# **PoDL PD V**on, **V**off, and **R**Loop **Specifications**

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## **D1.0** V<sub>on</sub> and V<sub>off</sub> Specifications

• The current  $V_{on}$  and  $V_{off}$  specifications are written as an equation based on both the power of the PD and the loop resistance.

The PD shall turn on at a voltage greater than  $V_{on(min)}$  which is the maximum of 4V or  $\sqrt{7.2P_{PD}R_{Loop}}$ .

The PD shall turn off at a voltage no less than  $V_{off(min)}$  which is the maximum of 3.75V or  $\sqrt{4PPDRLoop}$ .

- This requires that the PD controller know both the power it will draw and the loop resistance.
  - This would be very expensive to implement, particularly for PDs in systems that do not implement SCCP.
- In addition, the R<sub>Loop</sub>(max) values currently listed in Table 104-1 result in turn on voltages that are higher than V<sub>PSE</sub>(min).



# Example D1.0 Specification: Class I (12V)

- Plot shows  $V_{on}$  and  $V_{off}$  as a function of  $R_{Loop}$  for values of  $R_{Loop}$  less than or equal to  $R_{Loop}(max)$
- Note that V<sub>on</sub> is higher than V<sub>PSE</sub>(min) for R<sub>Loop</sub> values greater than ~5.5Ω.
- Also note that the minimum V<sub>off</sub> requirement is exactly the minimum requirement for system stability.
- Furthermore, the PD voltage actually intersects this curve when R<sub>Loop</sub> = R<sub>Loop</sub>(max).
- The minimum V<sub>on</sub> curve provides ~34% margin over the stability requirements.
- All of the classes listed in Table 104-1 have analogous graphs (see Appendix).





## What Specifications Make Sense?

- From an implementer's perspective, fixed numbers would be preferred.
- We should include a maximum turn on voltage that guarantees the PD will turn on below V<sub>PSE</sub>(min).
- We should include a minimum turn off voltage that guarantees system stability.
  - The turn off voltage also acts as a minimum turn on voltage.
- Since PoDL has different voltage classes, different specifications will be needed for each PSE voltage class.
  - Specifications should be kept constant across different classes that use the same voltage range.
- The difference between maximum turn on voltage and minimum turn off voltage should allow room for significant hysteresis.
  - Startup behavior should be investigated to make sure hiccups are avoided.
  - Specs affecting startup behavior need to be defined (e.g. dv/dt for PSE).
  - R<sub>Loop</sub>(max) may need to be reduced in order to allow for more hysteresis.



# **Example of Proposed Specification**

- Plot shows existing specifications and an example of the proposed specifications for the Class I (12V).
- The PD must turn on by V<sub>on</sub>(max) when the voltage is rising. This example is 5% lower than V<sub>PSE</sub> (min).
- The PD must turn off by V<sub>off</sub>(min) when the voltage is falling. This example is 5% higher than the stability point.





## **The Proposal**

- Replace PD  $V_{on}$  and  $V_{off}$  specifications that are currently stated as equations and apply to all voltage classes with:
  - A maximum V<sub>on</sub> specification for each voltage class.
  - A minimum V<sub>off</sub> specification for each voltage class.
  - All specifications shall be TBD until the level of hysteresis needed is determined.

							Additional
Item	Paramter	Symbol	Unit	Min	Max	PD Type	Information
4a	Maximum power supply turn on voltage (12V Classes)				TBD		
4b	Maximum power supply turn on voltage (24V Classes)	Von(max)	V		TBD		
4c	Maximum power supply turn on voltage (48V Classes)				TBD		
5a	Minimum power supply turn off voltage (12V Classes)			TBD			
5b	Minimum power supply turn off voltage (24V Classes)	Voff(max)	V	TBD			
5c	Minimum power supply turn off voltage (48V Classes)			TBD			



## **Summary**

- The current specifications for PD  $V_{\text{on}}$  and  $V_{\text{off}}$  voltages are written in a way that:
  - is hard for implementers to understand.
  - is hard to implement.
  - would lead to interoperability problems.
- We should rewrite the  $V_{on}$  and  $V_{off}$  specifications so that they are easier to understand and implement.
  - Use constant values as opposed to equations.
  - Include both a maximum  $V_{on}$  and a minimum  $V_{off}$ .
  - These values will need to be different for each supply voltage.
- Startup behavior for PoDL systems needs to be studied in order to determine the amount of hysteresis needed between  $V_{on}$  and  $V_{off}$ .
  - All  $V_{on}$  and  $V_{off}$  values should by TBD until this work is completed.



# **Appendix: Other Class Plots**



### **Example of Proposed Specification:** Class II (12V)





## Example of Proposed Specification: Class II (24V)





## Example of Proposed Specification: Class III (24V)





## Example of Proposed Specification: Class III (48V)





### **Example of Proposed Specification:** Class IV (48V)





### **Example of Proposed Specification:** Class V (48V)



