

Proposal for PCS Transmit Using 8b6T line code

100 Mb/s Long-Reach Single Pair Ethernet Task Force IEEE 802.3dg

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The PCS transmit function generates code-groups of the following form

```
{A_{n'} B_{n'} C_{n'} D_{n'} E_{n'} F_{n}}
```

Each code-group is a 6-tuple of ternary symbols

- The index, n, may be viewed as the value of a code-group counter or byte counter
- For each n, the PCS transmit function consume 2 samples of each MII transmit signal. We identify these using indices 2n and 2n+1 like this TXD_{2n} TXD_{2n}
- ▶ We will implement PCS data transmission enabling as in Figure 146-4
 - We will use the names tx_enable and tx_error rather than tx_enable_mii and tx_error_mii



- ▶ Per clause 22.2.1.6, the MAC may request that the PHY corrupt a frame
 - This is done by asserting TX_ER while TX_EN is high
- In clause 146 this situation is handled in the PCS transmit state diagram of Figure 146-5
 - A different end-of-stream delimiter identifies a frame that is to be corrupted
 - This approach was necessitated due to a shortage of special code-groups
- Previous clauses, such as clause 40, have used special symbols to propagate errors that are flagged by the MAC
 - We will use this approach
- The variable xmt_error will request the transmission of a special code-group xmt_error = (tx_enable_{2n} & tx_error_{2n})|(tx_enable_{2n+1} & tx_error_{2n+1})
 - An error that is flagged by the MAC for one nibble is expanded to a byte which is consistent with the intended use of TX_ER as described in clause 22.2.1.6



The side-stream scramblers for the LEADER and FOLLOWER will use the same generator polynomials as specified in clause 40.3.1.3.1

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g_L(x) = 1 + x^{13} + x^{33}
g_F(x) = 1 + x^{20} + x^{33}
```

- ► A realization of each of these scramblers using a linear feedback shift register (LFSR) is shown in Figure 40-6
- ▶ Bits X_n and Y_n are generated from the bits of the scrambler LFSR as in clause 40.3.1.3.2

 $X_n = Scr_n[4]^{Scr_n[6]}$

 $Y_n = Scr_n[1]^{Scr_n[5]}$



The 4 bits $Sy_n[3:0]$ are generated from the bit $Scr_n[0]$ using the following generating polynomial

 $g(x) = x^3 \wedge x^8$

▶ The equations for bits $Sy_n[3:0]$ are as follows

 $Sy_{n}[0] = Scr_{n}[0]$ $Sy_{n}[1] = g(Scr_{n}[0]) = Scr_{n}[3]^{Scr_{n}}[8]$ $Sy_{n}[2] = g^{2}(Scr_{n}[0]) = Scr_{n}[6]^{Scr_{n}}[16]$

 $Sy_n[3] = g^3(Scr_n[0]) = Scr_n[9]^Scr_n[14]^Scr_n[19]^Scr_n[24]$

▶ This is as was specified in clause 40.3.1.3.2



- ► The 4 bits $Sx_n[3:0]$ are generated from the bit X_n using the same generating polynomial, g(x), as was used to generate bits $Sy_n[3:0]$
- ▶ The equations for bits $Sx_n[3:0]$ are as follows

$$Sx_{n}[0] = X_{n} = Scr_{n}[4]^{S}cr_{n}[6]$$

$$Sx_{n}[1] = g(X_{n}) = Scr_{n}[7]^{S}cr_{n}[9]^{S}cr_{n}[12]^{S}cr_{n}[14]$$

$$Sx_{n}[2] = g^{2}(X_{n}) = Scr_{n}[10]^{S}cr_{n}[12]^{S}cr_{n}[20]^{S}cr_{n}[22]$$

$$Sx_{n}[3] = g^{3}(X_{n}) = Scr_{n}[13]^{S}cr_{n}[15]^{S}cr_{n}[18]^{S}cr_{n}[20]^{S}$$

$$Scr_{n}[23]^{S}cr_{n}[25]^{S}cr_{n}[28]^{S}cr_{n}[30]$$

► Again, this is as was specified in clause 40.3.1.3.2



- The 2 bits $Sg_n[1:0]$ are generated from the bit Y_n using the same generating polynomial, g(x), as was used to generate bits $Sy_n[3:0]$
- ▶ The equations for bits $Sg_n[1:0]$ are as follows

 $Sg_n[0] = Y_n = Scr_n[1]^Scr_n[5]$

 $Sg_n[1] = g(Y_n) = Scr_n[4]^{Scr_n[8]} Scr_n[9]^{Scr_n[13]}$

This is as was specified in clause 40.3.1.3.2 except that we only generate 2 bits



▶ We use similar equations to those of clause 146.3.3.4.3

 $Sd_{n}[3] = \begin{cases} TXD_{2n}[3]^{S}y_{n}[3], & \text{if } (tx_enable_{2n} = TRUE) \\ 1^{S}y_{n}[3], & \text{else} & \text{if } (loc_rcvr_status = OK) \\ Sy_{n}[3], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ 1^{S}y_{n}[2], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ Sy_{n}[2], & \text{else} & \text{if } (loc_lpi = TRUE) \\ Sy_{n}[2], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ Sy_{n}[2], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ Sy_{n}[1], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ Sy_{n}[1], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ Sy_{n}[0], & \text{else} & \text{if } (tx_enable_{2n} = TRUE) \\ \end{bmatrix}$

▶ Note that we do not reverse bits $Sy_n[1]$ and $Sy_n[2]$ during IDLE as was done in clause 146

• The rationale for this will be explained shortly



► We use the following equation for these bits

 $Sd_{n}[7:4] = \begin{cases} TXD_{2n+1}[3:0]^{S}x_{n}[3:0], & \text{if (tx_enable_{2n+1} = TRUE)} \\ Sx_{n}[3:0], & \text{else} \end{cases}$

Stream Delimiters

- ► The PHY generates a continuous stream of code-groups
 - Each code-group is a 6-tuple of ternary symbols
- ▶ Code-groups align with byte boundaries in the PHY
 - This is due to the use of an 8b6T line code
- MII is a nibble-oriented interface
 - There is no guarantee that byte boundaries in the PHY match those in the MAC
 - TX_EN may rise or fall on odd nibble boundaries from a PHY perspective
- ► Could delay TX_EN transitions to align with PHY byte boundaries
 - There is no guarantee that byte alignment between the MAC and the PHY is consistent from one system reset to the next
 - This could create latency variability
 - We will maintain the byte alignment from the MAC and pass it through the physical layer
 - This requires different stream delimiters for changes in TX_EN on odd nibble boundaries



Code-group Categories



The variables tx_mode, tx_enable and xmt_error determine the codegroup category which will be one of the following

Code-group Category	Criterion for Selecting this Category
SEND_Z	tx_mode is SEND_Z
SSD	tx_enable switches from FALSE to TRUE on a byte boundary
SSD_ODD	tx_enable switches from FALSE to TRUE on an odd nibble boundary
ESD	tx_enable switches from TRUE to FALSE on a byte boundary
ESD_ODD	tx_enable switches from TRUE to FALSE on an odd nibble boundary
XMT_ERR	An error condition is to be propagated to the link partner
DATA	Frame data is to be sent
IDLE	None of the other code-group categories have been selected

Outline of Transmission Process



- The code-group category determines which table will be used to select the non-negative disparity (NND) code-group for transmission
 - If the code-group category is SEND_Z, then the code-group is {0, 0, 0, 0, 0, 0}
 - Otherwise, the code-group is determined either by the bit $Sg_n[1]$ or by the bits $Sd_n[7:0]$, depending on the code-group category
 - NND code-groups are denoted {TA_n, TB_n, TC_n, TD_n, TE_n, TF_n}
- The NND code-groups are passed to the running disparity (RD) control function
 - This function may negate a code-group with positive disparity to bound RD
 - Negation of a code-group means negating each of the ternary symbols in the 6-tuple
 - We call the resulting code-group a balanced code-group
 - Balanced code-groups are denoted {A_n, B_n, C_n, D_n, E_n, F_n}
- Balanced code-groups are transmitted one ternary symbol at a time
 - The leftmost symbol in the code-group is transmitted first

Code-group Category Selection



	tx_enable				xmt_error		Code-group	Comment	
	2n-3	2n-2	2n-1	2n	2n+1	n-1	n	Category	
SEND_Z	х	х	х	х	х	х	х	SEND_Z	
not SEND_Z	0	0	0	0	0	х	х	IDLE	
	0	0	0	1	1	х	х	SSD	Ignore any error until next byte
	0	0	0	0	1	х	х	SSD_ODD	Ignore any error until next byte
	0	1	1	1	1	1	х	XMT_ERR	Delayed error from start of frame
	0	0	1	1	1	1	х	XMT_ERR	Delayed error from start of frame
	0	0	1	1	1	0	0	DATA	
	0	0	1	1	1	0	1	XMT_ERR	
	0	1	1	1	1	0	0	DATA	
	0	1	1	1	1	0	1	XMT_ERR	

Sending a code-group from the SSD_ODD code-group category informs the receiver that it should assert RX_DV on an odd nibble boundary

Code-group Category Selection



tx_mode	tx_enable					xmt_error		Code-group	Comment
	2n-3	2n-2	2n-1	2n	2n+1	n-1	n	Category	
not	1	1	1	1	1	х	0	DATA	
SEND_Z	1	1	1	1	1	х	1	XMT_ERR	
	1	1	1	1	0	Х	0	DATA	Last nibble of frame padded
	1	1	1	1	0	х	1	XMT_ERR	Error in last nibble of frame
	1	1	1	0	0	Х	Х	ESD	
	1	1	0	0	0	Х	Х	ESD_ODD	
	1	0	0	0	0	х	Х	IDLE	

- If the falling edge of tx_enable occurs on an odd nibble boundary, the final data nibble is padded out to a byte
 - Per the equations for $Sd_n[7:4]$, the nibble that is added is determined by $Sx_n[3:0]$
 - The code-group that follows is selected from the ESD_ODD code-group category. This informs the
 receiver that it should discard the last nibble of the previous byte and deassert RX_DV on an odd nibble
 boundary.



- ► We use bit Sg_n[1] to choose between 2 code-groups to avoid unnecessary correlation artefacts in the stream
 - Each of these 2 code-groups is the element-wise negative of the other
 - The code-groups in the SSD_ODD category are the same as those in the SSD category but with Sg_n[1] inverted

	Code-group Category	$Sg_n[1]$	TA _n , TB _n , TC _n , TD _n , TE _n , TF _n
ç	SSD	0	+1, +1, -1, -1, +1, -1
		1	-1, -1, +1, +1, -1, +1
SSD_ODD	SSD_ODD	0	-1, -1, +1, +1, -1, +1
		1	+1, +1, -1, -1, +1, -1



- ► We use bit Sg_n[1] to choose between 2 code-groups to avoid unnecessary correlation artefacts in the stream
 - Each of these 2 code-groups is the element-wise negative of the other
 - The code-groups in the ESD_ODD category are the same as those in the ESD category but with Sg_n[1] inverted

Code-group Category	$Sg_n[1]$	TA _n , TB _n , TC _n , TD _n , TE _n , TF _n
ESD	0	+1, -1, -1, +1, +1, -1
	1	-1, +1, +1, -1, -1, +1
ESD_ODD	0	-1, +1, +1, -1, -1, +1
	1	+1, -1, -1, +1, +1, -1



- We use bit Sg_n[1] to choose between 2 code-groups to avoid unnecessary correlation artefacts in the stream
 - Each of these 2 code-groups is the element-wise negative of the other

Code-group Category	<i>Sg</i> _{<i>n</i>} [1]	TA _n , TB _n , TC _n , TD _n , TE _n , TF _n
XMT_ERR	0	-1, -1, +1, +1, +1, -1
	1	+1, +1, -1, -1, -1, +1

When the selected code-group category is DATA we use bits Sd_n[7:0] to choose the code-group

• As there are too many code-groups to list them all here, the following file is provided

data_code_groups_05132024.txt

DATA Code-groups

This file has 256 lines. Each line has 7 columns. The first column is the Sd_n [7:0] value in binary form. The remaining 6 columns provide the ternary values for the code-group. The following table lists the first 4 code-groups from this file.

Code-group Category	<i>Sd</i> _{<i>n</i>} [7:0]	TA _n , TB _n , TC _n , TD _n , TE _n , TF _n
DATA	00000000	-1, +1, -1, +1, +1, -1
	0000001	-1, +1, +1, -1, +1, -1
	00000010	+1, -1, -1, +1, -1, +1
	00000011	+1, -1, +1, -1, -1 , +1



IDLE Signaling

▶ In clause 146 there is no reliable way to distinguish IDLE from DATA

- Bits Sy_n[1] and Sy_n[2] are swapped during IDLE. However, a data pattern can readily reproduce this effect. The result is that there is no way to detect IDLE signaling while receiving a frame.
- If the COMMA code-groups that mark the end of a frame are missed, the PCS receive state machine of Figure 146-9 becomes stuck in the DATA and DATA DECODE states. The situation may persist until the start of the next frame and both frames are lost.
- By contrast, the sign reversal scheme of clause 40.3.1.3.6 ensures that IDLE signaling can be detected while receiving a frame.

► We propose to use certain spare code-groups to identify IDLE

- We replace 16 of the code-groups that are used for DATA signaling with special codegroups that are used only during IDLE
- Detecting any of these special code-groups while receiving a frame will be treated as a premature end condition



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▶ When the selected code-group category is IDLE we use bits Sd_n [7:0] to choose the code-group

 For Sd_n[7:0] values in the binary range 00000000 to 11101111 the IDLE code-groups are the same as the data code-groups. However, for Sd_n[7:0] values in the binary range 11110000 to 11111111 the special IDLE code-groups listed in the following file are used

idle_code_groups_05132024.txt

IDLE Code-groups

This file has 16 lines and is organized in the same way as was used for the DATA codegroups. The following table lists the first 4 code-groups from this file.

Code-group Category	<i>Sd</i> _n [7:0]	TA _n , TB _n , TC _n , TD _n , TE _n , TF _n
IDLE	11110000	-1, +1, +1, +1, +1, +1
	11110001	+1, -1, +1, +1, +1, +1
	11110010	+1, +1, -1, +1, +1, +1
	11110011	+1, +1, +1, -1, +1, +1





- ▶ It is proposed not to support RD checking in the receiver
 - A disturbance such as an EFT event would be likely to cause an error in such an RD check
 - The RD checking process would take time to resynchronize after such an error
 - This would result in error propagation
- ▶ We do not see a benefit in including RD checking in the receiver
 - Such checking is not required to detect frame errors
 - The benefit of RD control is on the transmit side
- As we will not support RD checking in the receiver, there is no need to reset RD at the start and the end of each frame as was done in clause 146

 $DS = (TA \perp TB \perp TC \perp TDD \perp TED \perp TE)$

- The RD control function maintains a running disparity value, RD_n. This value is initialized to 0 at n=0
- ► A sign value SX_n is generated using the following equations

$$SX_{n} = \begin{cases} -1, & \text{if } (DS_{n} > 0) \& ((RD_{n} > 0) | ((RD_{n} = 0) \& (Sg_{n}[0] = 1))) \\ +1, & \text{else} \end{cases}$$

The balanced code-group is generated by applying the computed sign to the NND code-group

 ${A_n, B_n, C_n, D_n, E_n, F_n} = SX_n * {TA_n, TB_n, TC_n, TD_n, TE_n, TF_n}$

Here * denotes element-wise multiplication by a scalar.

▶ The running disparity value is updated as shown below

 $RD_{n+1} = RD_n + (A_n + B_n + C_n + Dn + En + F_n)$



