#### **Updated 4Tx Pilot Patterns for IEEE 802.16m**

#### **IEEE 802.16 Presentation Submission Template (Rev. 9)**

**Document Number:** 

IEEE C802.16m-08/0006

Date Submitted:

2009-01-07

Source:

Jerry Pi, Taeyoung Kim, Hai Wang Samsung Electronics zpi@sta.samsung.com

Venue:

Re: TGm Call for Contributions and Comments 802.16m-08/003r6 for Session 59

Base Contribution:

IEEE C802.16m-08/0006

Purpose:

To discuss and adopt the proposed text in the revision of the 802.16m SDD

Notice:

This document does not represent the agreed views of the IEEE 802.16 Working Group or any of its subgroups. It represents only the views of the participants listed in the "Source(s)" field above. It is offered as a basis for discussion. It is not binding on the contributor(s), who reserve(s) the right to add, amend or withdraw material contained herein.

#### Release:

The contributor grants a free, irrevocable license to the IEEE to incorporate material contained in this contribution, and any modifications thereof, in the creation of an IEEE Standards publication; to copyright in the IEEE's name any IEEE Standards publication even though it may include portions of this contribution; and at the IEEE's sole discretion to permit others to reproduce in whole or in part the resulting IEEE Standards publication. The contributor also acknowledges and accepts that this

contribution may be made public by IEEE 802.16.

#### Patent Policy:

The contributor is familiar with the IEEE-SA Patent Policy and Procedures:

<a href="http://standards.ieee.org/guides/bylaws/sect6-7.html#6">http://standards.ieee.org/guides/opman/sect6.html#6.3</a>.

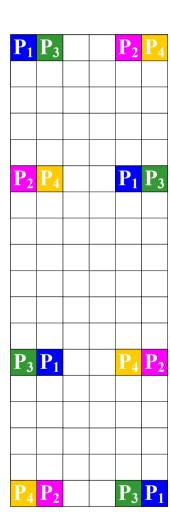
Further information is located at <a href="http://standards.ieee.org/board/pat-material.html">http://standards.ieee.org/board/pat-material.html</a> and <a hre

# Background

- 4Tx pilot pattern has been adopted in the latest SDD
  - Page 80, section 11.5.3, IEEE 802.16m-08/003r6
- 8Tx pilot pattern is being proposed in IEEE C802.16m-08/0007

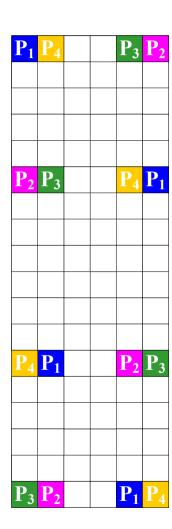
### Current 4Tx Pilot Pattern

- Channel estimation performance for {P<sub>1</sub>, P<sub>4</sub>} is different from that of {P<sub>2</sub>, P<sub>3</sub>}
- Two sets of MMSE or interpolation weights are required
  - One for  $\{P_1, P_4\}$ , the other for  $\{P_2, P_3\}$



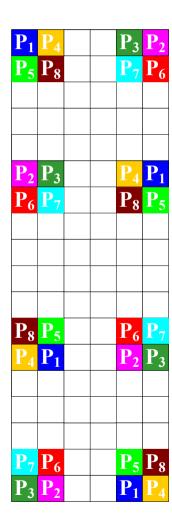
## Updated 4Tx Pilot Pattern

- All 4 pilot streams have mirrored pilot patterns
- Occupy the same set of subcarriers as the original 4Tx pilot pattern
- One sets of MMSE or interpolation weights for all 4 pilots
- Significant complexity reduction



## 8Tx Pilot Pattern

- 8 pilot streams
  - Overhead: 4/108 = 3.7% each
  - Total overhead 32/108 = 29.63%
- Mirrored pilot patterns
  - Reuse the 4Tx pilot patterns for P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub>, P<sub>4</sub>
    (See previous page for updated 4Tx pilot pattern)
  - Pilot patterns for P<sub>1</sub>, P<sub>2</sub>, P<sub>3</sub>, P<sub>4</sub> mirror in time or frequency
  - Pilot patterns for P<sub>5</sub>, P<sub>6</sub>, P<sub>7</sub>, P<sub>8</sub> mirror in time or frequency
  - Low complexity implementation of channel estimation
  - Easy to adapt for 5-symbol subframes (by removing the 3<sup>rd</sup> or 4<sup>th</sup> symbol in the pilot pattern for 6-symbol subframes)



## Simulation Assumptions

- 4Tx Pilot Pattern
  - Current vs. Updated
  - Rank-1 precoder cycling
  - Channel models:
    - Ped A 3kmph, Ped B 3kmph, Veh A 30kmph, Veh A 120kmph
  - MCS
    - QPSK 1/2, QPSK 1/3, 16QAM 1/2, 16QAM 1/3, 64QAM 1/2, 64QAM 1/3
  - 3 contiguous PRUs
  - 2D MMSE channel estimator per PRU
- Metric:
  - BLER
  - MSE

## Summary

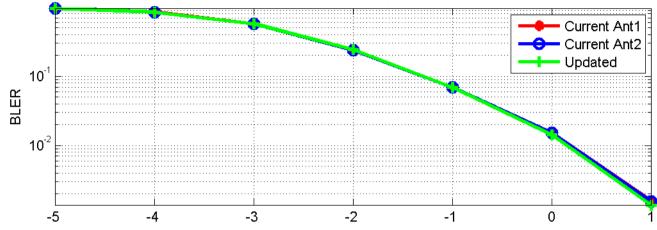
- Updated 4Tx pilot pattern achieves the same or slightly better performance than the current 4Tx pilot pattern
- All pilot streams achieve the same performance with the updated pilot pattern
- Updated 4Tx pilot pattern allows lower implementation complexity than current 4Tx pilot pattern

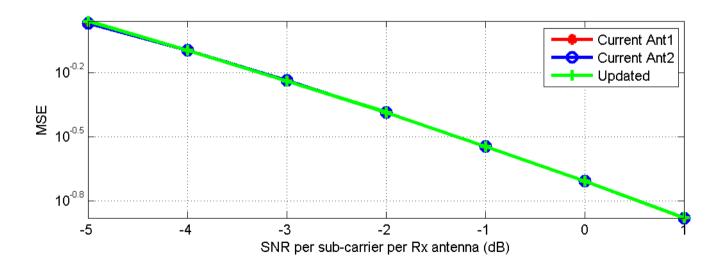
## Recommended SDD text change

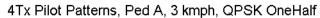
- Section 11.5.3, page 80, line 1
  - Replace figure 42 by the figure in page 4 of contribution C802.16m-08 0006

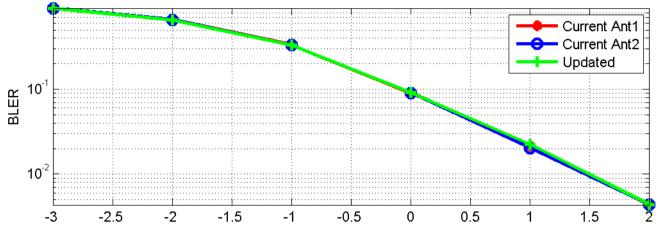
# SIMULATION RESULTS – 4TX PILOT PATTERNS

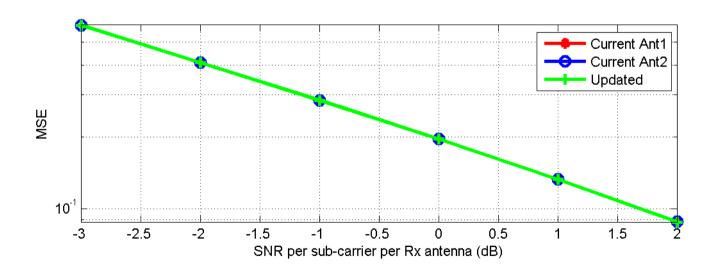
#### 4Tx Pilot Patterns, Ped A, 3 kmph, QPSK OneThird



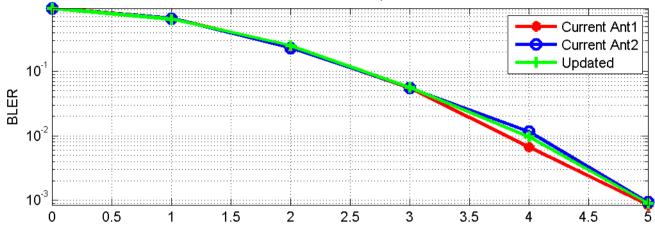


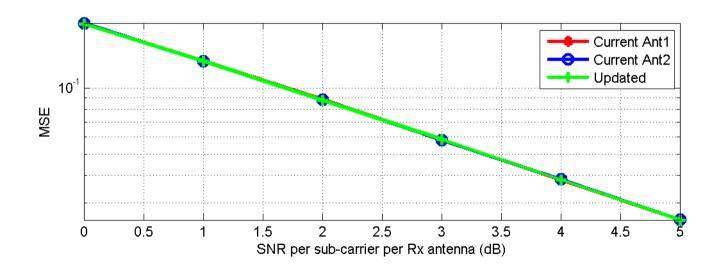




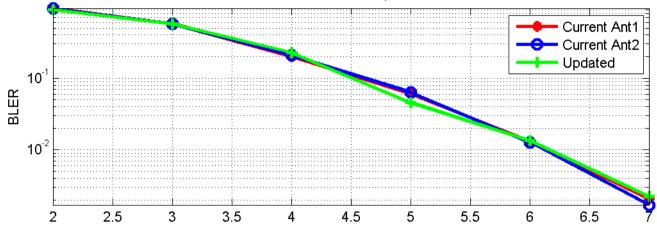


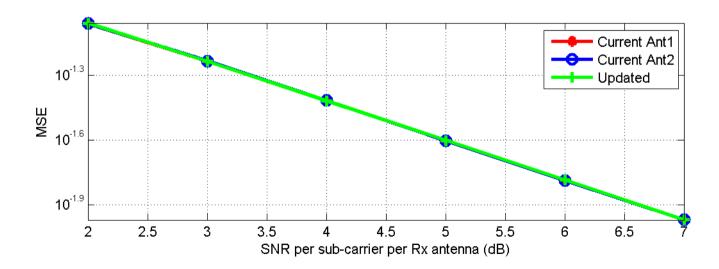
#### 4Tx Pilot Patterns, Ped A, 3 kmph, 16QAM OneThird



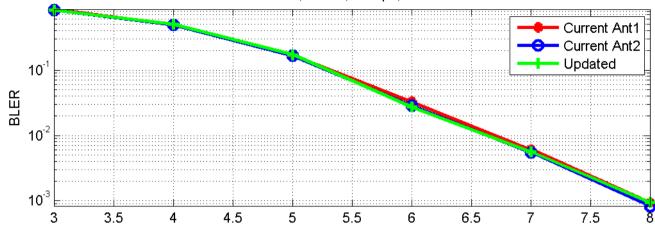


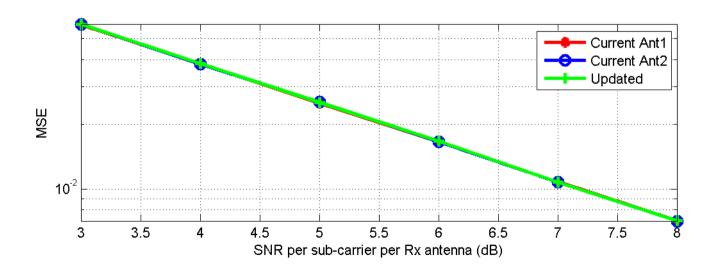




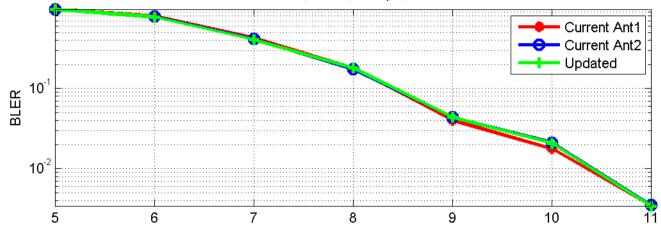


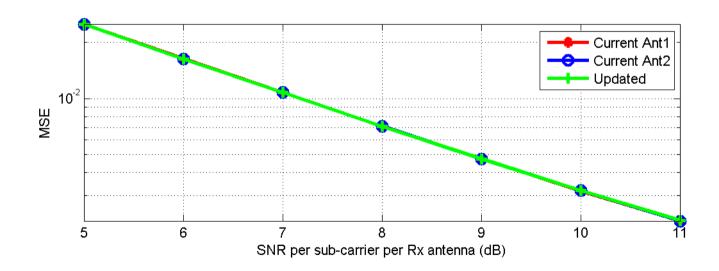
#### 4Tx Pilot Patterns, Ped A, 3 kmph, 64QAM OneThird

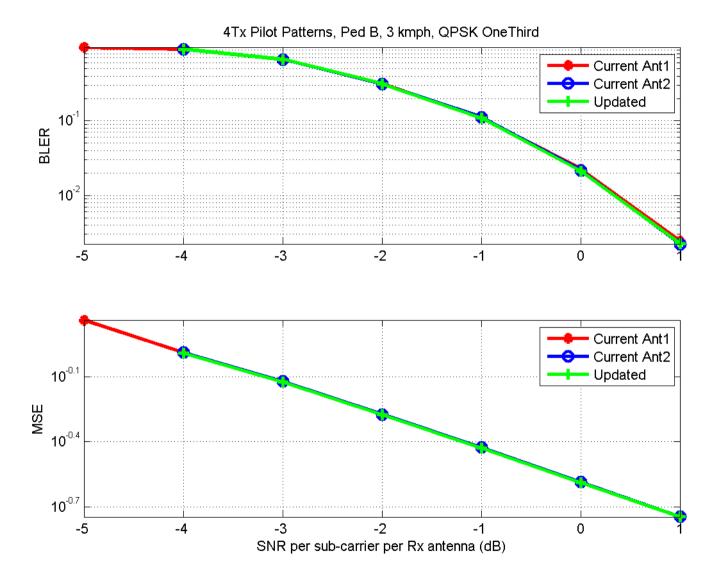




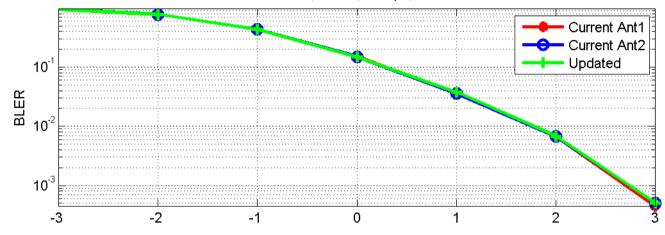
#### 4Tx Pilot Patterns, Ped A, 3 kmph, 64QAM OneHalf

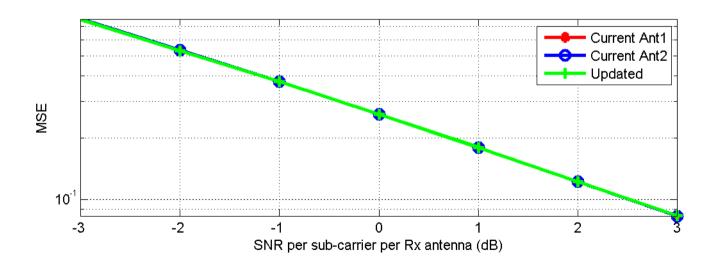


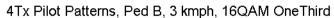


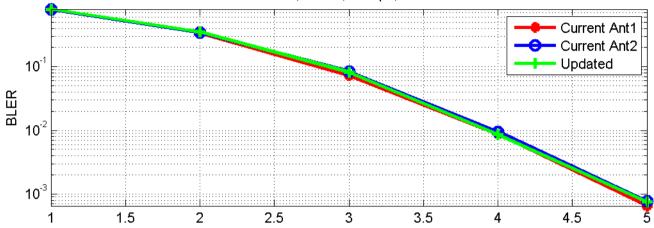


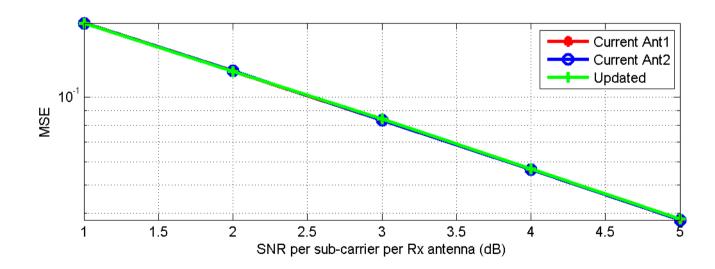
#### 4Tx Pilot Patterns, Ped B, 3 kmph, QPSK OneHalf



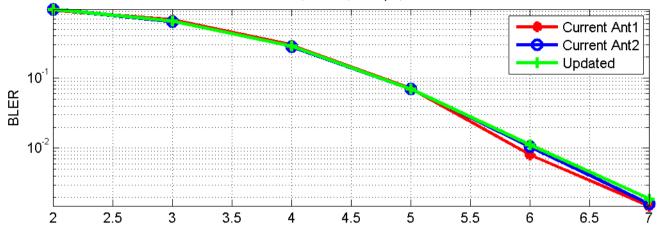


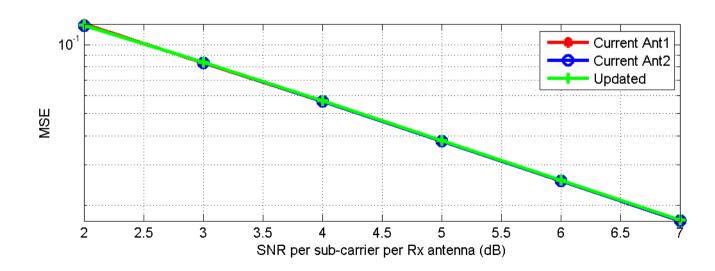


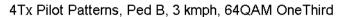


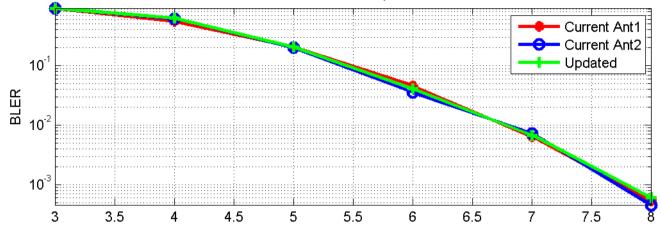


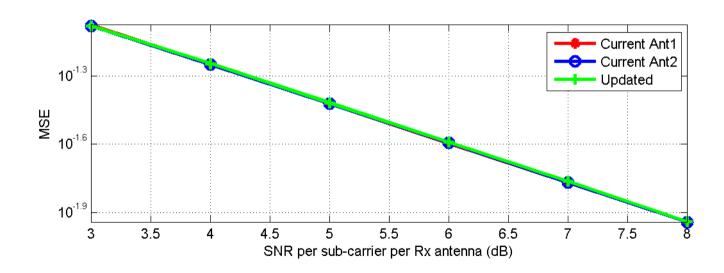
#### 4Tx Pilot Patterns, Ped B, 3 kmph, 16QAM OneHalf



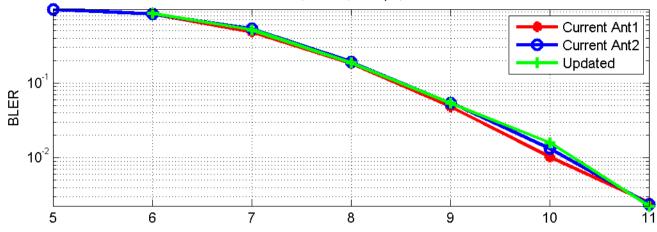


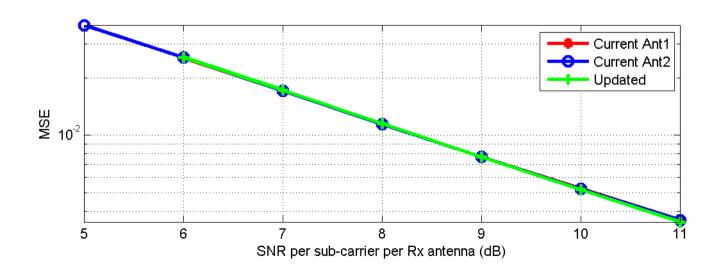


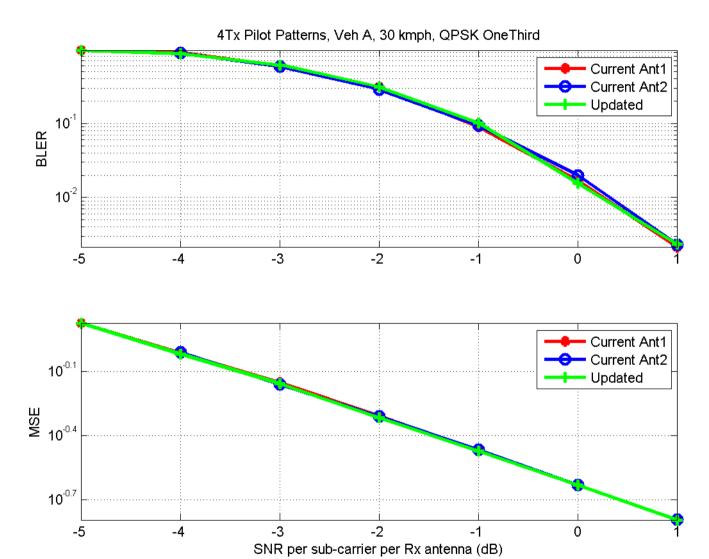




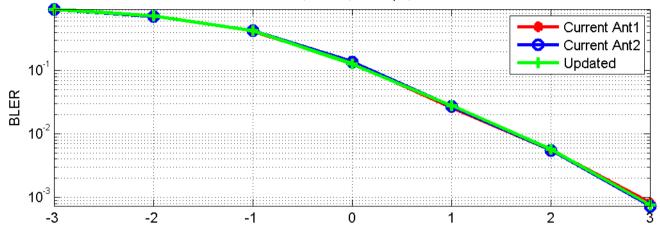
#### 4Tx Pilot Patterns, Ped B, 3 kmph, 64QAM OneHalf

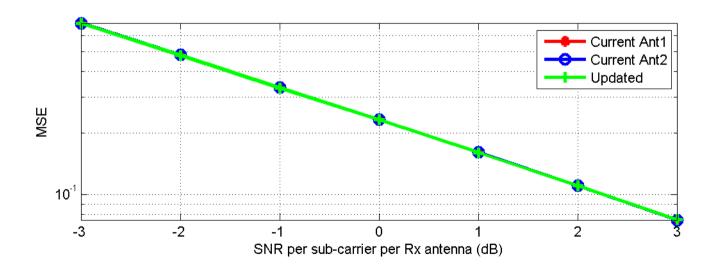


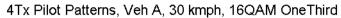


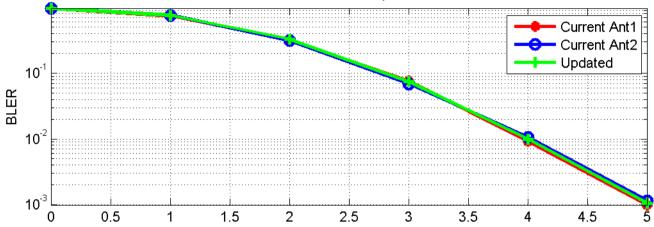


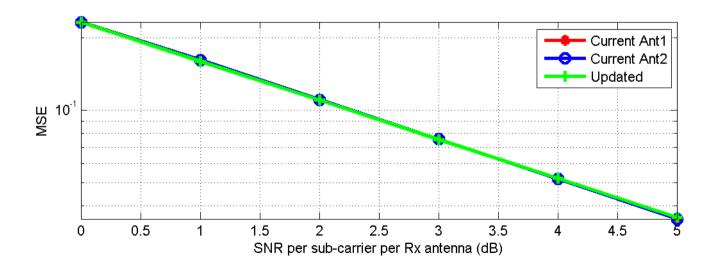
#### 4Tx Pilot Patterns, Veh A, 30 kmph, QPSK OneHalf

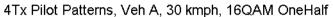


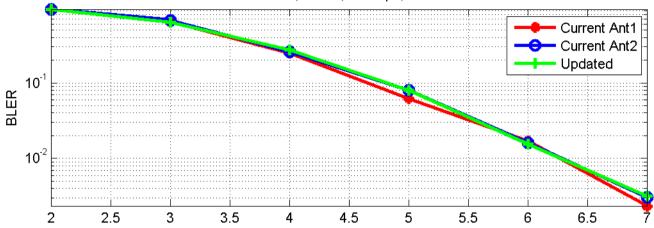


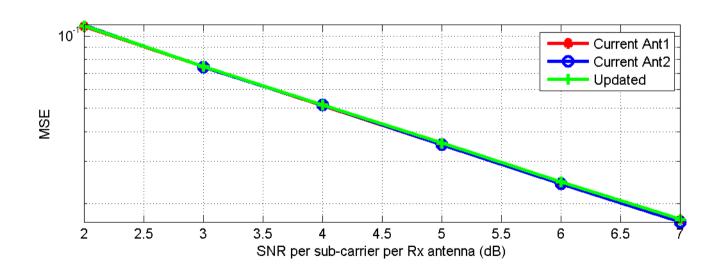




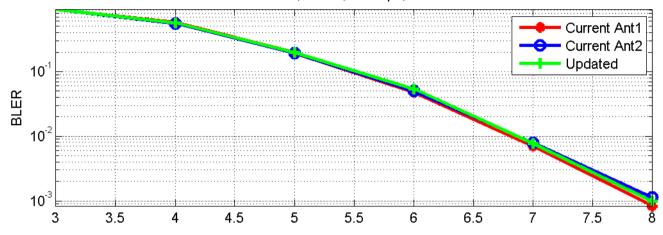


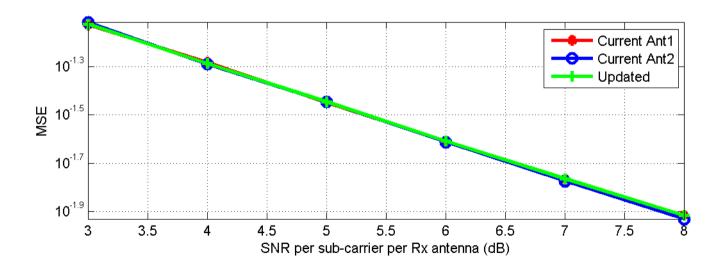


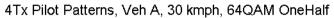


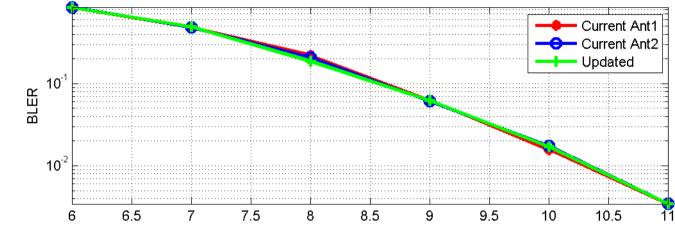


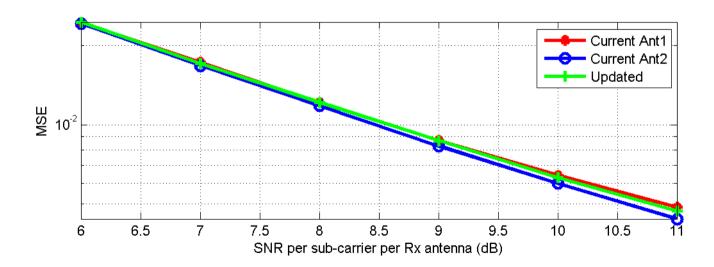
#### 4Tx Pilot Patterns, Veh A, 30 kmph, 64QAM OneThird



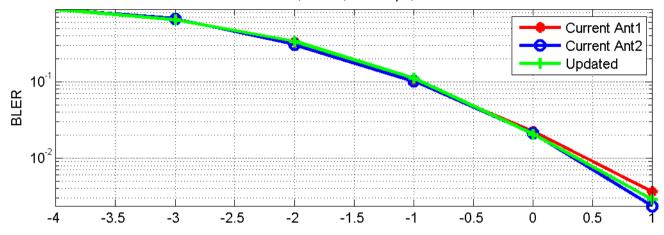


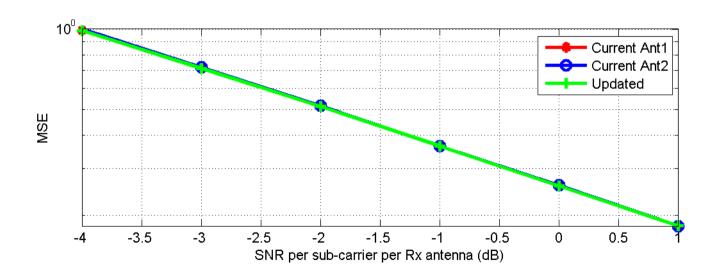




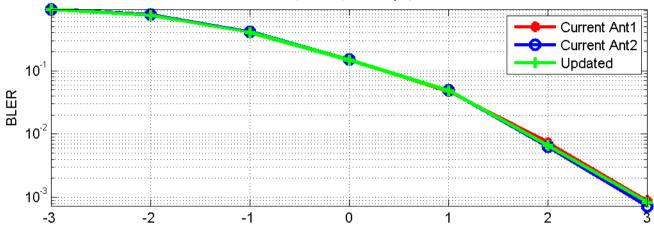


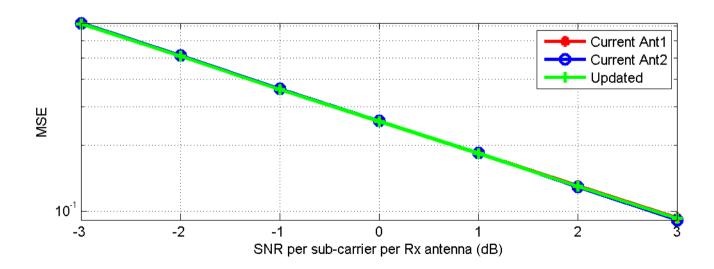
#### 4Tx Pilot Patterns, Veh A, 120 kmph, QPSK OneThird



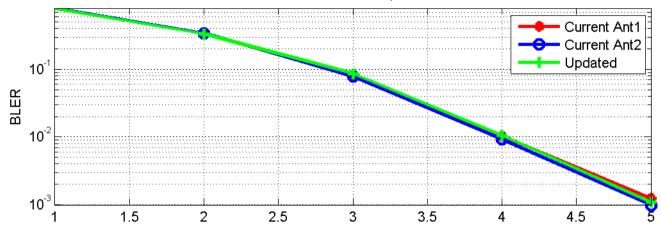


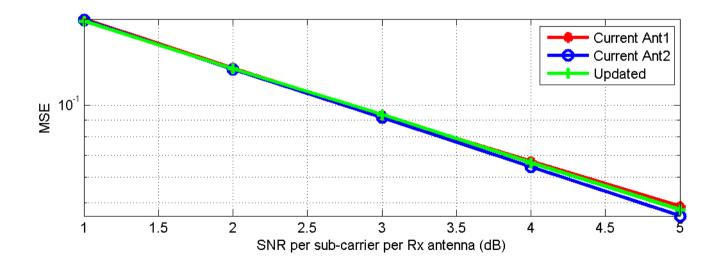
#### 4Tx Pilot Patterns, Veh A, 120 kmph, QPSK OneHalf

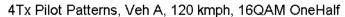


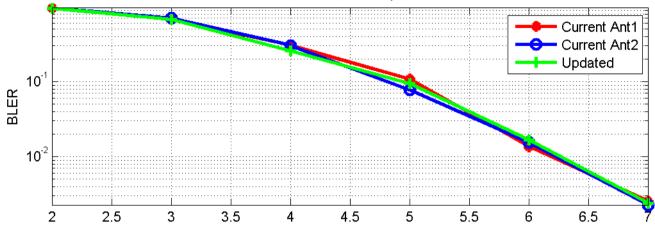


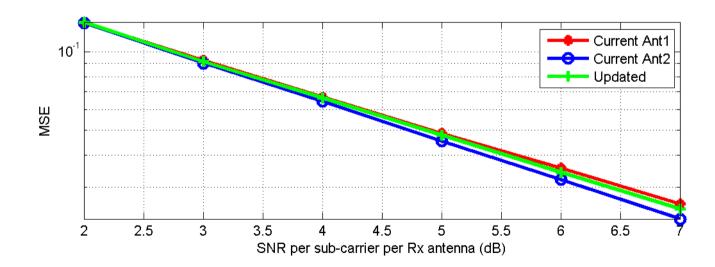
#### 4Tx Pilot Patterns, Veh A, 120 kmph, 16QAM OneThird











#### 4Tx Pilot Patterns, Veh A, 120 kmph, 64QAM OneThird

