



IEEE 802.3dg Task Force

100BASE-T1L PMA
State Machine Changes

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Suggested change to PHY Control State Machine

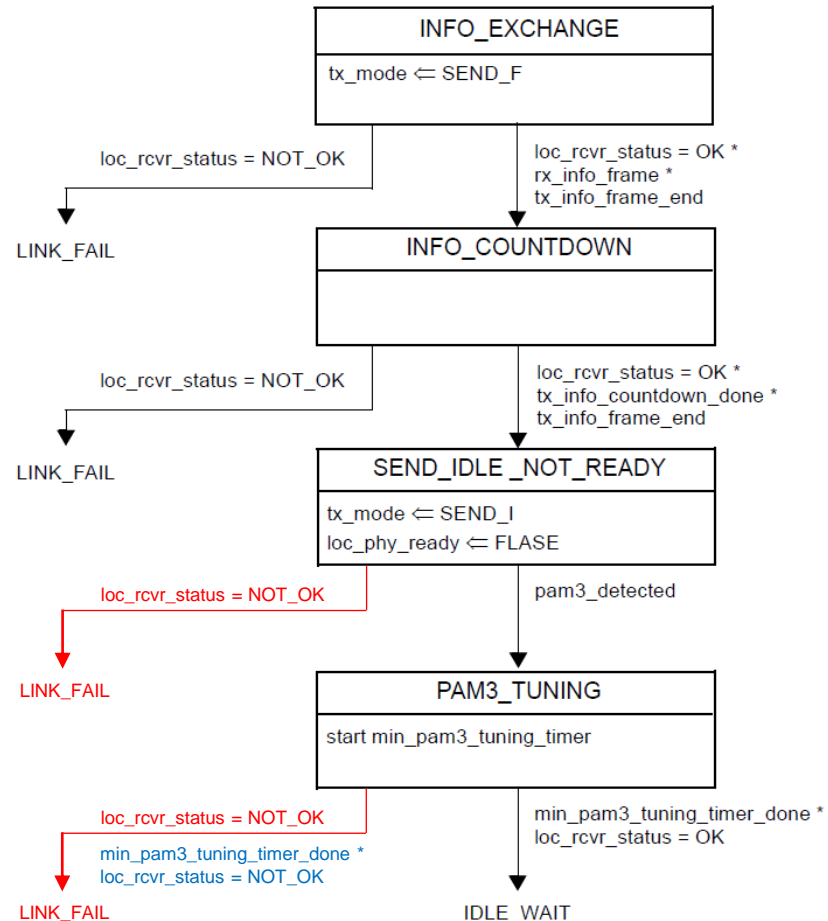


Figure 190–16—PHY Control state diagram, part b

- If `loc_rcvr_status = NOT_OK`, while in `SEND_IDLE_NOT_READY` or `PAM3_TUNING` states, the PHY Control state machine would stay in one of these states and not go to `LINK_FAIL` state (depending, if PAM3 symbols are detected or not).
- Finally the Auto-Negotiation state machine would bring the PHY Control state machine back to the start condition.
- From all other states the PHY Control state machine would go to `LINK_FAIL` in a similar condition (signaling earlier to the remote PHY that something is wrong by sending zeroes (`SEND_Z`)).
- This could be resolved by adding the two red colored additional exit conditions.
- If a risk is seen, that while switching from PAM2 to PAM3 the local receiver status can temporarily become `NOT_OK`, it makes sense, not to go to `LINK_FAIL` directly and allow the tuning timer to elapse first (in this case omitting the exit condition to `LINK_FAIL` in `SEND_IDLE_NOT_READY` state and using the blue colored, instead of red colored, exit condition in `PAM3_TUNING` state could make sense as alternative).

Other Changes to PHY Control State Machine

- Change exit condition of PAM2_TRAINING_WAIT state to:

$\text{loc_rcvr_status} = \text{OK} * ((\text{config} = \text{LEADER} * \text{rem_rcvr_status} = \text{OK}) + (\text{config} = \text{FOLLOWER} * \text{rx_info_frame}))$

- In SEND_IDLE state loc_phy_ready is set to TRUE. This results in the far end PHY signaling rem_phy_ready = TRUE. If both PHYs signal ready, then normal operation (state SEND_IDLE_OR_DATA) can start. Exit condition of SEND_IDLE state needs to be changed to:

$\text{loc_rcvr_status} = \text{OK} * \text{rem_phy_ready}$

- If either loc_rcvr_status = NOT_OK or pma_refresh_status = FAIL, the link should be restarted. Exit condition of SEND_IDLE_OR_DATA state needs to be changed to:

$\text{loc_rcvr_status} = \text{NOT_OK} + \text{rem_refresh_status} = \text{FAIL}$

Suggested change to EEE Refresh Monitor State Machine

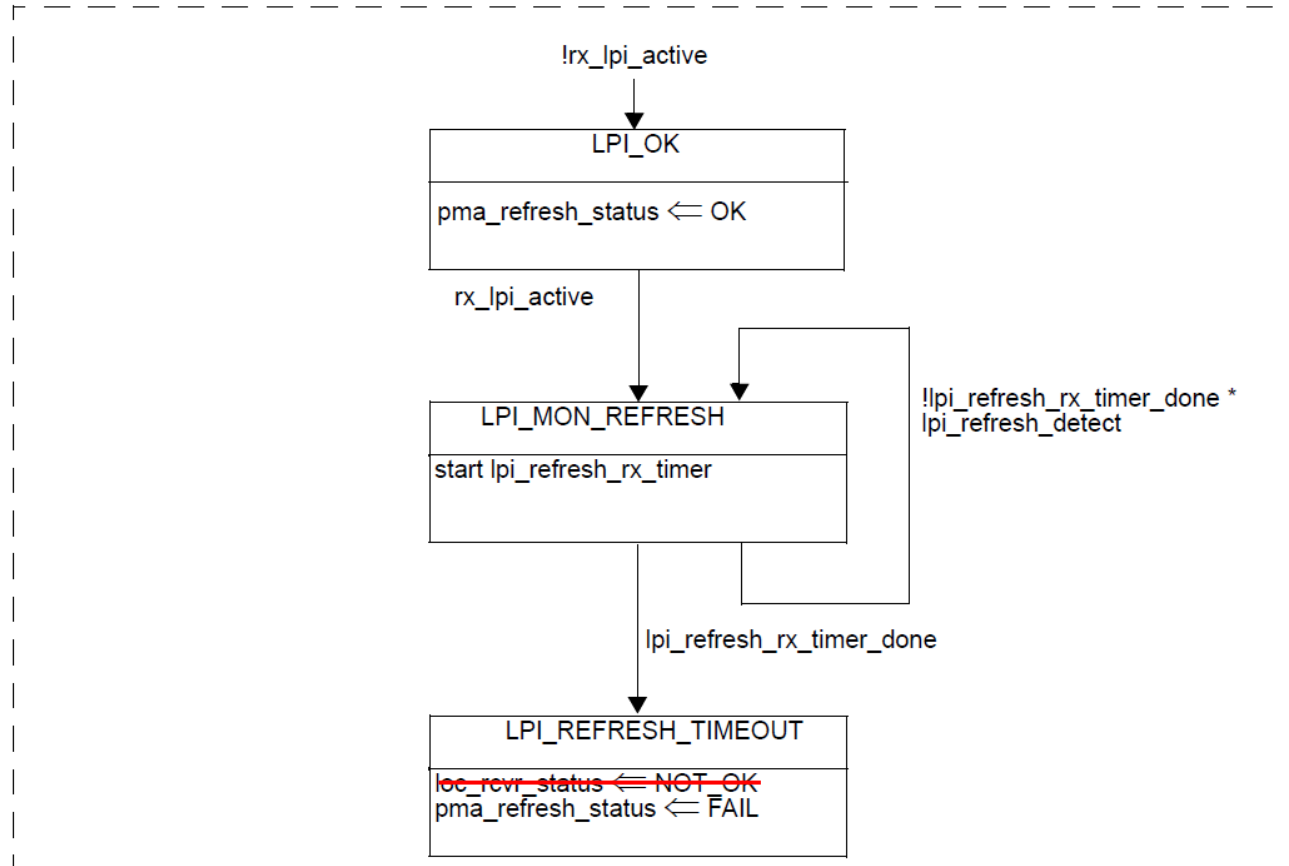


Figure 190-19—EEE Refresh monitor state diagram

- `loc_rcvr_status` is generated by PMA receive function.
- Thus, the EEE refresh monitor is not expected to have write access to this variable in parallel to the PMA Receive function, as this may end up in a conflict.
- Setting `pma_refresh_status` `<= FAIL` should be enough to do, as by setting this variable, the PHY Control state machine exits `SEND_IDLE_OR_DATA` state to `LINK_FAIL` state, which brings the link down by sending zeroes (and causes the same behavior as setting `loc_rcvr_status` to `NOT_OK`).

Thank you!