

Project	<b>IEEE 802.16 Broadband Wireless Access Working Group</b> < <a href="http://ieee802.org/16">http://ieee802.org/16</a> >	
Title	<b>Candidate Channel Determination (Using GPS/UTC Synchronized CMI and Common Profile)</b>	
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Re:	Call for Comments and Contribution, "IEEE 802.16's License-Exempt (LE) Task Group", 2006-02 Item 2.	
Abstract	This document specifies the candidate channel selection process for systems using GPS/UTC time Synchronization and common profile. The process is used typically by an IBS to select a channel in an interference neighborhood having the least amount of interference on it. This document incorporates changes to IEEE C802.16h-06-024.	
Purpose	To provide an channel selection proposal as part of the adaptive channel selection process.	
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### **Candidate Channel Determination (Using GPS/UTC Synchronized CMI and Common Profile)**

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In the selection of a channel by an IBS operating in a WirelessMAN-CX environment, there are a number of challenges, such as:

- (a). The necessity to identify, quantify, and rank channels used by a variety of users, some of which may have long periods of non-transmission or bursty performance. RLAN networks compliant to IEEE 802.11a/b/g are examples.
- (b). The need to measure interference signal power that may be below demodulation levels. It will be necessary to differentiate interference signal power from thermal noise.
- (c). The necessity to determine a noise floor power against which interference can be compared.

The proposal detailed below relies on the measurement and calculation of the mean and variance of received interference signals by techniques outlined in Section 8.4.11.2. These techniques can be used to quantify an interference-free noise floor [N], differentiate thermal noise from signal power, and measure interference power [I].

Within the context of the GPS/UTC synchronized system it is proposed that:

- (1) The CMI\_ID54 interval, which is free of IEEE802.16h traffic, be used to either determine the interference noise floor of the receiver or to identify a channel used by a non-IEEE 802.16 occupant. This is done by utilizing the statistical differences between LE signals and noise and additionally by defining expected noise floor values for the receiver.
- (2) Having defined a noise floor, the techniques of Section 8.4.11.2 can be used to identify and measure interference signal power, and
- (3) A representative sample of interference signals, free of bias introduced by data traffic transmission, are available in the form of SSURF traffic that is transmitted on the uplink in a periodic manner over the intervals CMI\_ID00 to CMI\_ID48.

*Insert the following in Section 4.0*

CCD      Candidate Channel Determination  
BSD      Base Station Descriptor

*Insert the following as section 15.4.1.1*

#### **15.4.1.1 Candidate Channel Determination (Using GPS/UTC Synchronized CMI and Common Profile)**

Candidate Channel Determination (CCD) is the process used by WirelessMAN-CX systems (using a synchronized CMI and common profile) where a base station monitors a band to which it has access and selects, within that band, a channel having minimal use and occupancy by neighboring wireless systems. This process is used, for example, by an IBS prior to undertaking entry into a Coexistence Community. Since a base station can only receive uplink traffic, this process relies on the monitoring uplink transmission intervals and the measurement of interference signal power [I] and noise power [N]. Each candidate channel will be ranked in terms of its (I/N) ratio. Those channels with the lowest ratio or ideally a ratio of 1 will be selected for use by the base station and be candidates for entry by an IBS, since such channels will have the lowest amount of discernable activity on them, hence likely have lower interference.

[I] and [N] will be determined using the RSSI measurement capability of the base station receiver as detailed in Section 8.4.11.2. After synchronization to the GPS and initialization of the base station operating parameters, the base station will select a channel and undertake noise floor measurements on CMI\_ID54, which is unoccupied by IEEE 802.16h networks but may be used by non-IEEE 802.16h networks (15.3.1.1.3.1).

CMI\_ID54, in situations when it is unoccupied, will be free from all IEEE 802.16h transmissions and will provide an interval allowing the measurement of the receiver thermal noise floor [N]. The thermal noise floor is the noise power spectral density of the received channel ( $N_0$ ) multiplied by the channel bandwidth. Measurements will be undertaken long enough to determine whether [N] has Gaussian characteristics. Characteristics not deemed as Gaussian and/or RSSI measurements that are 3 db (TBD) higher than a predetermined [N] value (which can be provided a priori as a Receiver Noise Figure estimate within RSSI measurement algorithm in the base station receiver) will be indicators that channel may be occupied by non-IEEE 802.16h users. In this instance the value of the mean RSSI will be taken as the [I] created by the occupying non-IEEE 802.16h network and the given channel will be discarded from further consideration. Otherwise, the measurement will provide a value for [N].

[I] measurements will be undertaken by calculating the mean signal strength and variance due to uplink SSURF messages summed over intervals CMI\_ID00 to CMI\_ID48. The number of CMI cycles to be measured will be a variable (TBD) set for the base station by the operator. Measurement of the RSSI will be done in accordance with Section 8.4.11.2, with care being taken to ensure that valid signals are being measured, even at close-to noise floor levels. The mean RSSI and variance calculated for the summed CMI intervals of the channel will be construed as interference values [I] and [Var I] for the channel.

The channels are then ranked, with the channel having the lowest I/N and smallest [Var I] measurements likely selected for IBS entry into a Coexistence Community. Figure Hxxx shows the CCD process.

Figure Hxxx. CCD Process.

