

# RPR Protection Proposal

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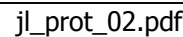
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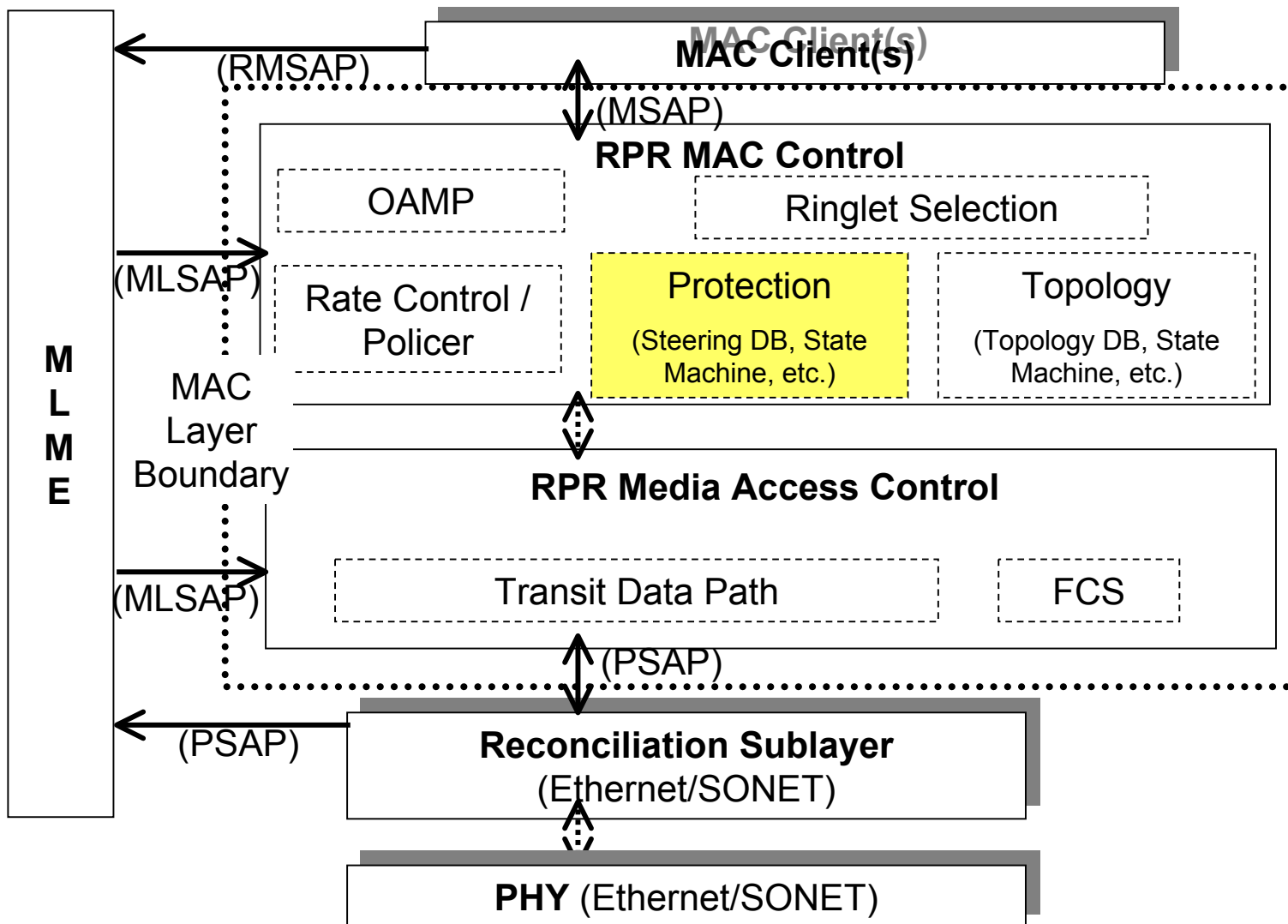
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## 302.17



# 802.17 MAC Components



# Common Goals

- Protection switching within 50ms
- Scalable from 1 to 100's of stations
- Quick dissemination of loss of connectivity information on the ring
- Tolerance of message loss
- Operation without any master station on the ring
- Operation independent of and in the absence of any management systems
- Operation with dynamic addition and removal of stations to/from the ring

# Differing Goals

- Maximal utilization and stable/efficient bandwidth management vs minimal packet loss
- Tolerance of multiple failures vs tolerance of only single failures
- Scalable to multiple ringlets vs designed for dual ringlets only

# Overview

- Each station knows of a ring segment failure and steers ring traffic away from the failure within 50ms of the failure
- Ring protection is initiated by all stations that become directly aware of a failure via local detection or through broadcast announcement

# Use Of Topology Image

- Each station uses its knowledge of the topology of the ring to know how and when to steer ring traffic away from a failure

# Use By Ringlet Selection or MAC Client

- The topology information is combined with the state of each link segment to allow a decision of when and where to steer ring traffic



# Triggers

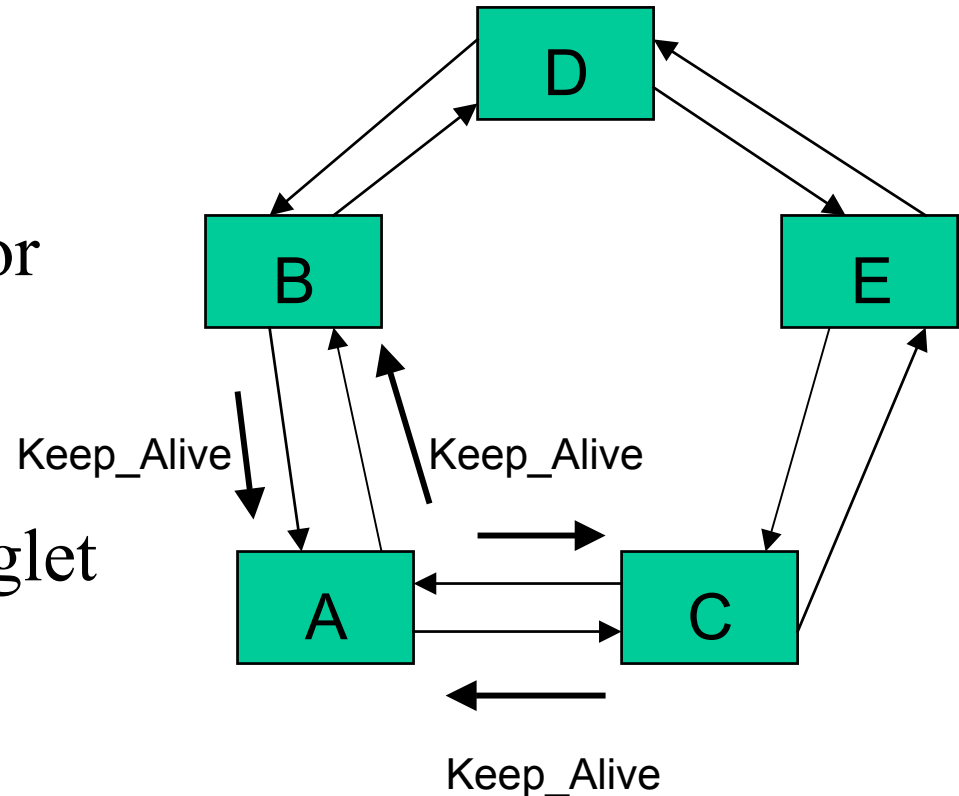
- Protection is triggered by reception of a Link\_Status message indicating a new link status
- Link\_Status messages are generated as a result of a local link failure or restoration as detected by
  - Physical Layer Triggers
    - SONET/SDH Triggers
    - Ethernet Triggers
  - Manual Triggers
  - Keep\_Alive Triggers

# Protection Hierarchy

- Protection hierarchy is used to handle multiple, concurrent events
  - FS, Forced Switch - operator originated (highest priority)
  - SF, Signal Fail (e.g LOS, LOF, EXBER, LOK (Loss Of Keep\_Alive)) - automatically originated
  - SD, Signal Degrade - automatically originated
  - MS, Manual Switch - operator originated
  - WTR, Wait Time To Restore - automatically originated
  - NR, No Request present (lowest priority)

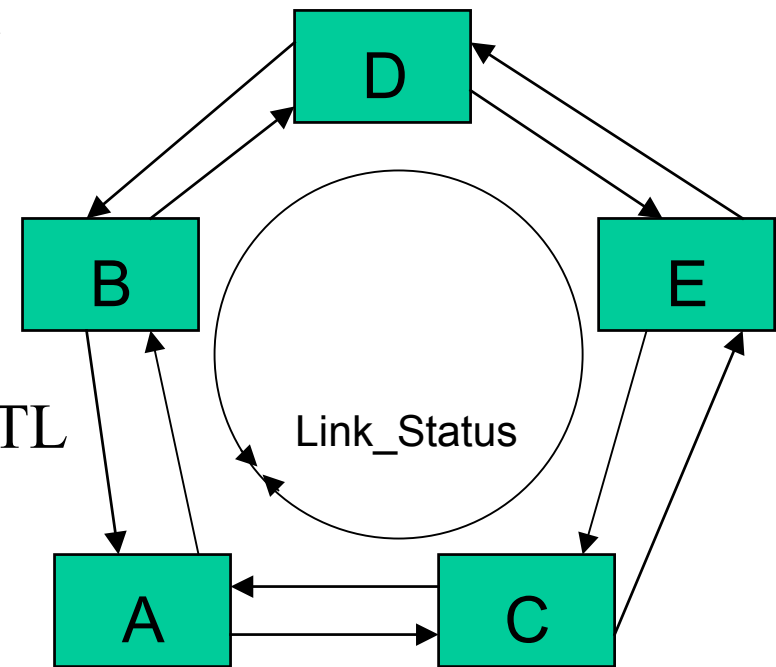
# Keep\_Alive Control Message

- Provides a means of detecting link failure or station failure
- No data field
- Broadcast on each ringlet with  $TTL = 1$ 
  - Removed by neighbor



# Link\_Status Control Message

- Reports changes in neighbor link status
- Key fields
  - Ringlet ID
  - Neighbor link status
- Broadcast on each ringlet with TTL = Max\_Ring\_Size
  - Removed by source
- Evaluating sending continuously
- Evaluating possibly combining with RCM



# Configurable Parameters

- Hold-Off Time
- Wait To Restore time
- Keep Alive loss threshold for down link declaration
- Uni-directional/Bi-directional protection switching mode
- Revertive/Non-revertive protection switching mode

# Unicast Protection

- If sourcing station can reach intended destination through normal route, then use normal route
- Otherwise, if packet is protected and it can reach intended destination through protection route, then use protection route

# Multicast Protection

- If sourcing station can reach intended destination through normal route, then use normal route
- Else, if packet is protected and it can reach intended destination through protection route, then use protection route
- Otherwise, use both routes (2 counter-rotating ringlets)
- TTL is set to the distance to the failed link on each ringlet

# Steering Performance Analysis

- Set up
  - 64 stations, 640 km circumference
  - Dual ringlet ring, 1 Gbps ring rate
  - Processing times for messages set to exponentially distributed times around mean of 200 usec for Keep\_Alive messages and 500 usec for Link\_Status messages
  - Keep\_Alive interval: 1ms
- Failure Scenario
  - Link 0->1 goes down
  - Failure is detected by not receiving a Keep\_Alive in 3 intervals



# Steering Performance Analysis, contd

- Response time = time when all the stations can start protection switching – time when the failure occurs
- Response time = 5.2 ms

# Protection Summary

- Broadcast based algorithm best for steering
- Stability and robustness in case of multiple failures
- Support for multiple ringlets
- Support for Layer 1+2 failure detection
- Also works well for wrapping