#### Motions and Straw Polls

# IEEE P802.3ch Multi-Gig Automotive Ethernet Task Force

Steve Carlson, Chair

High Speed Design, Inc., Robert Bosch

Geneva, CH, January 25-26, 2018

- Move to approve the agenda as shown in <u>agenda 3ch 01b 0118.pdf</u>
- M: Brett McClellan
- S: Sujan Pandey
- Approved by voice without opposition (Procedural > 50%)
- Motion Passes

- Move to approve the minutes of the November 2017 IEEE P802.3ch Multi-Gigabit Automotive Ethernet PHY Task Force Meeting.
- M: Brett McClellan
- S: Sujan Pandey
- Approved by voice without opposition (Procedural > 50%)
- Motion Passes

- Move to adopt the "Blue Limit Line" equation as shown on page 3 of Farjad\_3ch\_01\_0118.pdf as the insertion loss specification for all 3 speeds for frequencies from 5 MHz to 5.5 GHz.
- M: Natalie Wienckowski
- S: Gerrit den Besten
- (Technical >= 75%)
- Y: 23 N: 2 A: 8
- Motion Passes

- Move to adopt the return loss limit line equation as shown on slide 8 of Farjad\_3ch\_01b\_0118.pdf as the return loss specification for all 3 speeds.
- M: Gerrit den Besten
- S: Ramin Farjadrad
- Y: 18 N: 0 A: 4
- Motion Passes (Technical >= 75%)

- Move to instruct the Chief Editor to create D0.2 from D0.1 and adopted baseline from motions in the January Interim.
- M: Natalie Wienckowski
- S: Gerrit den Besten
- Approved by voice without opposition (Procedural > 50%)
- Motion Passes

Choose one:

A: Blue Curve

**B:** Gold Curve

A: 11 B: 8

Chicago Rules:

A: Blue Curve at 105C as the insertion loss limit line

B: Gold Curve at 105C as the insertion loss limit line

C: Neither

A: 9B: 15 C: 1

Chicago Rules: I would oppose

A: Blue Curve at 105C as the insertion loss limit line

B: Gold Curve at 105C as the insertion loss limit line

A: 2B:6

I am likely to attend 802.3ch at:

Attend March 2018 802 Rosemont, IL plenary:

Y: 22 N: 4 M: 6

Attend May 2018 interim, EA, Pittsburgh, PA, USA:

Y: 14 N: 1 M: 13

- To adjourn the meeting.
- M: Olaf Krieger
- S: Matthias Fritsche
- Approved by voice without opposition (Procedural > 50%)
- Motion Passes

# Thank You!