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- CF-Async is a **delivery modality**, not a **service class**.
 - Both contention-based Async and CF-Async deliver frames for the "asynchronous data" service class.
 - Time-Bounded Services involve one or more, service classes.
- CF-Async differs from contention-based async in **media access and control communication**:
 - Access to the medium for CF-Async transmission is controlled by the PCF. Stations receive permission to transmit when "polled" by the PCF.
 - CF-Async frames are delivered without contention delays and backoffs, but only during the CF-Period of each superframe.
 - CF-Async acknowledgements and polls are (generally) piggybacked on the headers of CF-Async data frames.

1. Unify asynchronous data handling:
 - Eliminate the separate CF frame type.
 - Adopt consistent acknowledgement timing.
 - Define rules under which all active stations can receive asynchronous data frames during the contention period and the contention free period.
2. Correct some problems:
 - Fix a mechanism broken in 20b3.
 - Fix a latent flaw present in 20bX.
 - Clarify the rules for usage of the CF-period.

- CF-Async does not need a separate frame type:
 - By defining some new subtypes, all asynchronous data frames can use the "Asynchronous" data type.
 - This simplifies the use of either contention-based async or CF-Async for data frame transmission at stations that support both delivery modalities.
 - This creates a reserved frame type, which may be useful for other service classes. (Time-Bounded Service may be able to benefit from using the spare frame type.)
 - Using a single frame type simplifies asynchronous data delivery and allows simpler control state machines, especially for IFS and Ack generation.
- NOTE: The terms "CF-up" and "CF-down" that still appear in the draft are strictly descriptive (meaning to and from the PCF, respectively). The adoption of 94/236 eliminated the CF-up and CF-down frame types (which are unnecessary).

- The ability for a station to operate as the PCF is optional.
- The options concerning contention-free "service" pertain to **transmission** during the CF-Period.
 - All stations can **receive** data frames sent as CF-Async.
 - Stations may optionally **transmit** data frames when polled by the PCF.
 - Stations that are not "CF-Aware" acknowledge CF-Data frame reception identically to contention-based data frames (by sending an ACK control frame).
- The elimination of the separate CF frame type simplifies the reception of asynchronous data frames by non-CF-Aware stations.

- Draft changes from 94/236 broke a PCF mechanism:
- The CF-Poll frame control bit was eliminated, using the receipt of a CF frame from the PCF as an **implicit CF-Poll**.
 - Without an **explicit CF-Poll** function, the PCF has no way to acknowledge a received CF frame without granting access to the medium. This means that, under certain conditions, **THE CF-PERIOD MIGHT NEVER END!**
- The best way to correct this is to use one of the Subtype bits to encode the "CF-Poll" function. This is detailed in a subsequent slide.

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Fixing a Latent Flaw Slide 7

The PCF description in 93/20bX contains a flawed mechanism:

- The communication of CF-Poll and CF-Ack indications, when there is no CF-Data frame to transfer, is specified to occur using a CF-Data frame with a zero-length payload.
- This is a bad approach:
 - The receipt of a data frame generates an indication to the receiver's LLC, even for zero-length payloads.
 - There is no mechanism to distinguish zero-length MSDUs provided by the transmitting LLC and zero-length CF-Data frames generated by the MAC.

The best way to correct this is to use one of the Subtype bits to encode a "no payload" function. This is detailed in a subsequent slide.

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Simplified IFS Usage During the CFP Slide 8

The alternating use of PIFS and SIFS during the CF-Period is unnecessary and inefficient:

- The PIFS is required only in two situations:
 - At the beginning of the CF-Period: To allow the PCF to gain control of the medium.
 - During the CF-Period, when the recipient of a CF frame from the PCF fails to respond within an SIFS interval: To allow the PCF to retain control of the medium.
- The SIFS should be used between all other frames during the CF-Period:
 - The control state machine is simplified because all acknowledgements, whether in ACK control frames or piggybacked in CF-Data+Ack frames, are expected an SIFS-duration after the associated data frame.
 - The time required to send a given set of frames during the CF-Period is reduced.

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The Async Data Subtype Field Slide 9

Async Subtype:	Reserved	No-Data	CF-Poll	CF-Ack
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Subtype	Sent By	Meaning
0000	any STA	Data (same as 20b3)
0001	any CF-STA	Data+CF-Ack (same as 20b3)
0010	PCF	Data+CF-Poll
0011	PCF	Data+CF-Ack+CF-Poll
0100	none (any?)	null function
0101	any CF-STA	CF-Ack (no data)
0110	PCF	CF-Poll (no data)
0111	PCF	CF-Ack+CF-Poll (no data)
1xxx	none	reserved

- Non-CF-aware stations only need to test for "No-Data = 0" in the Subtype field of Async frames.
- Each CF-related combination already needs to be handled by the PCF and/or CF-aware stations (see 94/207A).

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CF-Period Usage Rules Slide 10

1. Only Data frames (and resulting Ack frames, if any) shall be sent during the CF-period. All management frames shall be sent during the contention period.
2. A PCF may send Async Data frames to any active station (not to stations in PSP or PSNP mode).
 - CF-aware stations shall acknowledge receipt of each Async Data frame (from the PCF) that has CF-Poll=1 using CF-Ack=1 in a Data frame (possibly with No-Data=1), sent after an SIFS-interval; and shall acknowledge the receipt of all other Async Data frames using ACK Control frames sent after an SIFS-interval.
 - Non-CF-aware stations shall acknowledge receipt of (all) Async Data frames using ACK Control frames sent after an SIFS-interval. (This is the same as these stations already do for contention-based async.)

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CF-Period Usage Rules (cont.) Slide 11

3. When polled by the PCF (CF-Poll=1 in the header of a directed Data frame), a CF-aware station may send one Data frame to any destination.
 - Such a frame directed to or through the PCF station shall be acknowledged by the PCF, using CF-Ack=1 in a Data frame (possibly with No-Data=1), sent after an SIFS-interval.
 - Such a frame directed to non-PCF stations shall be acknowledged using an ACK Control frame sent after an SIFS-interval. (This is the same as these stations already do.)
 - A polled CF-aware station with neither a Data frame nor acknowledgement to send shall not respond, permitting the PCF to resume transmission after a PIFS-interval.
4. The PCF shall not send Data frames with CF-Poll=1 if insufficient time remains in the current CF-Period to permit the polled station to transmit a Data frame containing a maximum-length MPDU.

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 Slide 12

MOTION #1

Slide 13

1. To restore the explicit CF-Poll capability lost in 93/20b3, using a bit in the Frame Subtype, as defined in document 94/252.
(motion not made due to approval of Motion #4)

MOTION #2

Slide 14

2. To eliminate the use of zero-length CF-Async frames for polling and acknowledgement when there is no CF-Async data, using instead a "no data" bit in the Frame Subtype, as defined in document 94/252.
(motion not made due to approval of Motion #4)

MOTION #3

Slide 15

3. To adopt the changes to contention free asynchronous operation, including frame types/subtypes, usage rules, IFS durations, etc. as defined in document 94/252.
(motion not made due to approval of Motion #4)

MOTION #4

Slide 16

4. To adopt the changes to contention free asynchronous operation, including frame types/subtypes, usage rules, IFS durations, etc. as defined in document 94/252; and to modify the updates to section 4.1.2.1.2. to designate the "reserved" frame type (type code =11) as "time bounded" frame type.
(this motion was approved in MAC group 18-2-12)

