802.1 Standards (e.g., IEEE Std 802.1Q)

More versatile, if available via management/YANG/MIB (CNC) and for offline engineering. However:

- Providing device capabilities and resource limitations may not always be desired. But providing these is already a requirement for certain application areas/markets, then ...
- ... finding **the right abstraction level** appears important:
 - Overpessimism/cuts in device capabilities and resource limitations can be assumed to be low in generic and detailed models, but higher complexity can be expected.
 - The opposite appears to be true for rather simple models.
 - One option is to go for generic and detailed models that allow reduction to simpler models when used.

Missing Station Capabilities for Resource Engineering, Johannes Specht

12

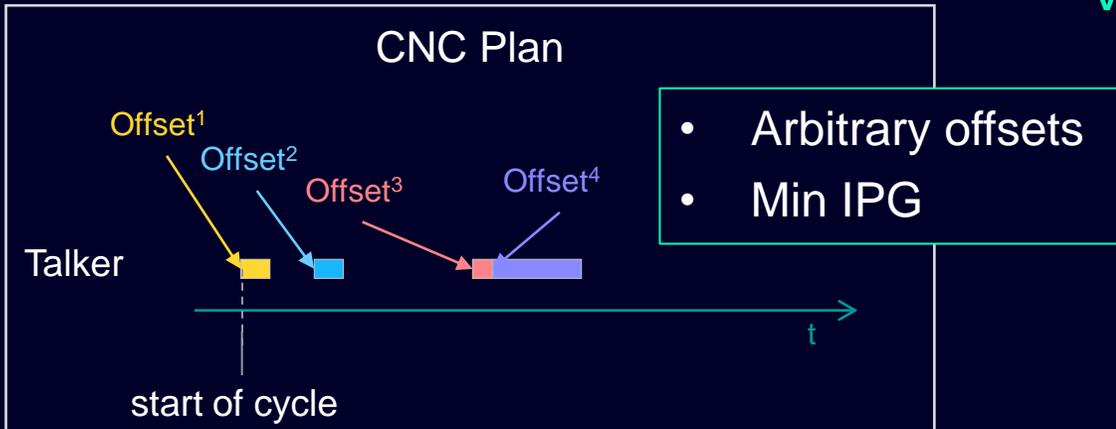
Extracted from new-specht-dev-caps-and-limits-1121-v01.pdf

Motivation

Need

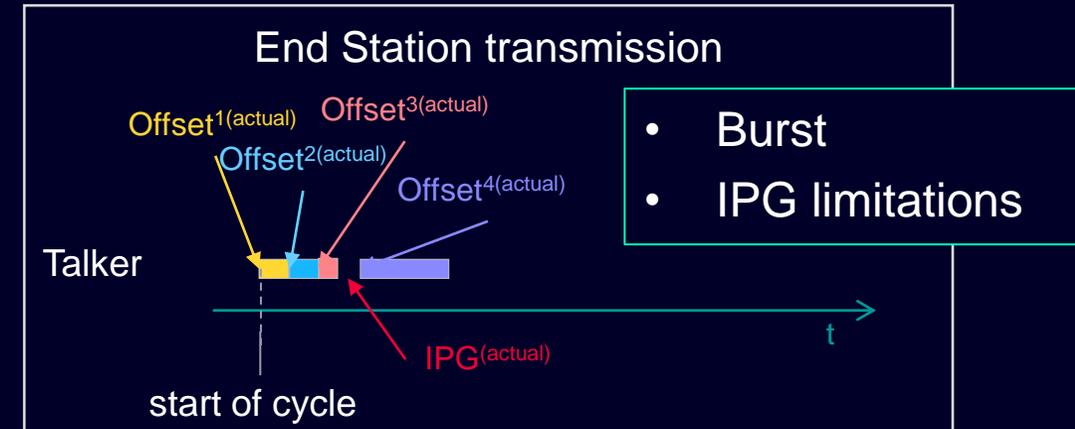
- Means to describe supported/ configured relevant capabilities of each node in the domain to allow for the CNC to correctly plan streams

CNC Assumptions



VS.

End Station Capabilities



**Actual stream behavior
completely different from planned**

Issue to be addressed

Required: Capability model for nodes

Where should they be addressed

- Qdj ?
- 60802 ?
- ...?

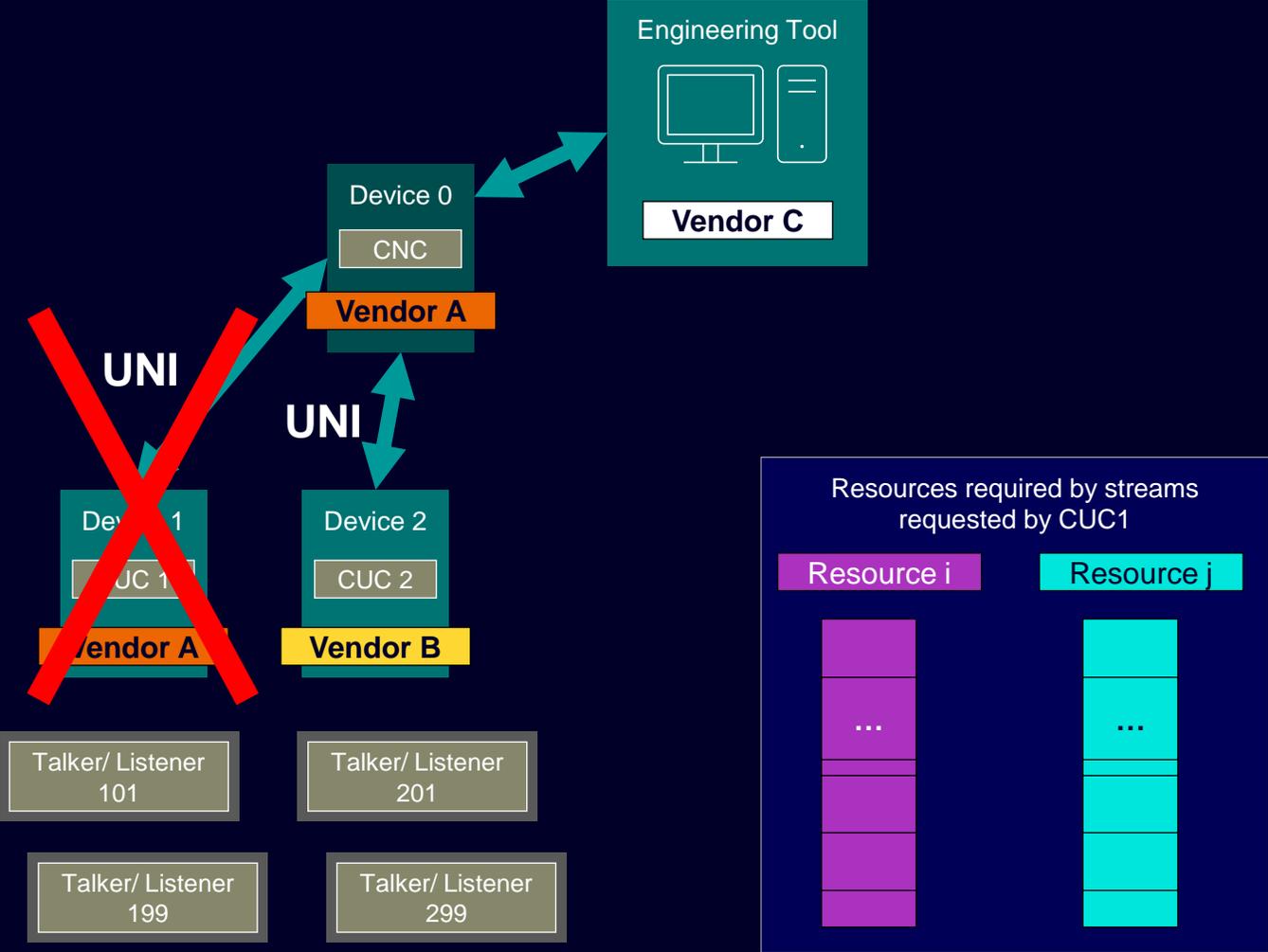
Behavior of CNCs and CUCs (Dynamics) E.g. CUC Removal

Motivation

Need for standardized behavior to ensure

- Multivendor
- Plug & Produce
- Converged network

Current Qdj: Not addressed



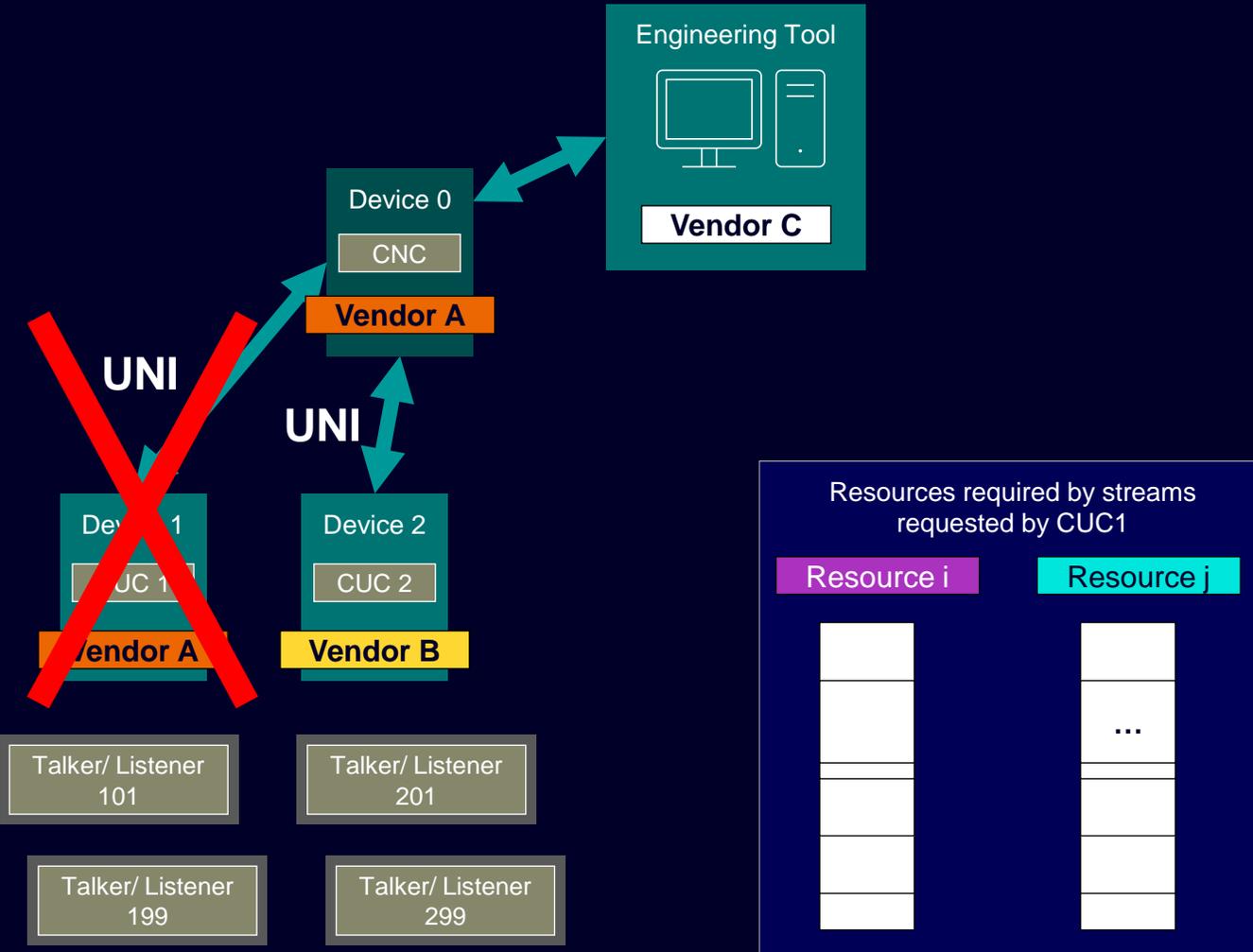
Example 1: **CNC-unaware** removal of machine controlled by CUC 1

- No signaling from CUC 1
- CNC cannot auto-detect CUC 1 removal

Consequently

- **CNC does not free resources** of requested streams
- **Zombie streams**: reservations exist, stream communication (probably) does not

Current Qdj: Not addressed



Example 2 : **CNC-aware** removal of machine controlled by CUC 1

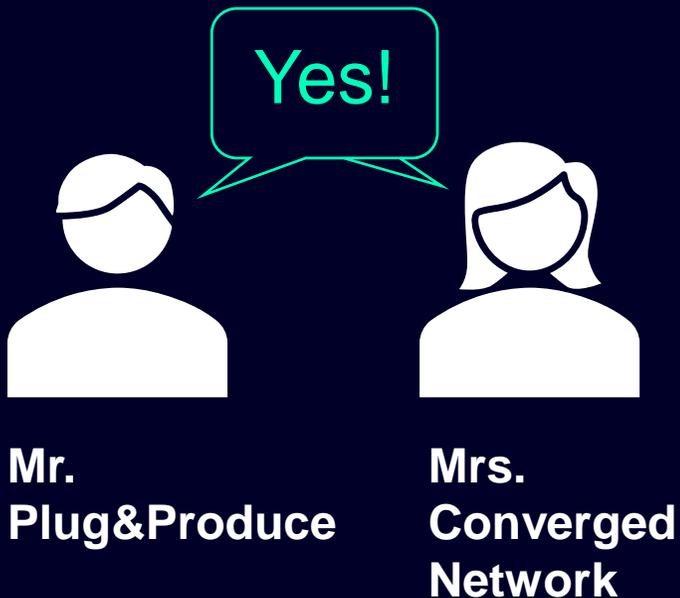
- **CUC 1 requests** CNC to free required resources, **or**
- **CNC auto-detects** CUC 1 removal

Consequently

- If so configured, **CNC frees resources**
- Streams not available anymore
- If so configured, **CNC keeps resources**
- Machine can be quickly re-inserted

Issue to be addressed

Is **CNC-aware removal** a requirement for a consistent **stream management** in a **multivendor** domain?



Required:

Definition for **CNC behavior**

Further open issues

Currently not described in Qdj (or other Q standards)

- Power-on behavior of CNC
- On-boarding procedure
- Behavior in error detection
 - too many CUCs, CNCs, stream requests ...
- Overall **dynamic behavior**

Where should they be
addressed

- Qdj ?
- 60802 ?
- ...?

| Further questions?

| Contact

Dr. Rodrigo Ferreira Coelho

System Architect

DI FA CTR ICO ARC

Siemenspromenade 1

91058 Erlangen

Deutschland

Phone: +49 9131 17-45546

E-mail: rodrigo.ferreira_coelho@siemens.com