

448G/Lane Modulation & FEC

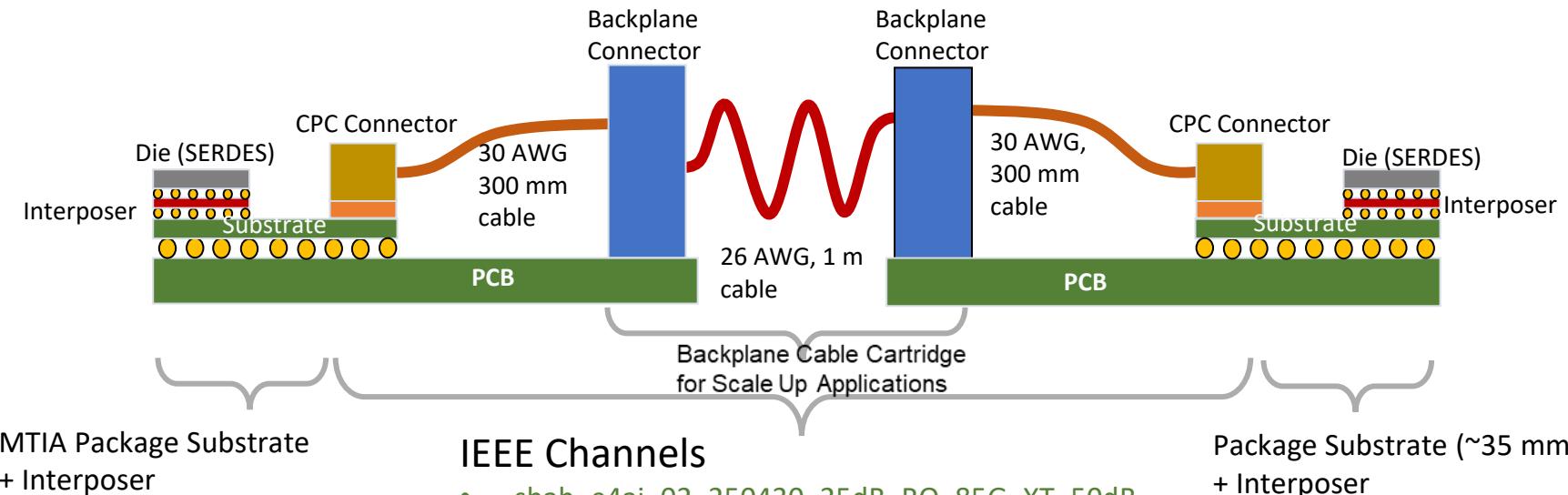
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May-29, 2025



- 448G/Lane Simulations
 - Channel Models
 - Simulation Results with PAM
 - Bidirectional Signaling
- New FEC Proposal
 - 2D RS FEC Results (Under Burst Error)
 - Complexity and Latency Analysis
- Conclusion (Summary and Future Work)

448G/Lane Channel Model



MTIA Package Substrate
+ Interposer

IEEE Channels

- shah_e4ai_02_250430_25dB_RO_85G_XT_50dB
- shah_e4ai_02_250430_25dB_RO_85G_XT_55dB
- shah_e4ai_02_250430_25dB_RO_85G_XT_60dB
- shah_e4ai_02_250430_30dB_RO_85G_XT_50dB
- shah_e4ai_02_250430_30dB_RO_85G_XT_55dB
- shah_e4ai_02_250430_30dB_RO_85G_XT_60dB
- shah_e4ai_02_250430_35dB_RO_85G_XT_50dB
- shah_e4ai_02_250430_35dB_RO_85G_XT_55dB
- shah_e4ai_02_250430_35dB_RO_85G_XT_60dB
- tracy_efai_250430_DAC

Package Substrate (~35 mm)
+ Interposer

Limiting Factors:

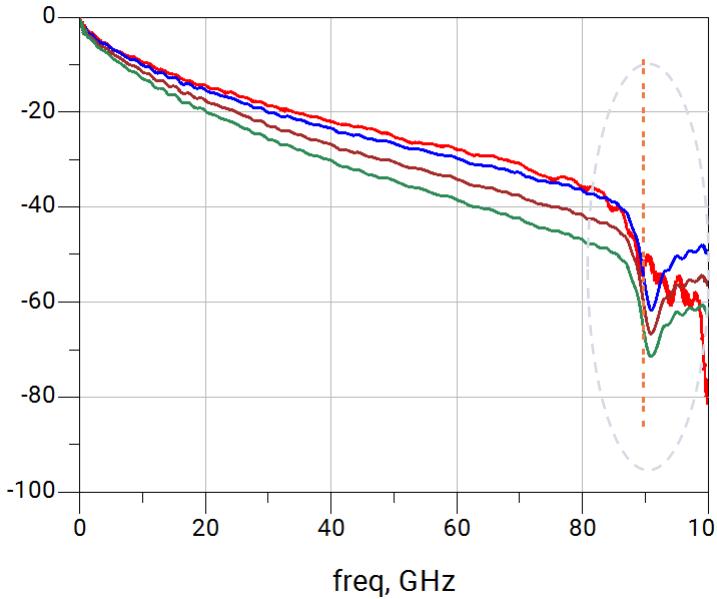
- Channel Insertion loss
- Resonance/Roll-off within pass band
- High crosstalk (NEXT and FEXT)

We acknowledge IEEE and connector vendor for kindly providing the channel models:
https://www.ieee802.org/3/ad_hoc/E4AI/public/channel/index.html

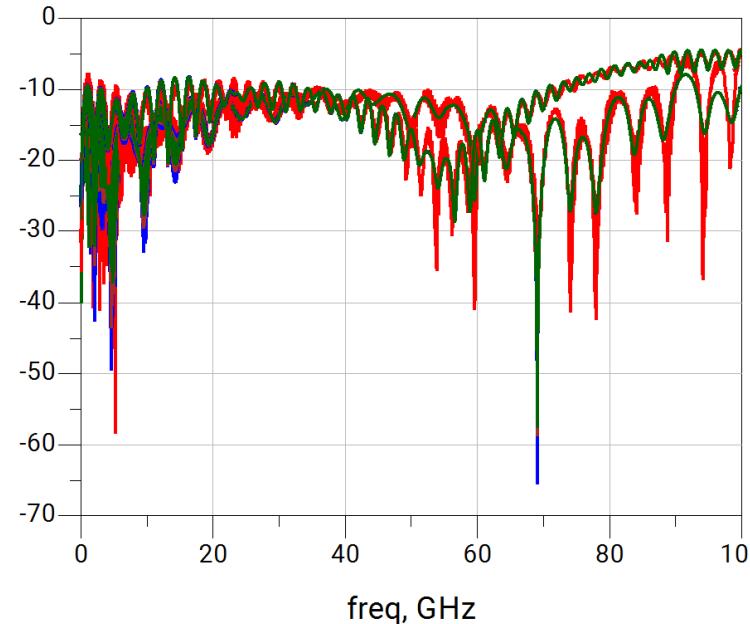
S-Parameter Plots



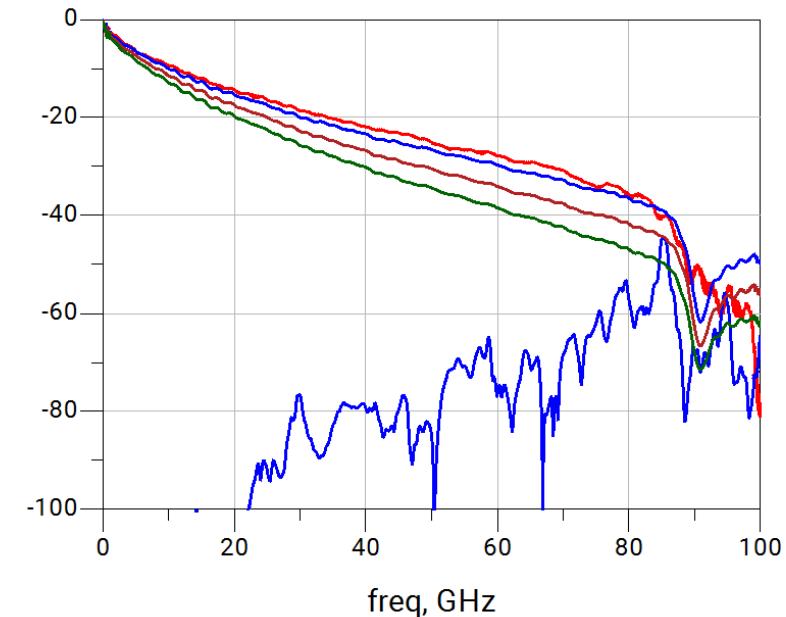
Channel Insertion Loss



Return Loss



Insertion Loss and 50dB Crosstalk Channels



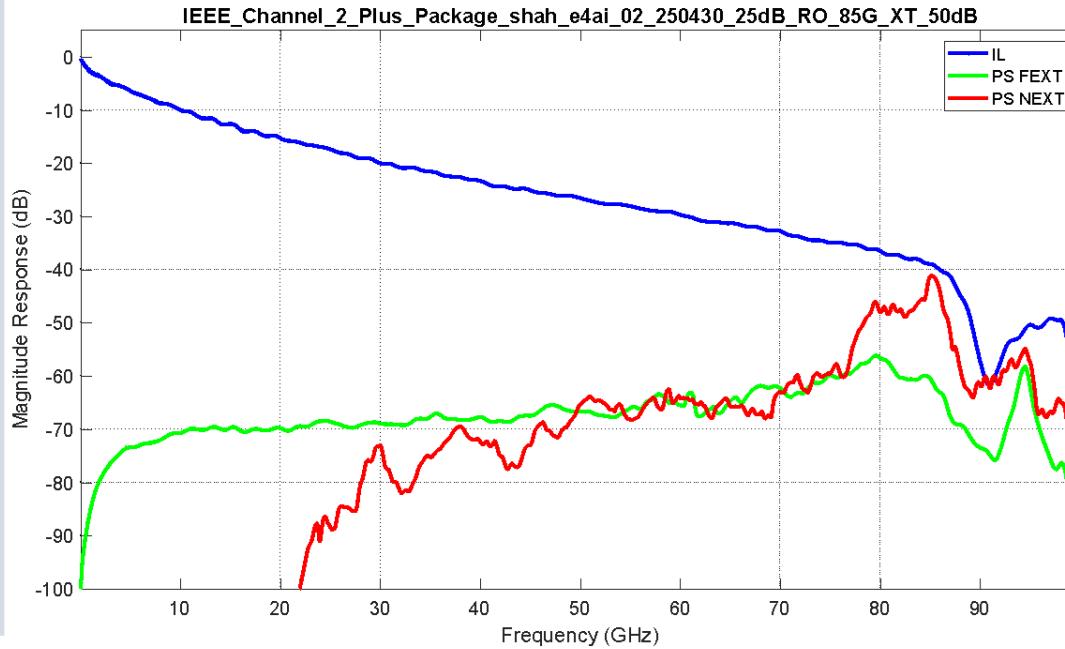
Ask from Industry:

- Provide SERDES Interposer + Package models
- Find ways to reduce crosstalk and eliminate resonance around Nyquist frequency

shah_e4ai_02_250430_25dB_RO_85G_XT_50dB + Package + Interposer



Channel Model Response



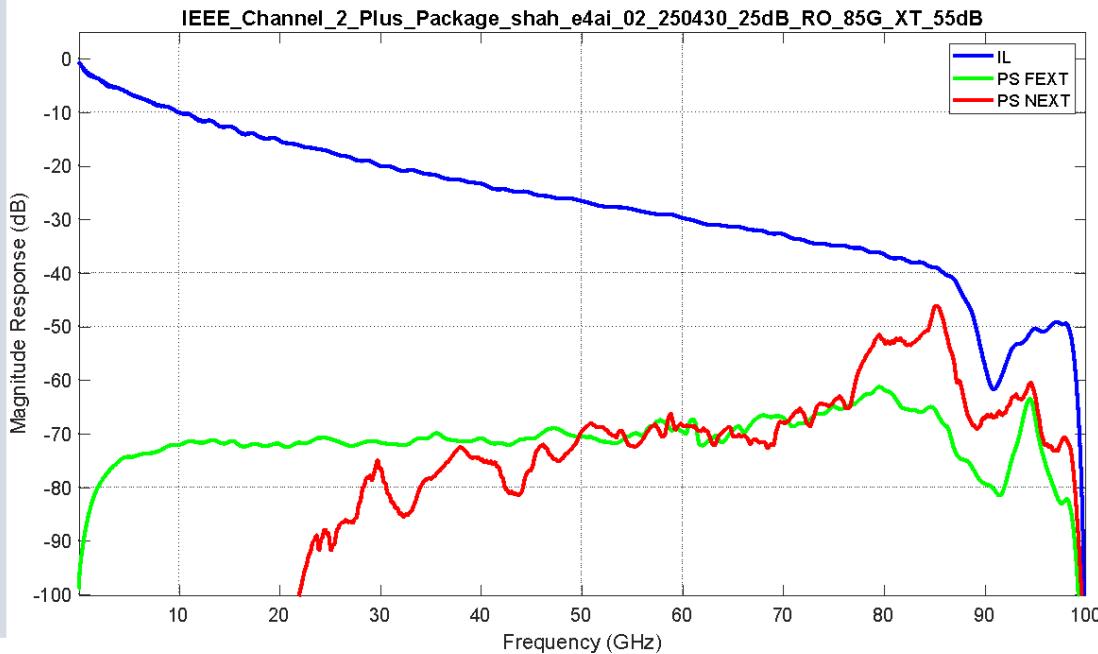
Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
DAC SNR (dB)	41	41	41	41
Transmit SNR (dB)	31	31	31.8	31.7
ADC/DAC Jitter(fs)	50	50	50	50
CTLE Gain(dB) @ 0.8*BW	18	18	18	18
ADC SNR (dB)	43	43	43	43
Equivalent AFE SNR (dB)	33.2	33.3	33.6	34.1
Slicer SNR	23.1	23.4	25.9	26.4
SNR Margin (@1e-3)	3.0	3.3	3.4	3.9
DFE SER	3.1e-4	2.0e-4	6.4e-5	2.1e-5
MLSE SER	5.9e-6	5.9e-6	5.2e-6	4.3e-6

shah_e4ai_02_250430_25dB_RO_85G_XT_55dB + Package + Interposer

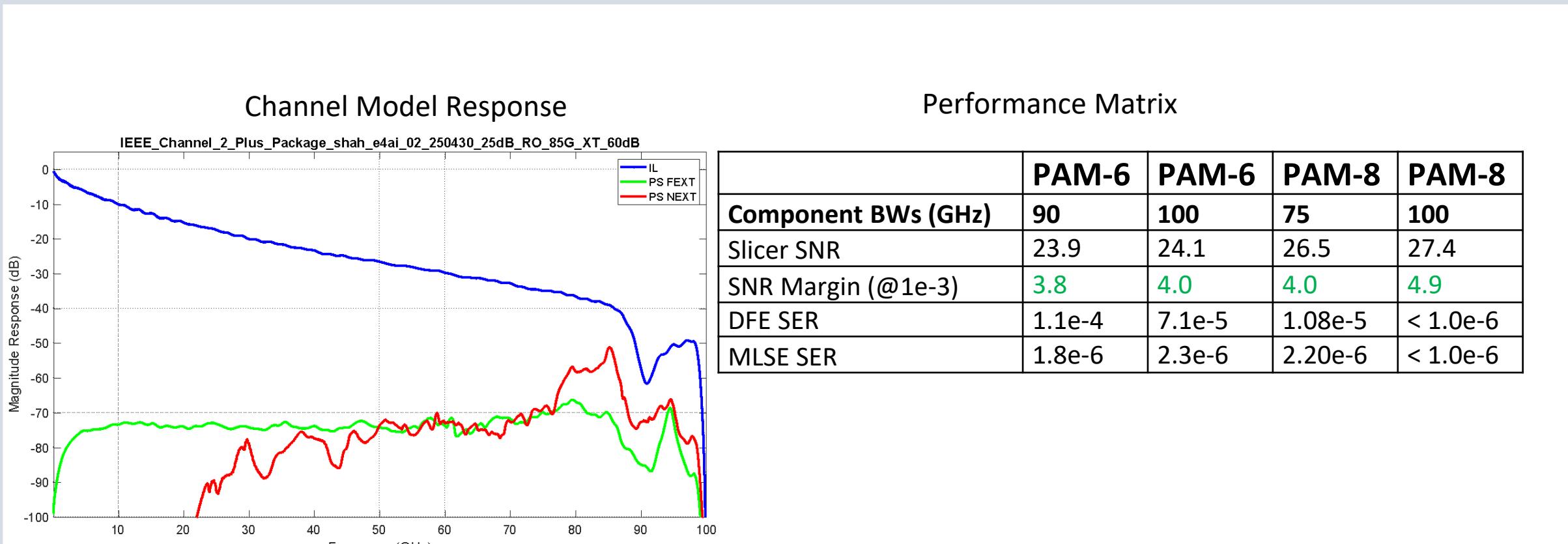


Channel Model Response

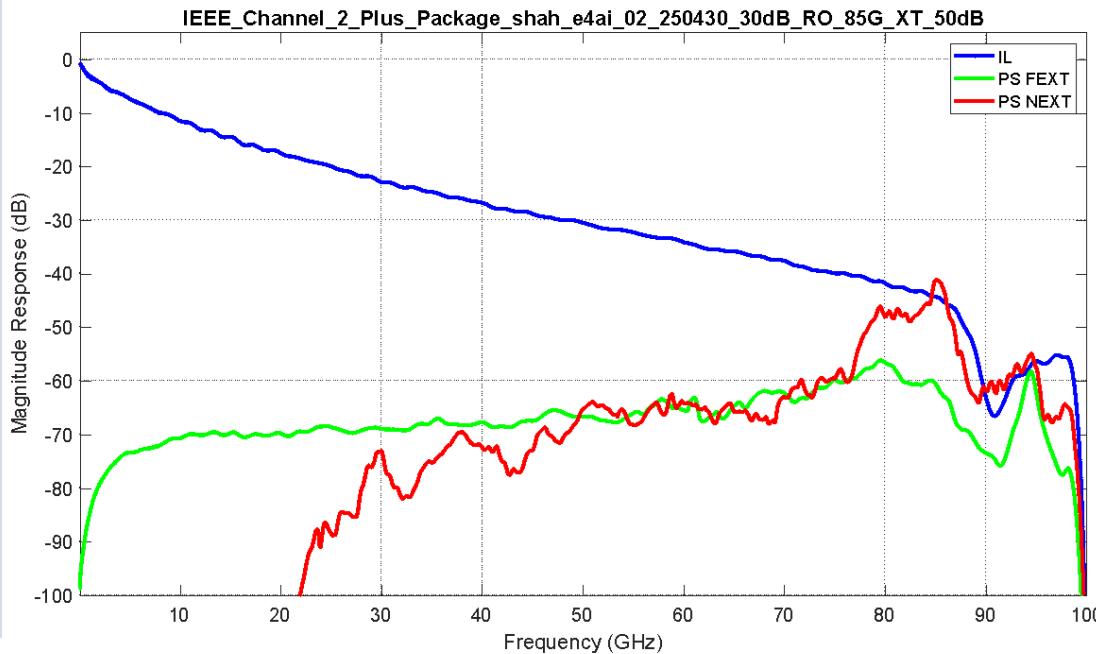


Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
Slicer SNR	23.7	23.9	26.3	27.0
SNR Margin (@1e-3)	3.6	3.8	3.8	4.5
DFE SER	1.3e-4	8.1e-5	1.5e-5	3.3e-6
MLSE SER	3.0e-6	1.8e-6	3.6e-6	1.3e-6



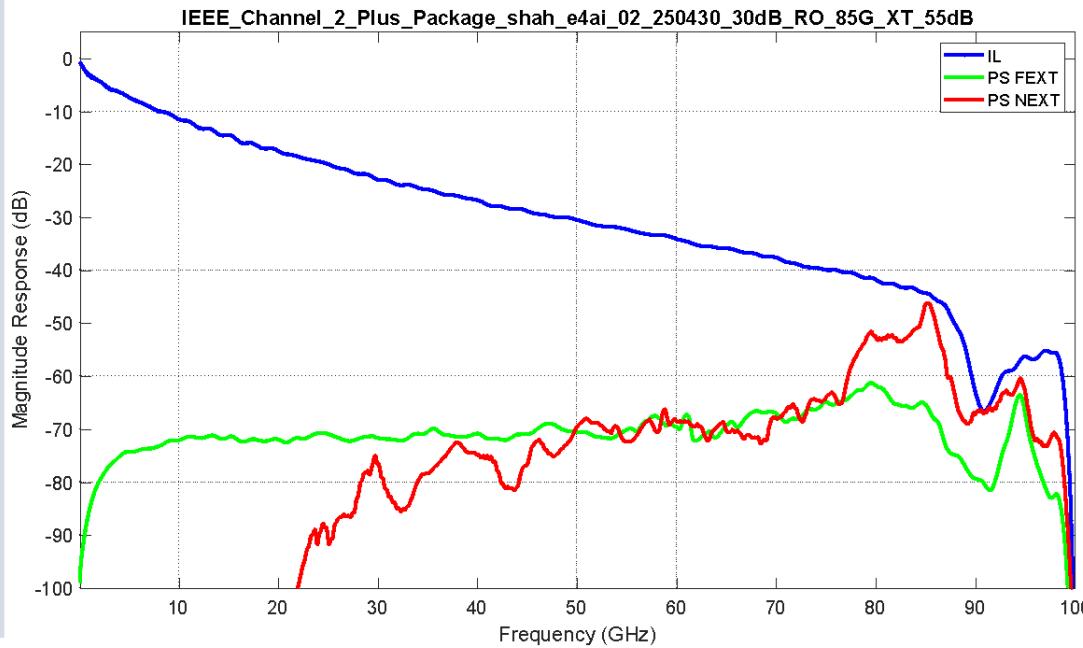
Channel Model Response



Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
Slicer SNR	20.0	20.2	24.3	24.4
SNR Margin (@1e-3)	-0.1	0.1	1.8	1.9
DFE SER	6.9e-3	5.9e-3	1.6e-3	1.2e-3
MLSE SER	6.7e-4	4.8e-4	4.7e-5	3.4e-5

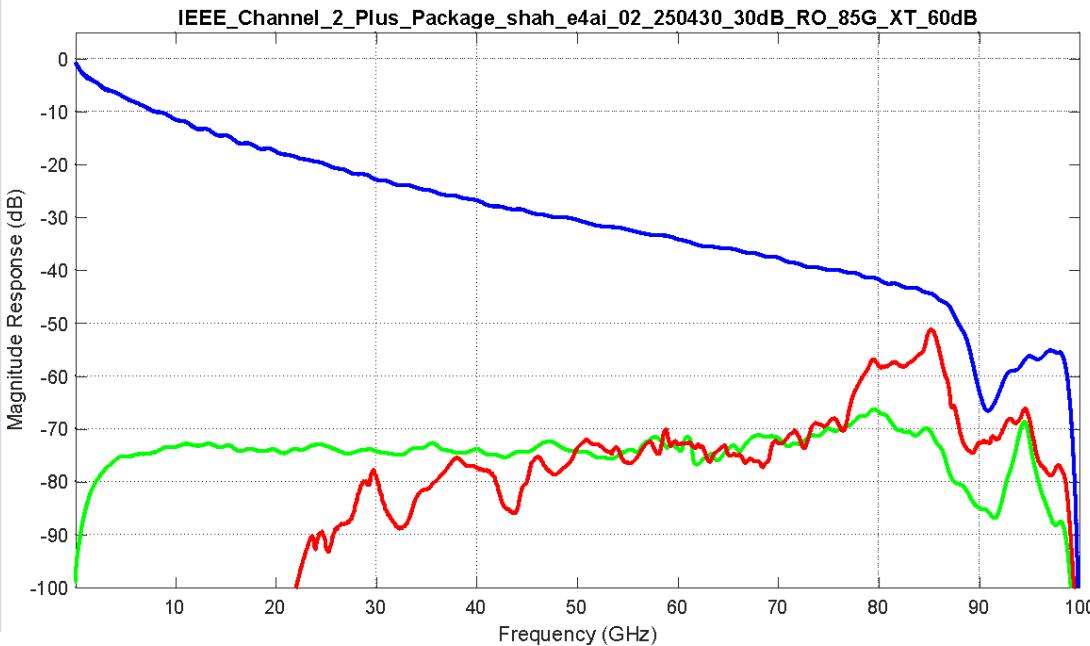
Channel Model Response



Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
Slicer SNR	21.4	21.7	24.9	25.3
SNR Margin (@1e-3)	1.3	1.6	2.4	2.8
DFE SER	2.2e-3	1.7e-3	4.7e-4	1.8e-4
MLSE SER	9.6e-5	9.0e-5	1.6e-5	1.1e-5

Channel Model Response



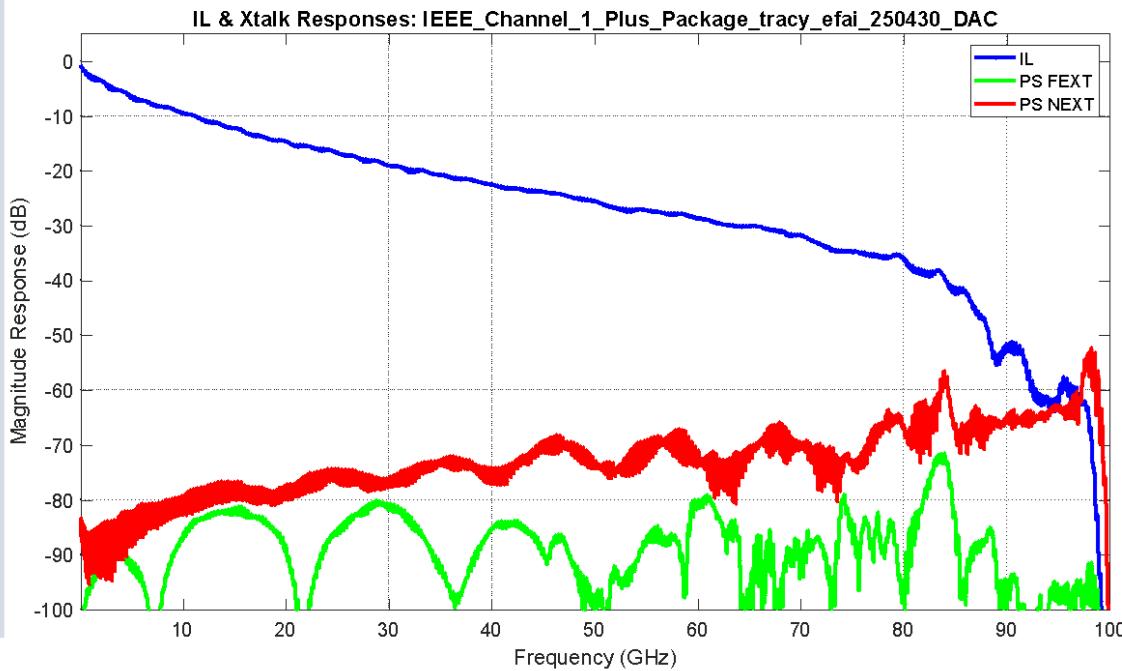
Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
Slicer SNR	21.9	22.3	25.1	25.7
SNR Margin (@1e-3)	1.8	2.2	2.6	3.2
DFE SER	1.5e-3	8.6e-4	3.3e-4	4.8e-5
MLSE SER	5.7e-5	3.0e-5	1.4e-5	7.6e-6

Channel: tracy_efai_250430_DAC + Package + Interposer



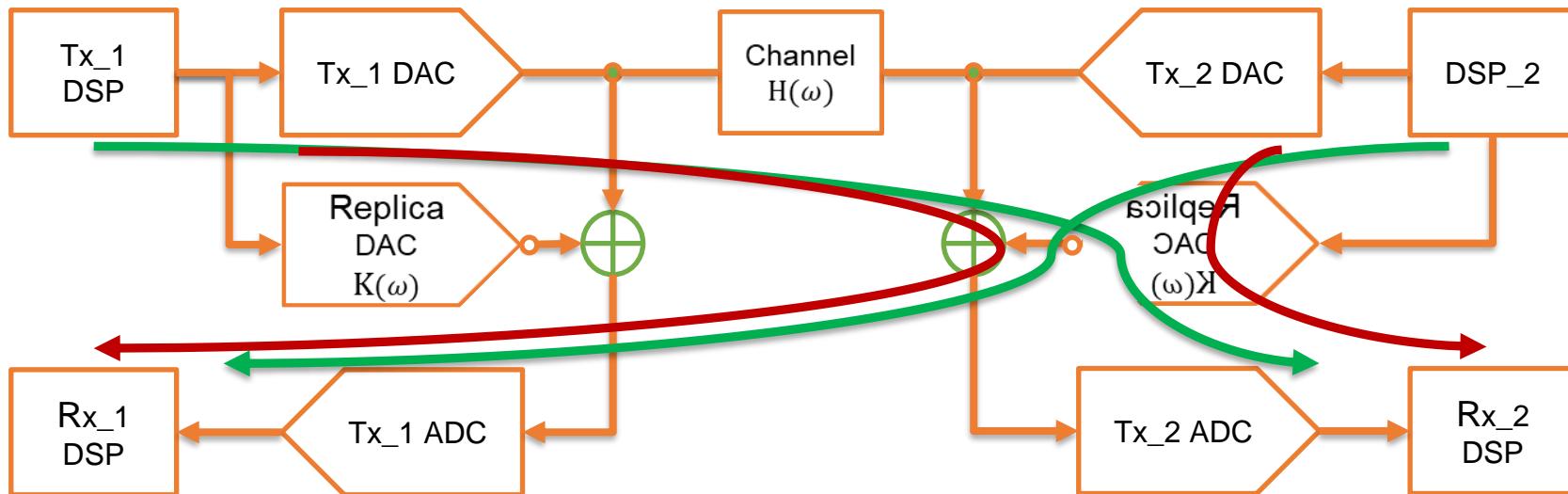
Channel Model Response



Performance Matrix

	PAM-6	PAM-6	PAM-8	PAM-8
Component BWs (GHz)	90	100	75	100
Slicer SNR	22.1	22.2	25.1	25.8
SNR Margin (@1e-3)	2.0	2.1	2.6	3.3
DFE SER	1.1e-3	9.6e-4	2.8e-4	3.1e-5
MLSE SER	2.7e-5	2.3e-5	1.4e-5	8.7e-6

Bidirectional Signaling (2x224G PAM-4)



- Received Signal:

$$rx_1(t) = tx_1(t) * (1 - k(t)) + tx_2(t) * h_{21}(t)$$
- Ideal Hybrid → Only Tx_2 signal remains as if unidirectional transmission
- Not be the case in practice :
- Non-ideal Hybrid
- Additional Reflections from the channel (S_{11}) and other side

- Due to high insertion loss, TX noises limits the performance, unlike RX-limited unidirectional systems

	Pessimistic	Expected	Optimistic
Cancellation Level (dB)	10	20	30
Bandwidth Mismatch (GHz)	10	5	3
SNR Correlation Coeff	0.5	0.7	0.9
Jitter Correlation Coeff	0.5	0.7	0.9
~ Slicer SNR Margin (dB)	-6.4	-3.3	2.1
~ Slicer SNR Margin (dB)	-0.5	1.6	5.0
~ Slicer SNR Margin (dB)	-1.2	1.0	4.6

224G Channel



tracy_efai_250430_DAC + Package



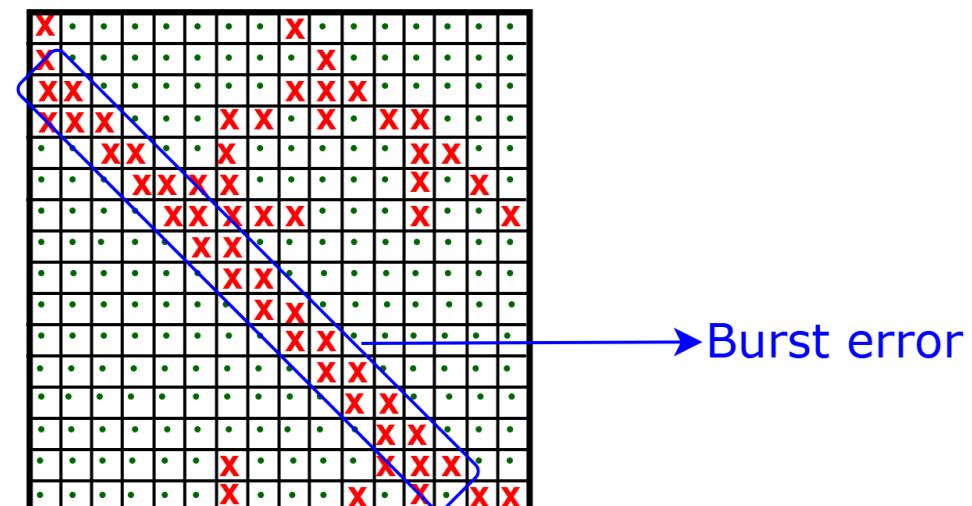
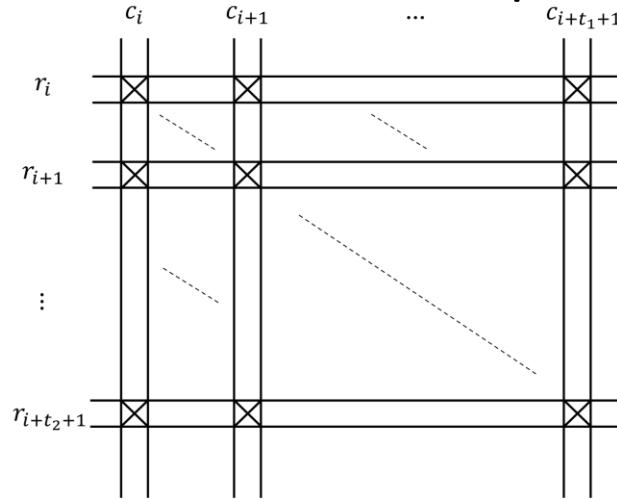
shah_e4ai_02_250430_25dB_RO_85G
XT_60dB+ Package



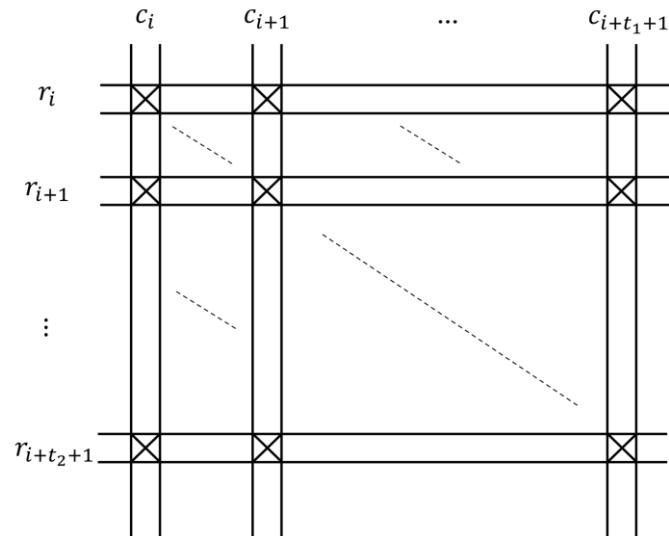
New FEC Proposal



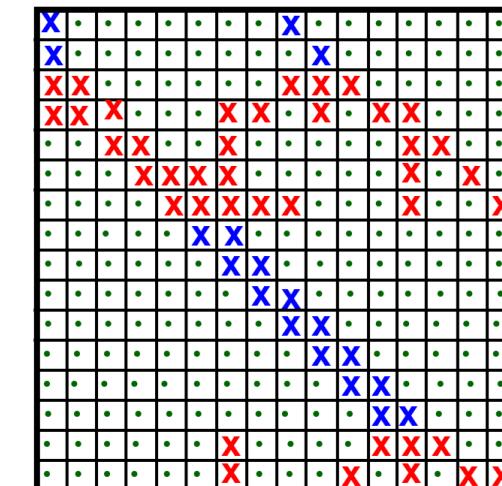
- 2D Codes are both simple and powerful, especially for constructing very long block codes from smaller, more manageable components
- Iterative Decoding
 - Each bit/symbol is encoded by two component codewords
 - Decode rows and columns alternatingly
- Example:
 - Assume a two-error correcting component code
 - A lot more than 2 errors in a row/ column can be corrected by iterative decoding
- Minimum undecable pattern $(t_1+1) \times (t_2+1)$



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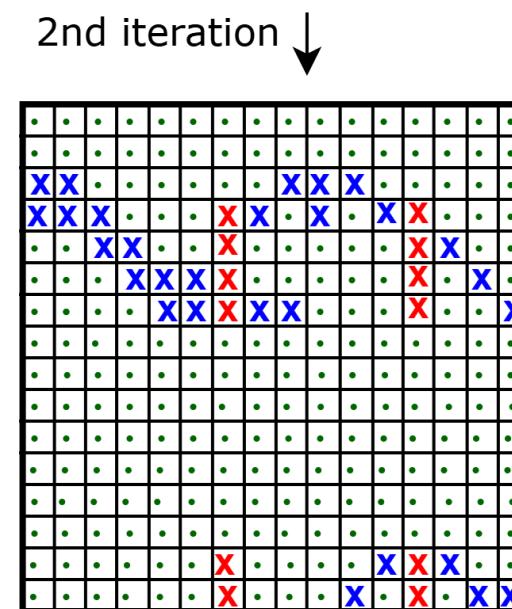
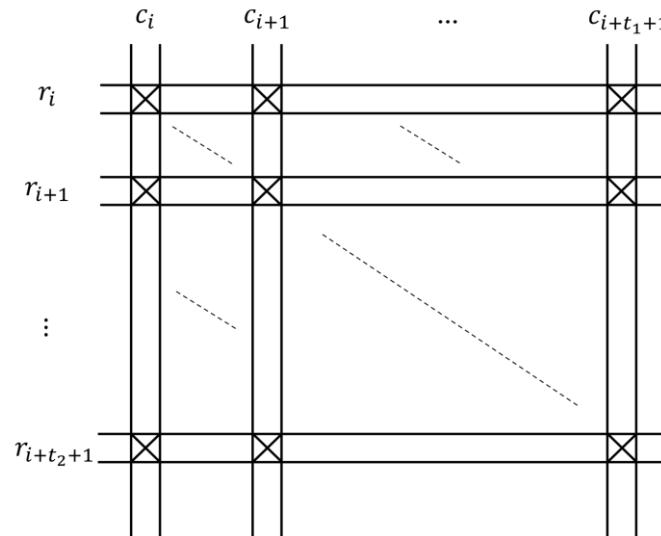
1st iteration →



New FEC Proposal



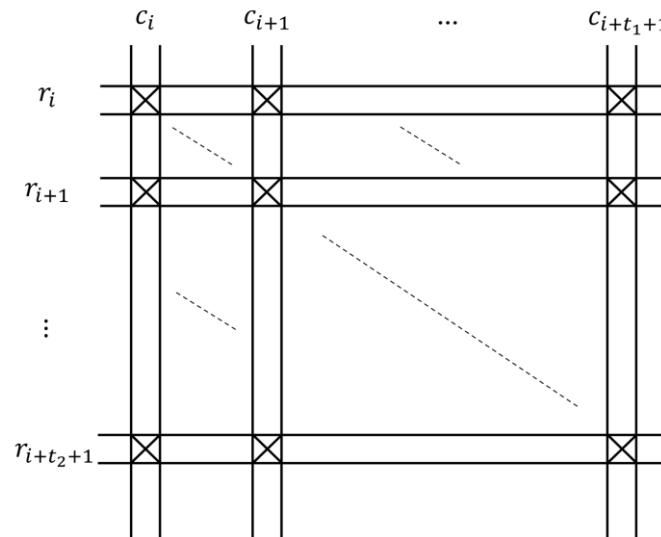
- Iterative Decoding
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- Example:
 - Assume a two-error correcting component code
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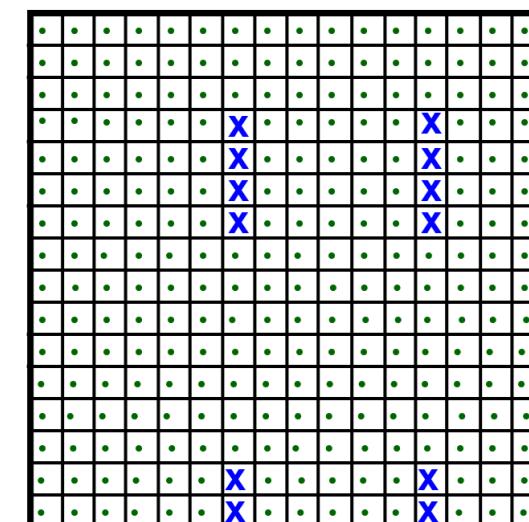
New FEC Proposal



- Iterative Decoding
 - Each bit/symbol is encoded by two component codewords
 - Decode rows and columns alternatingly
- Example:
 - Assume a two-error correcting component code
 - A lot more than 2 errors in a row/ column can be corrected by iterative decoding
- Minimum undecable pattern $(t_1+1) \times (t_2+1)$



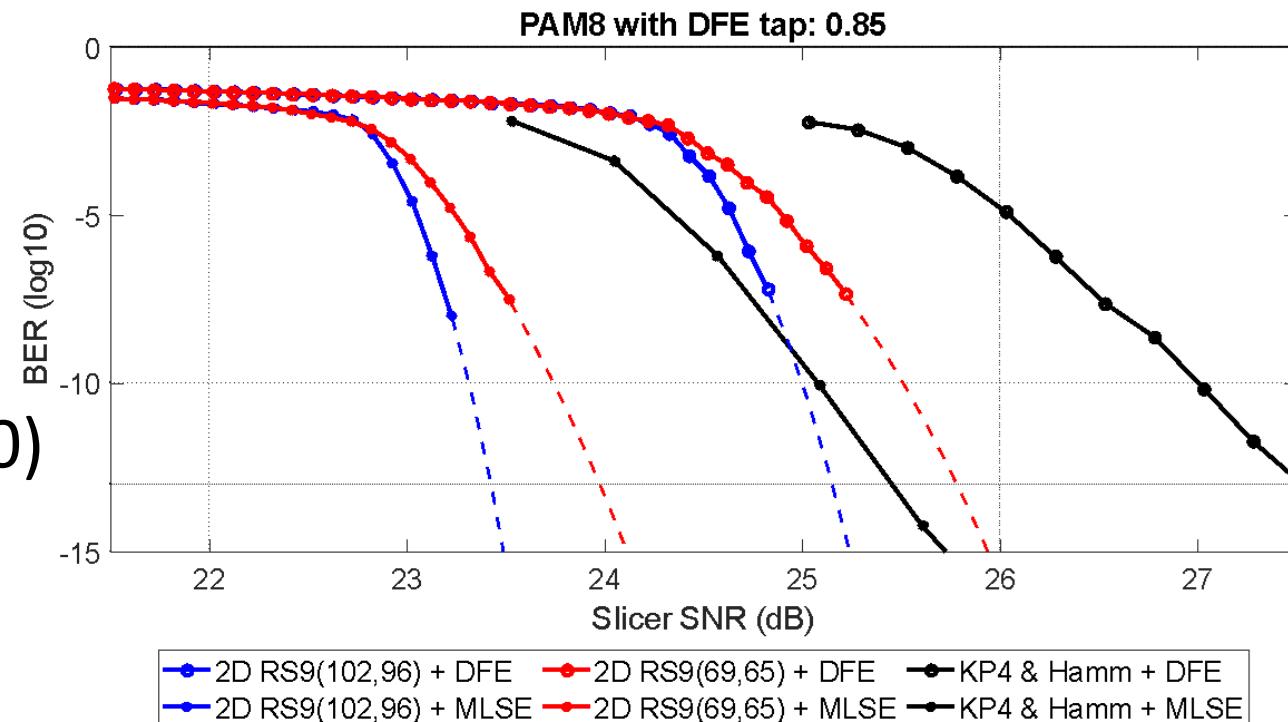
3rd iteration →



New FEC Proposal



- 2D RS FEC : RS Component Codes with $t=2$ or $t=3$
- >1.5 dB gain with RS9(69,65)
>2 dB gain with RS9(102,96) with respect to RS10(544,514)+Ham.(128,120) (KP4+Hamming)



Complexity and Latency Analysis



- Total Complexity and Latency of some 2D-RS codes at 1.6T PCS wrt KP4

	RS9(69,65)		RS9(102,96)	RS10(544,514) – KP4 (+Hamming)
	Lower Complexity (8 iterations)	Lower Latency (6 iterations)		
Overhead (OH)		%12.68	%12.89	%5.84 (%12.89)
Total LUT Utilization(FPGA)	100 K	181K	171K	171K ^(*)
Total Latency(ns)	339.8	201	673.3	83.2 ^(*)
SNR Gain wrt (KP4+Hamming) @ 10^{-15} BER	1.8	1.7	2.3	0

(*)Additional complexity & latency due to Hamming Code

- High latency due to iterations can be decreased with further optimizations such as:
 - Increase the complexity to a level equivalent to current KP4 for 2D-RS codes
 - Incremental computation of syndromes for subsequent iterations
 - Number of iterations can be decreased with marginal performance penalty

- With the current package and channel models PAM6, PAM8 or bidirectional are feasible options
 - Bidirectional need more analog models for hybrid subtractor
- Need more improvement on channel and xtalks
 - Need more package models
- FEC with more coding gain than KP4(+Hamming) => 2D RS Codes
 - Minimal additional latency: > 1.5 dB coding gain
 - Same complexity: >2 dB coding gain
- Working on alternative decoding strategies for 2D RS codes to lower complexity

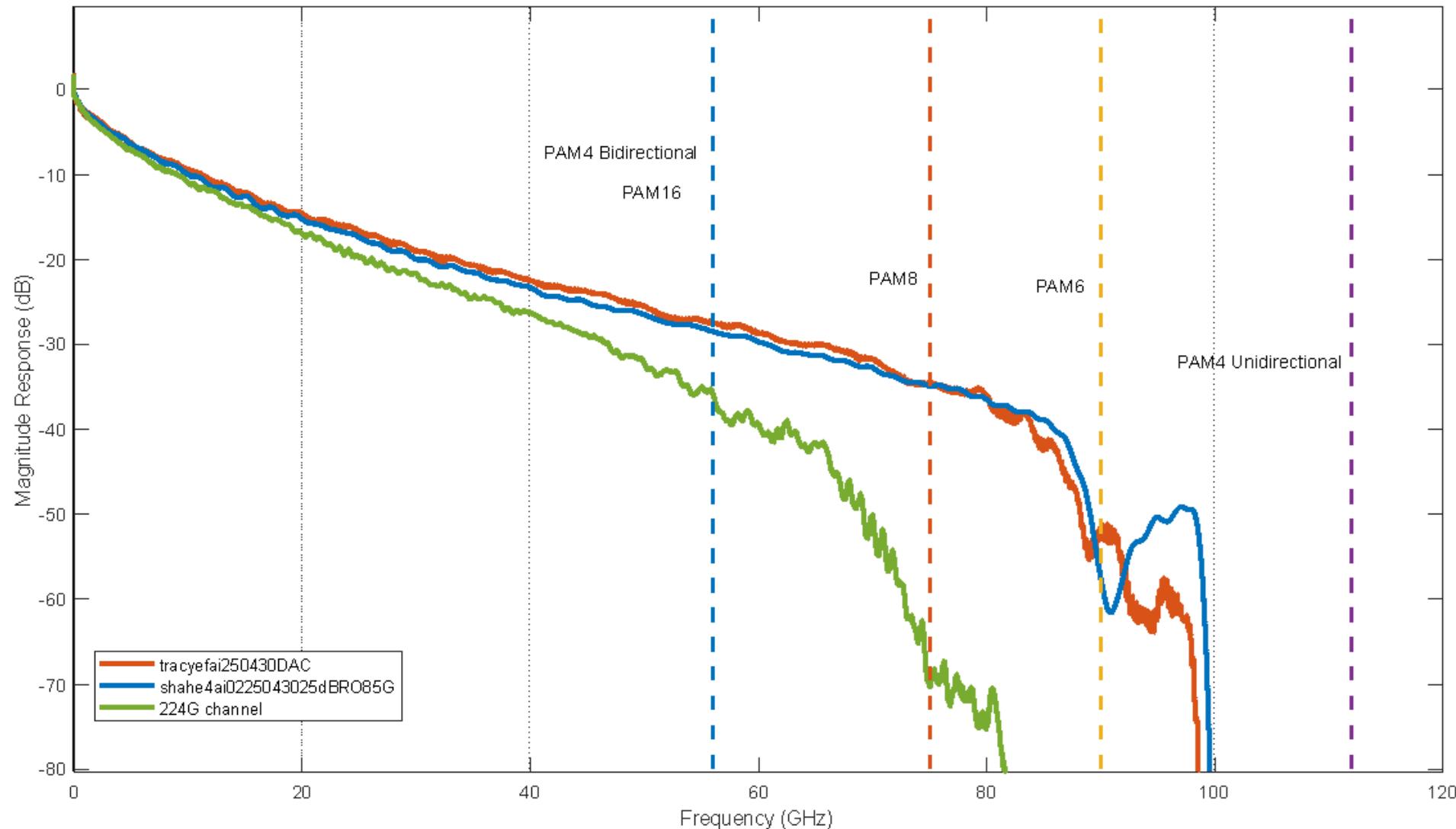
Thank You!



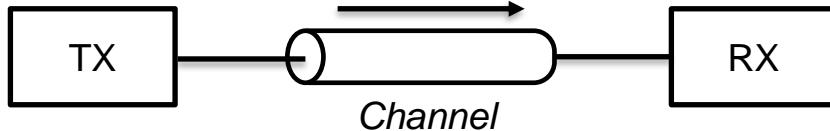
Reserved Slides



Channels

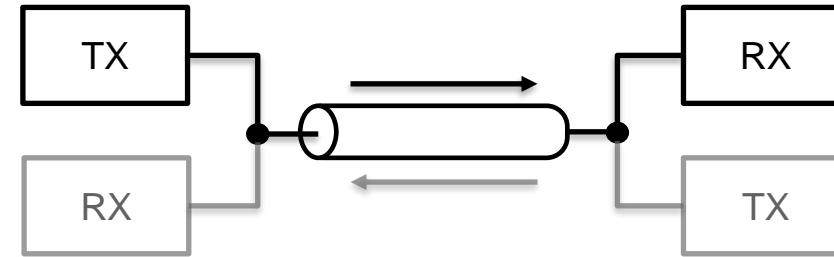


Communication Topologies



Uni-Directional Transmission

- Higher Bandwidth
 - Higher Insertion Loss
 - Increased Crosstalk Interference
- Higher Modulation Order
 - Increased SNR Penalty
- One-Way Communication
 - Simple RX Design
 - More Signal Power



Simultaneous Bi-Directional Transmission

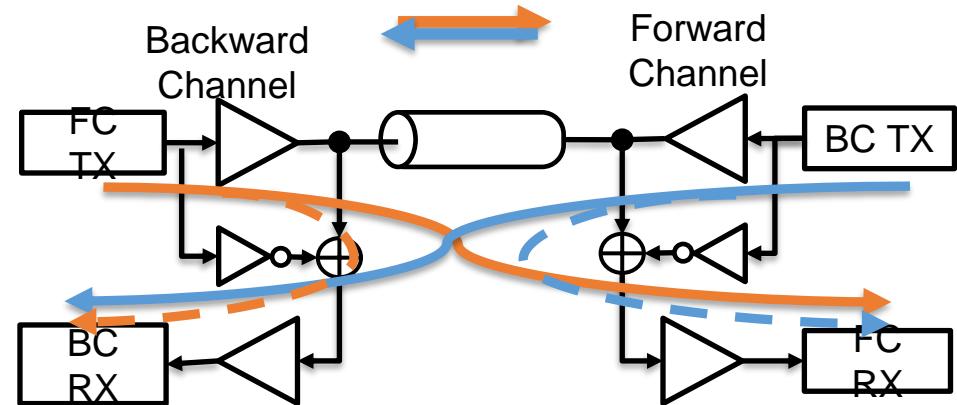
- Same Bandwidth
 - No Extra Loss
 - No Extra Crosstalk Interference
- Same Modulation Order
 - Same SNR Requirements
- Two-Way Communication
 - Complex RX Design with additional components
 - Very high interference

Channel Model and Additional Components

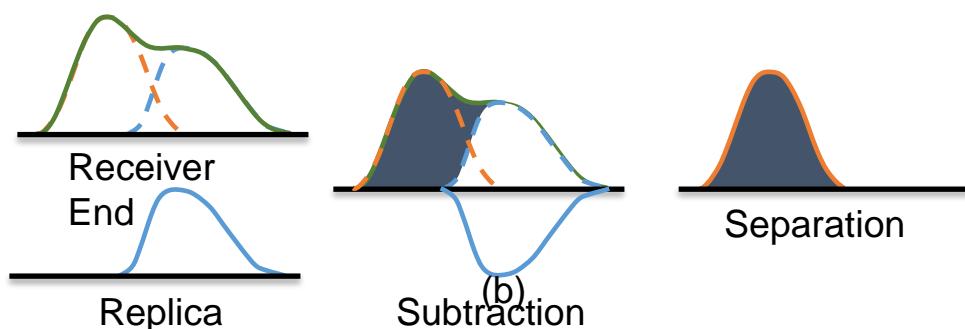


Major Differences over Uni-Directional Channel

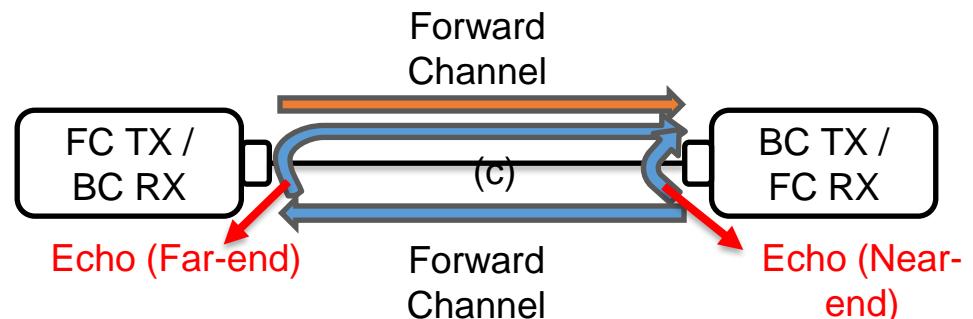
- Overlap of Desired Inbound Signal and Very Strong Outbound Signal: Figure (a)
 - Solution: Hybrid Circuitry for cancellation by subtraction of overlapped signal: Figure (b)
 - To utilize dynamic range of ADC better
 - Requires a Replica Driver
- Echoes of Outbound Signal: Figure (c)
 - Analog Echo Cancellation (AEC)
 - Strong Near-End Echo ($\propto S_{11}$ of Channel)
 - Digital Echo Cancellation (DEC)
 - Weak Far-End Echo ($\propto S_{12} \& S_{21}$ of Channel)



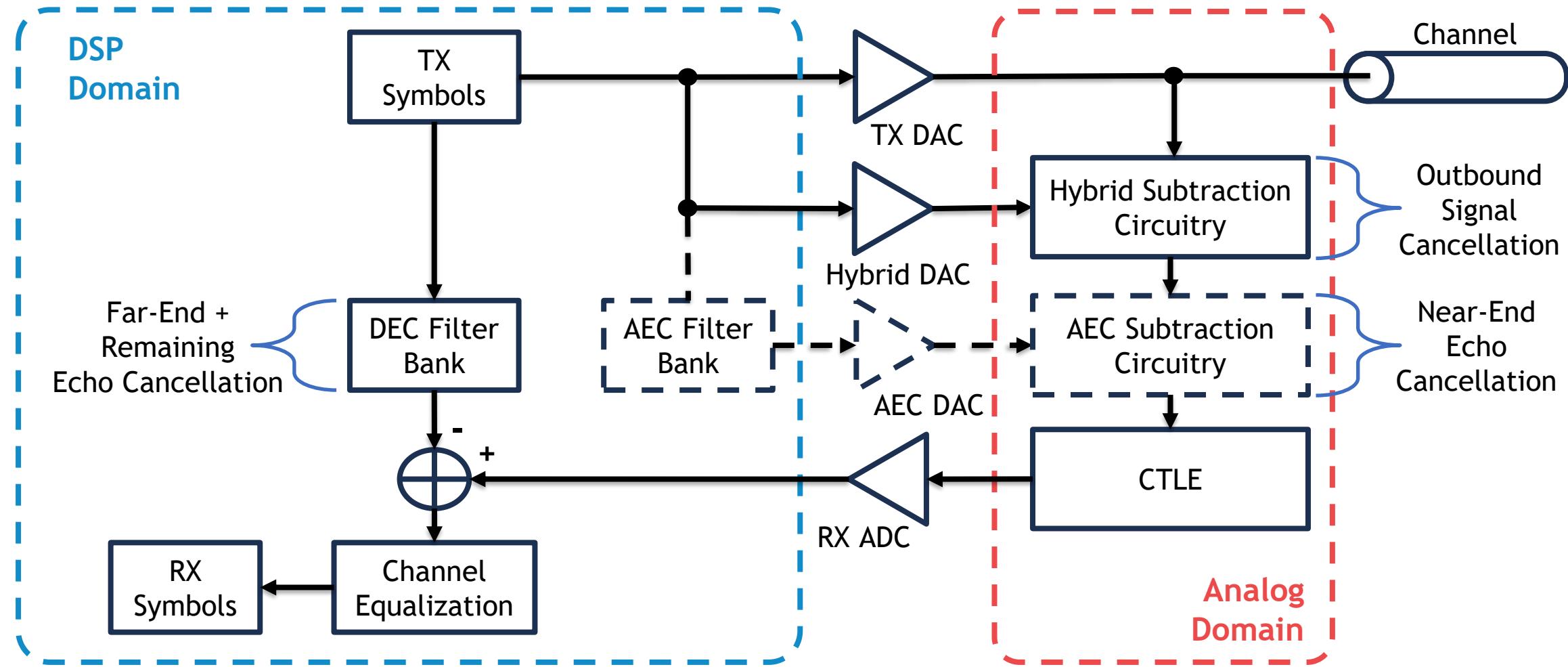
(a)



(b) Subtraction



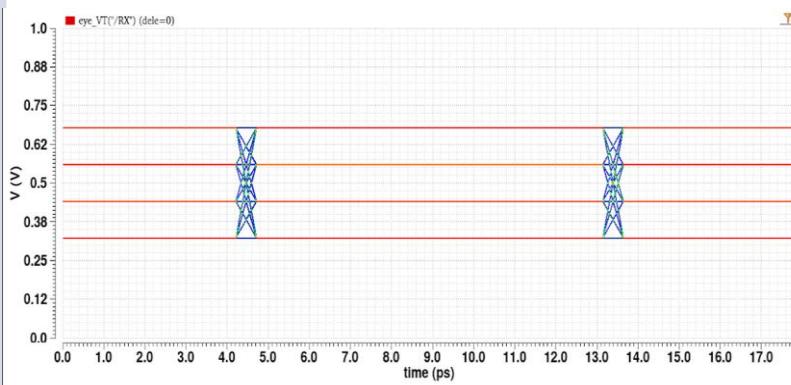
Simple Block Diagram of SBT (Single Side)



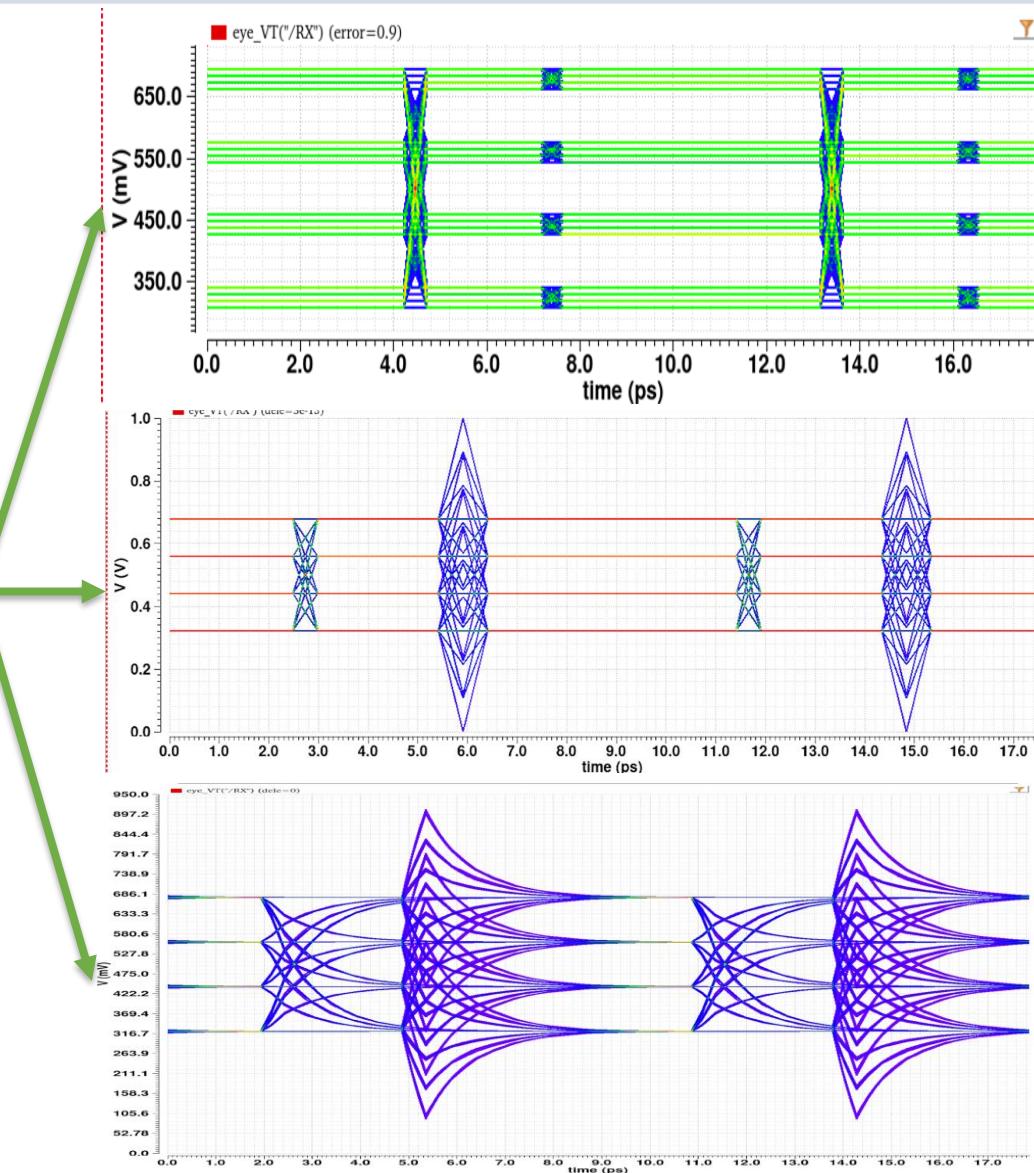
TX - Replica Imperfections



Eye Diagram of Perfectly Matched Replica and Tx DAC



There will be additional insertion loss depending on the Hybrid design!



1. Gain Mismatch
 - Commonmode Changes
 - Can be easily calibrated
2. Phase Mismatch
 - Degrades eye performance
 - Calibration required
3. Bandwidth Mismatch
 - Same effect on eye as phase mismatch
 - Broadband calibration required