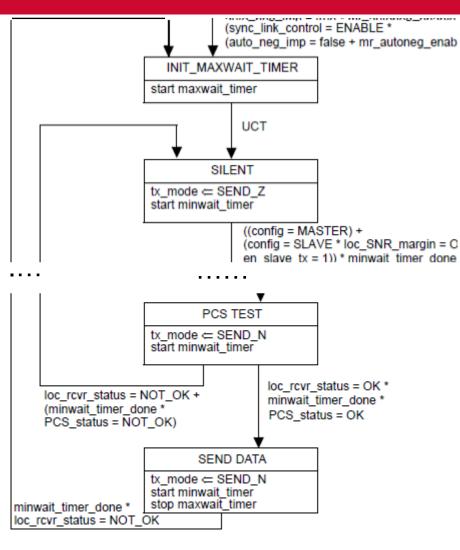
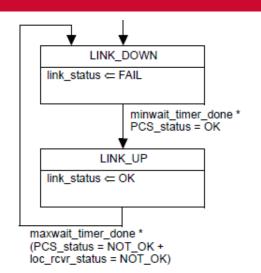
### **Issues in D1.1 State Diagrams**

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# Figure 149-31 SEND\_DATA and Figure 149-32 LINK\_UP

- PHYC enters SEND\_DATA state, with maxwait timer not yet expired
   maxwait timer stopped
- Link monitor enters LINK\_UP state
  - link\_status <= OK</p>
- Assume loc\_rcvr\_staus drops when PHYC minwait\_timer expires
  - PHYC exits SEND\_DATA and goes to INIT\_MAXWAIT\_TIMER, then to SILENT
- Link monitor unable to exit LINK\_UP state, as maxwait\_timer already stopped, so never expires
  - link\_status stays OK although PHYC went back to redo PAM2 training
- One work-around is to add the watchdog\_status which monitors the line becoming SILENT
  - Add watchdog\_status to the exit condition from the LINK\_UP state, as shown in page 2 of Lo 3ch 01 0319.pdf.

### On "PCS\_status"

- hi\_rfer
  - Figure 97-13 was proposed as RFER monitor state diagram for 802.3ch (comment #101 and #221).
  - In Figure 97-13, hi\_rfer is initialized to false after either PCS reset or block\_lock=false
- block\_lock
  - Page 97 line 39: "...as well as an InfoField, which is inserted in the 16th PCS partial PHY frame. When the PCS Synchronization process is synchronized to this pattern, block\_lock is asserted."
  - So block\_lock will be asserted while still in PAM2 training
- PCS\_status
  - D1.1, page 107 line 47
  - Indicates whether the PCS is in a fully operational state. It is only true if block\_lock is true and hi\_rfer is false.
- Therefore the PCS\_status will get set during PAM2 training mode according to D1.1.
- One solution is to set hi\_rfer<=true by default
- Another way is to define PCS\_status differently

#### **Comments from George**

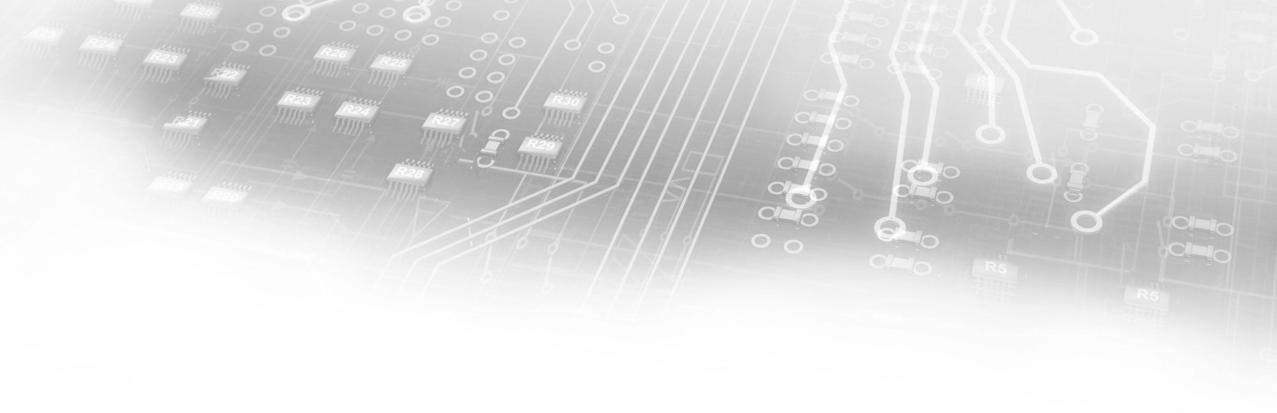
- Mike at first, I thought you may have uncovered a VERY old problem on slide 2, that EVERY BASE-T PHY since 100BASE-T2 has carried forward (yes, the same relationship of maxwait\_timer\_done to the phy control and link monitor diagrams is present in 100BASE-T2, 1000BASE-T, 10GBASE-T, 2.5G/5GBASE-T, 25GBASE-T, 40GBASE-T, and 100BASE-T1).
- They all stop maxwait\_timer upon reaching data (or idle) transmission, and they all rely on maxwait\_timer\_done as a condition going from link\_up to link\_fail. They all have an identical structure.
- Adding a 'watchdog' is not the way to fix this, if it is, in fact, a problem. Changing the maxwait\_timer\_done for something else on the link monitor might be better – IF anything needs to be done. I'm not sure it does, but I'm not entirely sure that it does. Here's what it looks like happens from the state diagrams (which doesn't agree with my memory):
- The maxwait timer will not be done when the phy successfully trains. Entry to the data (or idle) state stops
  maxwait\_timer. If maxwait\_timer\_done is true, the PHY has failed to train. Link goes down, link fail inhibit dies with
  it.
- BUT, reading the state diagrams (again, I think implementations might be different) all of these phys, according to the state diagrams have hysteresis in their link state which seems to allow a retrain attempt. If the local receiver status drops to FAIL in the data or idle state will attempt a retrain, first resetting maxwait\_timer (a "start timer" always resets the timer). They return to the training state in PHY control where maxwait\_timer is started. In 802.3ch this is INIT\_MAXWAIT\_TIMER. If data mode is established without maxwait\_timer expiring, no problem. Link stays up. If not, they drop link, and autoneg starts again.
- On the one hand, this seems to make sure you don't have to re-autoneg if you don't need it, but again, not sure this
  is what really happens I would have thought link would drop.
- I've asked UNH if my interpretation above is correct because it seems weird.

#### **Comments from George (cont.)**

- On high\_rfer, I wouldn't want to set it true by default. That is indicating an error condition that shouldn't happen. I suggest defining pcs\_status to be:
- Pcs\_status = block\_lock \* (!hi\_rfer) \* (txmode = SEND\_N)
- That way, PCS\_status is what it says it is:
- The parameter pcs\_status conveys to the PMA Receive function the information that the PCS is operating reliably in the data mode.

#### **Comments from William**

- For issue #1 simply remove stop maxwait\_timer from the SEND DATA state. This
  is what is done in 1000BASE-T1.
- I'm ambivalent about the watchdog. I made a comment on that in case we want to adopt it but I'm also ok not having it.
- For issue #2 I think we can redefine PCS\_status by adding one more condition and that is the PCS datapath is decoding properly.
- I don't like the solution to set hi\_rfer to default to true since it may have other side effects like setting registers.



## THANK YOU

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