### **PHY Enhancement for 100BASE-T1L**

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IEEE P802.3dg 100 Mb/s Long-Reach Single Pair Ethernet Task Force

### Purpose

- Preliminary FEC consideration for 3dg PHY.
- Other alternatives for performance enhancement.



# **PHY Objectives Review**

### **Basic PHY Objectives**

Consensus:

- 1. Preserve the IEEE 802.3/Ethernet frame format at the MAC client service interface.
- 2. Preserve minimum and maximum frame size of the current IEEE 802.3 standard.
- 3. Do not preclude meeting FCC and CISPR EMC requirements
- 4. Support for optional single-pair Auto-Negotiation
- Do not preclude the ability to survive industrial fault conditions (e.g., shorts, overvoltage, EMC)
- Do not preclude working within an Intrinsically Safe device and system as defined in IEC 60079
- 7. Support optional Energy Efficient Ethernet optimized for Operational Technology (OT) applications, including very low power devices
- 8. Support fast-startup operation which enables the time from power\_on=FALSE to a state capable of transmitting and receiving valid data to be less than 500ms

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EMC immunity is very important for a PHY system working in industrial environment.

There are different ways to improve the system' s noise tolerance:

- Increasing the transmit signal amplitude;
- Reducing the insertion loss of the cable;
- Improving shielding;
- Extra mechanism such as forward error correction or retransmission...



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## 10BASE-T1L with No FEC

Noise measurement results showed that the noise level will not cause communication issues for the 4B3T coded PHY.

### Conclusion

- · Several examples of noise sources within our facility have been measured.
- Due to the use of a shielded twisted pair cable the measured differential mode in-band noise is quite low.
- The maximum differential mode noise level measured in all four measurement locations has been 25.20 mV<sub>np</sub>, applying a gain correction factor of 1.5.

• It is expected, that this noise level will not cause communication issues in conjunction with the proposed 4B3T coded PHY.

- The maximum common mode noise level is significantly higher than the differential mode noise level.
- It is in the range of 300 mV<sub>pp</sub> or even higher, applying a gain correction factor of 1.5.
- Nevertheless because a symmetric differential receiver is being used, common mode noise within this amplitude range is not expected to be an issue.

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The 802.3cg defines mode conversion for unshielded link segments and coupling attenuation for shielded link segments, both up to 20MHz:

Table 146–5—Differential to common mode conversion

	Frequency (MHz)	E1	E <sub>2</sub>
TCL	$0.1 \leq f \leq 10$	≥ 50 dB	≥ 50 dB
TCL	$10 < f \le 20$	$\geq 50 - 20 \log_{10}\left(\frac{f}{10}\right) dB$	$\geq 50 - 20\log_{10}\left(\frac{f}{10}\right) dB$

#### Table 146–6—Coupling attenuation

Frequency (MHz)	(dB)			
	El	E2	E <sub>3</sub>	
0.1 to 20	≥ 50	≥ 50	≥ 60	

The 10BASE-T1L system with the required shielding performance is sufficient in E3 environment, even without FEC.



# Signal and Noise for 100BASE-T1L

Compared with 10BASE-T1L, 100BASE-T1L faces a different situation due to 10x bandwidth.

More signal attenuation/lower received signal power
 @ Nyquist bandwidth (take 3.75MHz \* 10 for PAM3 as an example).



- Larger external EMI/RFI noise on the cable as Mode conversion loss/Coupling attenuation will get worse at higher frequency band. (need measurement based evaluation)
- Also, a burst impulsive noise will affect more symbols for a higher symbol rate.

If we leave all these requirements only to link segment, it can be aggressive for cable/connectivity vendors, which seems not good for reusing existing cable system.

On the other side, further increasing transmit power may violate FCC and CISPR EMC requirements.

Therefore, there is a need to consider PHY enhancement to ensure 100BASE-T1L performance.



## Equalization and Coding

#### **Basic PHY Objectives**

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Try to avoid use of PBO or THP as in 2.5/5GBASE-T and 10GBASE-T:

- SPE does not have in-pair FEXT issue, PBO is not so necessary.
- Exchanging coefficients and re-adapting slows things down, not very suitable for fast link up.

#### It is better to use DFE instead of THP.

(Similar with Automotive SPE)

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#### **Conducted Immunity (CI)**

- IEC61000-4-6 models the RF noise in industrial environments as follows
- Continuous Wave (CW) simulating "intentional" RF transmitters in the frequency range from 150 KHz to 80 MHz.
  - Some OEM requires testing above 80 MHz as well
- The CW is coupled (CM) to the channel using clamps or CDNs (preferred)
- The amplitude of the CW is calibrated to be a specific value measured at the MDI

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- during the test, the amplitude is 80% AM modulated by a 1 kHz sine wave
- The base (unmodulated) amplitude is selected among three classes, according to the application
- Class 1 → 1 V<sub>rms</sub> (Low EM radiation environment)
- = Class 2 → 3 V<sub>ms</sub> (Moderate EM, typical commercial env)
- Class 3 → 10 V<sub>ms</sub> (Severe EM, typical industrial env)
- The CW sweeps the frequency range in 1% steps and a minimum of 0.5 s of dwell time (typ. 2 s)





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- IEC61000-4-4 models the impulse noise in industrial environments as follows
- Calibrated pulses of up to 2kV (CM)
- Duration: 50 ns (50% to 50%)
- Rise time: 5 ns
- Burst rate: 100 kHz (10 µs)
- Burst duration: 15 ms - Burst repetition: 300 ms
- Pulses are calibrated on a 50  $\Omega$  load at different peak levels (classes)







Two major noise sources in industrial environments are:

- RFI Noise: need heavy DFE instead of linear equalization; DFE can cause error propagation.
- Transient Impulse Noise: can cause burst error.

**Reed-Solomon FEC is a good choice for** solving the burst error problem.



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## **RS-FEC** Considerations

#### **Basic concept of RS-FEC:**

RS(N,M,k):

- Single RS frame consists of N symbols, and M of them are data (M < N)</li>
- Each RS symbol consists of k bits (N < 2<sup>k</sup>)
- Max number of correctable RS symbols is (N-M)/2

### Key features of RS-FEC:

- Coding gain
- Coding overhead
- Correcting length
- Latency

### **RS-FEC used in SPE PHY:**

- 1000BASE-T1: RS(450,406,9)
- 2.5/5/10GBASE-T1: RS(360,326,10) with interleaving
- 25GBASE-T1: RS(936,846,10) with interleaving

#### Take RS(450,406,9) as an example:

Achieve coding gain >6dB @ 1e-10; If shifted from 1Gbps to 100Mbps: RS frame length

= 36us, correcting length = 1.76us.

According to IEC61000-4-4 impulse noise model: duration = 50ns, burst rate = 100kHz ( $10 \mu$ s).



#### Worst case:

4 pulses are included in a single RS frame; total error length = 50ns \* 4 = 200ns << 1.76us, but the FEC latency reaches 40us. (<10us for 3cg)

For 100BASE-T1L, if RS-FEC is used, the code parameters need to be well designed to balance different metrics.



# Performance vs. Latency

From the perspective of performance and latency requirement, we have two typical use cases:

#### **USE CASE 1: Process Industry**

- 500m reach @ 100Mbps
- Lower SNR, more susceptible to external noise
- No specific latency requirement

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• Shielding may be not enough, FEC is likely to be required

#### **USE CASE 2: Servo Motor Control**

- 100m reach @ 100Mbps
- Higher SNR, less susceptible to external noise
- Low latency requirement, FEC should not be enabled
- Good shielding protection must be ensured



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When FEC is used, how does 100BASE-T1L satisfy both applications?



### Two Modes for One PHY

There are some IEEE examples that support different modes in one PHY:

#### 802.3bp: Different link segment operation mode

The 1000BASE-T1 PHY operates using full-duplex communications over a single twisted-pair copper cable with an effective rate of 1 Gb/s in each direction simultaneously while meeting the requirements (EMC, temperature, etc.) of automotive and industrial environments. The PHY supports operation on two types of link segments:

- a) An automotive link segment supporting up to four in-line connectors using a single twisted-pair copper cable for up to at least 15 m (referred to as *link segment type A*)
- b) An optional link segment supporting up to four in-line connectors using a single twisted-pair copper cable for up to at least 40 m to support applications requiring extended physical reach, such as industrial and automation controls and transportation (aircraft, railway, bus and heavy trucks). This link segment is referred to as *link segment type B*.

#### 802.3cg: Different PMA operation mode

When tested with the test fixture shown in Figure 146–20 with the transmitter in test mode 1, the transmitter output voltage shall be 2.4 V + 5%/-15% peak-to-peak (for the 2.4 Vpp operating mode) and 1.0 V + 5%/-15% peak-to-peak (for the 1.0 Vpp operating mode). Transmitter output voltage can be set using the management interface or by hardware default set-up.

#### 802.3ck: Dual FEC operation mode

#### 100GBASE-CR1/KR1 FEC Support

- > One option is to support both RS 544 FEC mechanisms:
  - Non-Interleaved RS FEC using 4:1 bit muxing (Clause 91)
  - Interleaved RS FEC based on nicholl\_3ck\_01b\_0519
- > Operation would be as follows:
  - All implementations implement both FECs for TX and RX
- AN is used to negotiate which FEC is used for a given link
  The chosen FEC is used in both directions on that link
- Default FEC is TBD
- Best of both worlds
  - Lowest latency with non-interleaved FEC for those links that don't have burst error concerns
  - More robust interleaved FEC for those links that want it
  - Minimal impact to designs

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As a reference, 100BASE-T1L can include different PCS operation modes based on applications:

- Normal mode (enable FEC);
- Low-latency mode (bypass FEC);
- Modes can be determined through Auto Negotiation or manual configuration.

### FEC Alternative: PHY Retransmission

- Physical layer retransmission can be seen as a "FEC function" enabled only when needed, which is more flexible;
- The data should be retransmitted in the form of a defined packet;
- TX retransmission can be triggered by different signals from RX, such as received data without acknowledgement or retransmission request;
- Retransmission should be designed under the overall latency limit;
- Example: ITU 998.4 DSL, MIPI A-PHY .....



# Summary

- 3dg is obviously different from 3cg due to bandwidth expanding, and some PHY enhancement is required for better immunity;
- Noise type of industry is similar with vehicle, so RS can be a good choice for FEC coding;
- Different PCS operation modes (w/ and w/o FEC) can be designed to adapt to different applications;
- Physical layer retransmission can be an alternative of FEC.



# Thank you.

