

# COM 2.51 with rxFFE updates

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Experimental Features

- Modification in diagram
- Vector forcing DFE/RxFFE
- Algorithm to compute tap for a long FFE

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Computing HH, sampled ISI matrix

# COM 2.51 may be used to investigate 2 Signal Architectures

- ❑ Zero Forced DFE (Annex 93A) ... No change
- ❑ One DFE tap and a number of (Rx)FFE taps
  - FFE tap adjustments, algorithm modifications, and index corrections added for COM 2.51

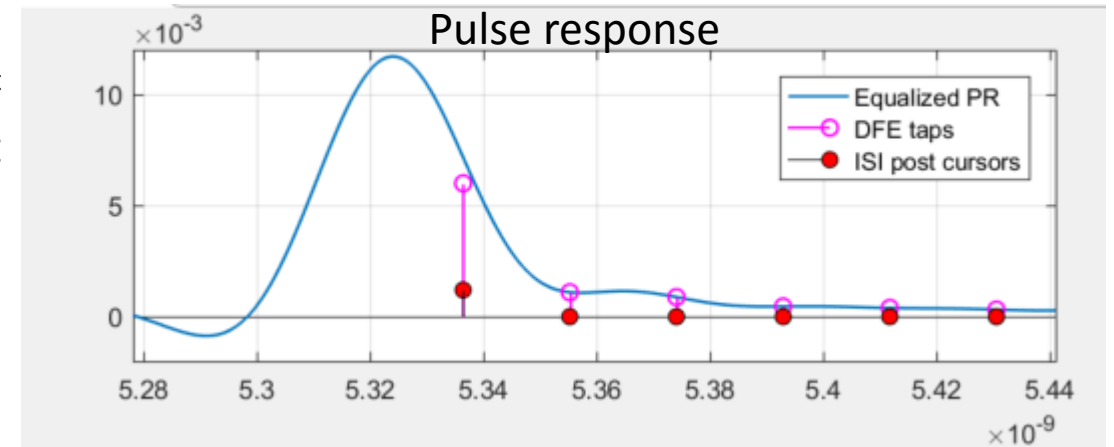
# Zero Forced DFE (Annex 93A) ... No change

- ❑ Same as Clause 93A COM
- ❑ Review presented in mellitz\_3ck\_01\_0718 (slide 5)

Example where 1<sup>st</sup>  
DFE tap reach limit  
creating ISI noise

$$FOM = 10\log_{10}\left(\frac{A_s^2}{\sigma_{TX}^2 + \sigma_{ISI}^2 + \sigma_J^2 + \sigma_{XT}^2 + \sigma_N^2}\right) \quad (93A-36)$$

The FOM is calculated for each permitted combination of  $c(-1)$ ,  $c(1)$ , and  $g_{DC}$  values per Table 93A-1. The combination of values that maximizes the FOM, including the corresponding value of  $t_{tr}$ , is used for the calculation of the interference and noise amplitude in 93A.1.7 and the calculation of COM in 93A.1.



[http://www.ieee802.org/3/ck/public/18\\_07/mellitz\\_3ck\\_01\\_0718.pdf](http://www.ieee802.org/3/ck/public/18_07/mellitz_3ck_01_0718.pdf)

# One DFE tap and a number of (Rx)FFE taps

- ❑ Vector forcing algorithm to determine equalization settings
- ❑ Review presented in mellitz\_3ck\_01\_0718 (slide 5)
- ❑ Does not necessarily resemble a receiver

# Evaluation COM reference Model with Rx FFE

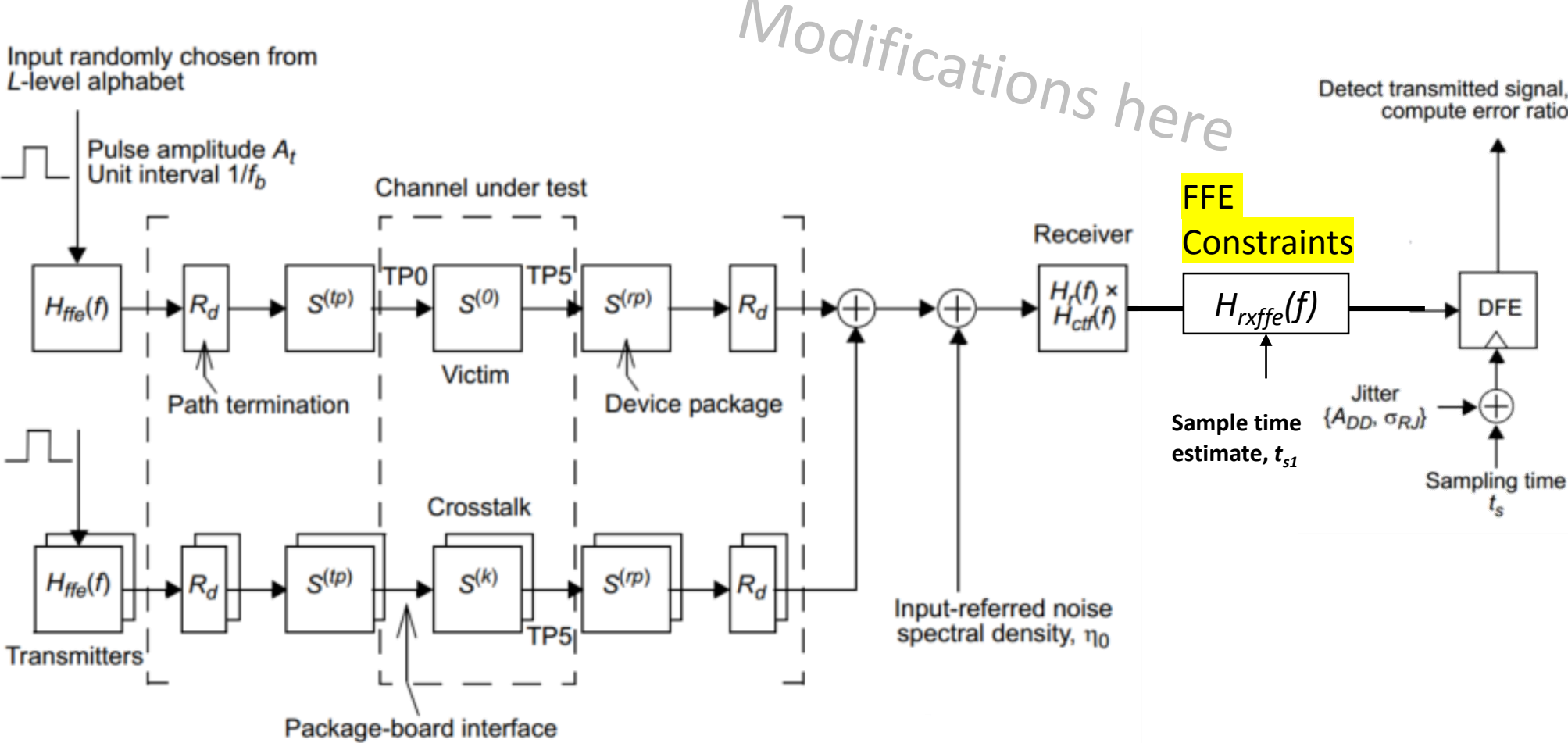


Figure 93A-1—COM reference model

\* [http://www.ieee802.org/3/ck/public/18\\_07/mellitz\\_3ck\\_01\\_0718.pdf](http://www.ieee802.org/3/ck/public/18_07/mellitz_3ck_01_0718.pdf)

# COM is based on the pulse response (Annex 93A)

- Thru (ISI) channel response is  $h^{(0)}(t)$  i.e. the pulse response

The pulse response  $h^{(k)}(t)$  is derived from the voltage transfer function  $H^{(k)}(f)$  (see 93A.1.4) using Equation (93A-24).

$$h^{(k)}(t) = \int_{-\infty}^{\infty} X(f)H^{(k)}(f)\exp(j2\pi ft)dt$$

- The following uses pulse response plots to describe COM equalization
- Best FOM for full grid searching for all ctf and Tx ffe values determines setting for the ctf and Tx FFE to compute COM

# Adding the long FFE with DFE in COM 2.51

Same full grid as for zero forced DFE except compute C, Hisi, and FOM for each grid setting

- ❑ Find the Rx FFE taps settings, C , with LMS vector force method
- ❑ Readjust sample point
- ❑ Apply C to form a new Hisi to be used to compute a the FOM
- ❑ Settings with be best FOM are used to compute COM

Next... how to find C

Same as  
mellitz\_3ck\_01\_0718



# Determining FFE taps, C within the inside loop

□  $C = (HH^T * HH^{-1} * HH^T)^T * FV^T$

- C are the Rx FFE taps
- HH is derived from  $h^{(0)}(t)$
- HH is shifted sampled ISI matrix

□ FV is the forcing vector ,

- $FV = [\dots, 0, 0, FV0, FV1, 0, 0, 0, 0 \dots]$

□ FV for the cursor tap is

- $FV0 = h^{(0)}(t_s)$
- This forces the cursor tap to 1

☞ Modified from mellitz\_3ck\_01\_0718:

FV for the post cursor tap ( $\bar{2.5I}$  update)

- $FV1 = \text{sign}(h^{(0)}(t_s + T_b)) \min(|h^{(0)}(t_s + T_b)|, |b_1 h^{(0)}(t_s + T_b)|)$
- This makes sure the  $b_1$  is not violated for the DFE

□  $h_{fferx}(f)$  is computed from the C found as in eq 93A-21

# NEW: Adjust C with an inside loop

- ❑  $H_{isi}$  is the resampled (1 UI or  $T_b$  spaced) pulse response
- ❑ Apply the Rx FFE with tap values C to  $H_{isi}$ 
  - Shift, multiply add method
  - This creates  $H_{isi\_filtered}$  (filtered pulse response)
- ❑ Determine an interim FOM for  $H_{isi\_filtered}$  by dividing the cursor value by the root sum square (RSS) of all the other values and converting to dB
- ❑ Incrementally zero out C taps starting with last tap, and compute a new  $H_{isi\_filtered}$  and FOM. The code only goes back 4 taps now
- ❑ Use the C with best interim FOM
- ❑ Continue with the grid loop to determine FOM with eq. 93A-36

# Additional Inner loop constraints and settings for evaluation

ffe_pre_tap_len	<b>3</b>
ffe_post_tap_len	<b>16</b>

If both set to zero Rx FFE computation is eliminated and default back to original COM method

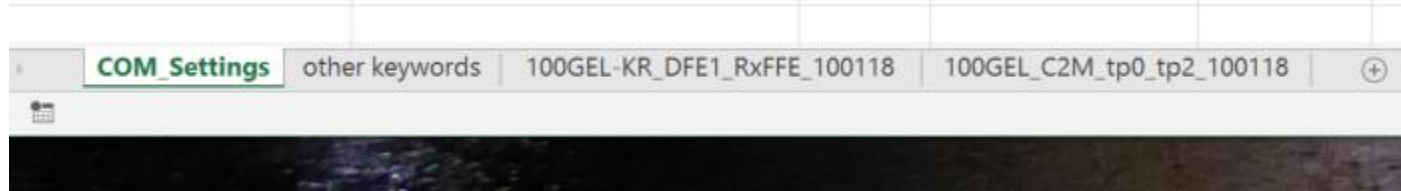
ffe_tap_step_size	0.01
ffe_main_cursor_min	0.7
ffe_pre_tap1_max	0.3
ffe_post_tap1_max	0.3
ffe_tapn_max	0.125

If set to zero, taps are not quantized

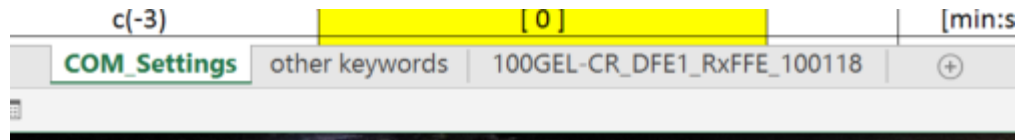
These just break the loop for now.

# Included in ZIP

❑ config\_com\_ieee8023\_93a=100GEL-CR\_DFE\_100118.xls



❑ config\_com\_ieee8023\_93a=100GEL-KR\_DFE\_100118.xls



❑ com\_ieee8023\_93a\_251.m

Backup: Computing HH,  
shifted sampled ISI matrix

# Start with Pulse Response, and Resample

Let the pulse response be  $h^{(0)}(t)$  by

Apply  $H_r(f)$ ,  $H_t(f)$ ,  $H_{\text{CFT}}(f)$  and  $H_{\text{FFE}}(f)$  setting to  $H_{21}^{(0)}(f)$

Find sample point  $t_s$  and resample as  $\text{hisi}(n)$

Example pulse response for 20 UI

```
hisi=[ hisi1, hisi2, hisi3, hisi4, hisi5, hisi6, hisi7, hisi8, hisi9, hisi10,  
hisi11, hisi12, hisi13, hisi14, hisi15, hisi16, hisi17, hisi18, hisi19, hisi20]
```

Example: Let  $\text{hisi}(9)$  correspond to the sample point

Example; 2 pre cursors, 5 post cursors

$C$  is the set of cursors ( $c_1 \dots c_n$ )

Zero pad  $\text{hisi}$  in preparation for circshift function

```
[ 0, 0, hisi1, hisi2, hisi3, hisi4, hisi5, hisi6, hisi7, hisi8, hisi9, hisi10, hisi11, hisi12, hisi13, hisi14, hisi15, hisi16, hisi17,  
hisi18, hisi19, hisi20, 0, 0, 0, 0, 0]
```

# Find C with Vector Forcing LMS

Define HH array of shifted hisi vectors: HH =

```
[ hisi9, hisi10, hisi11, hisi12, hisi13, hisi14, hisi15, hisi16, hisi17]
[ hisi8,  hisi9,  hisi10, hisi11, hisi12, hisi13, hisi14, hisi15, hisi16]
[ hisi7,  hisi8,  hisi9,  hisi10, hisi11, hisi12, hisi13, hisi14, hisi15]
[ hisi6,  hisi7,  hisi8,  hisi9,  hisi10, hisi11, hisi12, hisi13, hisi14]
[ hisi5,  hisi6,  hisi7,  hisi8,  hisi9,  hisi10, hisi11, hisi12, hisi13]
[ hisi4,  hisi5,  hisi6,  hisi7,  hisi8,  hisi9,  hisi10, hisi11, hisi12]
[ hisi3,  hisi4,  hisi5,  hisi6,  hisi7,  hisi8,  hisi9,  hisi10, hisi11]
[ hisi2,  hisi3,  hisi4,  hisi5,  hisi6,  hisi7,  hisi8,  hisi9,  hisi10]
```

FV is the forcing vector , FV =

```
[ 0, 0, FV0, FV1, 0, 0, 0]
```

Such that

$$FV = HH.' * C.'$$

And we solve for C

$$C = ( (HH.' * HH) ^{-1} * HH.' )' * FV';$$