

# 200 Gb/s per lane KR Backplane Objective Proposal

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# Presentation Goal

MOTIONS\_3DFDJ\_2303

- Propose a value for “X” in straw poll #1 (motions\_3dfdj\_2303)

## Straw Poll #1

I would support a one-lane 200 GbE, a two-lane 400 GbE, a four-lane 800 GbE, and an eight-lane 1.6 TbE backplane objective of the form:

“Define a physical layer specification that supports [n\*200] Gb/s operation over [n] lanes over electrical backplanes supporting a die-to-die insertion loss  $\leq X$  dB at 53.125 GHz”

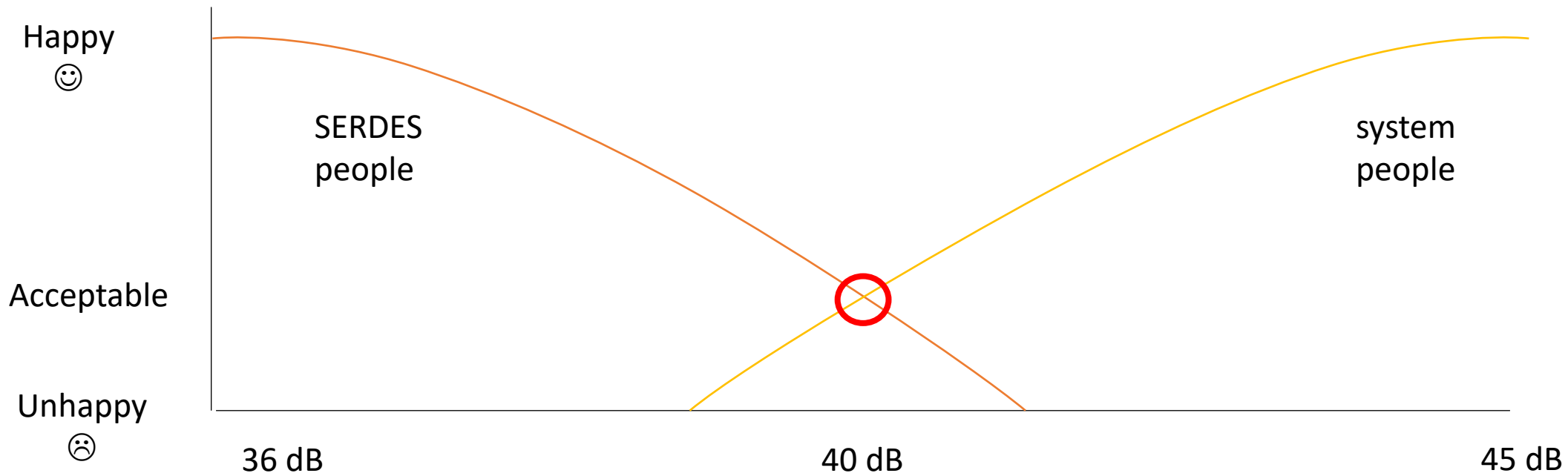
Results (all) Y: 56 , N: 11 , A: 14

**X = 40**

# Why 40 dB?

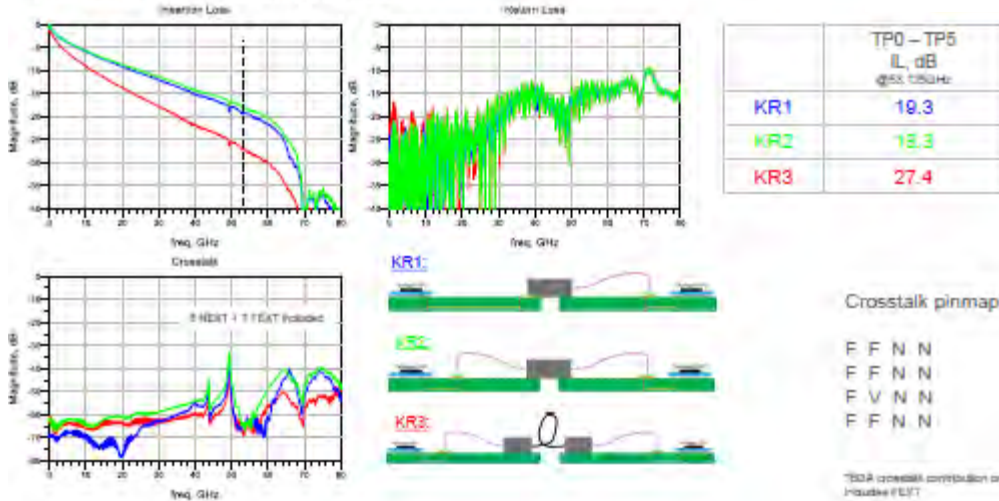
COMPROMISE!!!!

- ❑ Feedback from people building SERDES: 36-37dB IL target
- ❑ Feedback from people building systems: 42-45 dB IL target



# Feasibility based on P802.3dj contributions illustrate a variety of 200 G KR configurations

## Performance Comparison



- Simulation of a typical KR cabled backplane architecture over various cable lengths
- Contributions:
  - BGA / PCB trace / NPC via escapes simulated with HFSS
  - NPC + BP cable assemblies: provided by Michael Rowlands, affiliated with Amphenol
- Ball-to-Ball topology: does not include package effects
- This presentation does NOT propose the following:
  - Specific aggregate or cable losses
  - Specific host architecture implementations

## 200 Gb/s PAM4 Channel Topologies

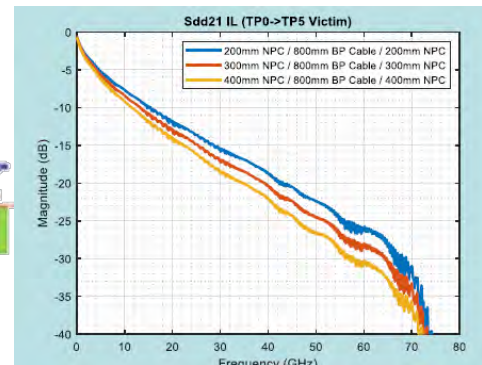
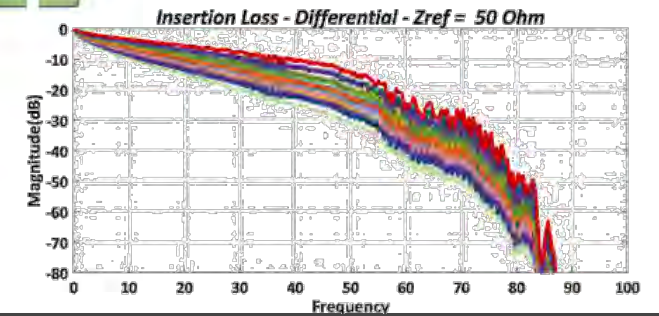
Length variations provide an amalgamation of products a with range of losses



### Chip to Chip (C2C) Mezzanine



IEEE P802.3dj Ethernet Task Force



Summary of KR reaches are up to

- 1 meter for a cabled backplane
- 300 mm of cable on a host plus a few inches for break out
  - Or between 5 to 7 inches of host PCB trace
- Subset of KR may include
  - orthogonal box designs
  - chip to chip

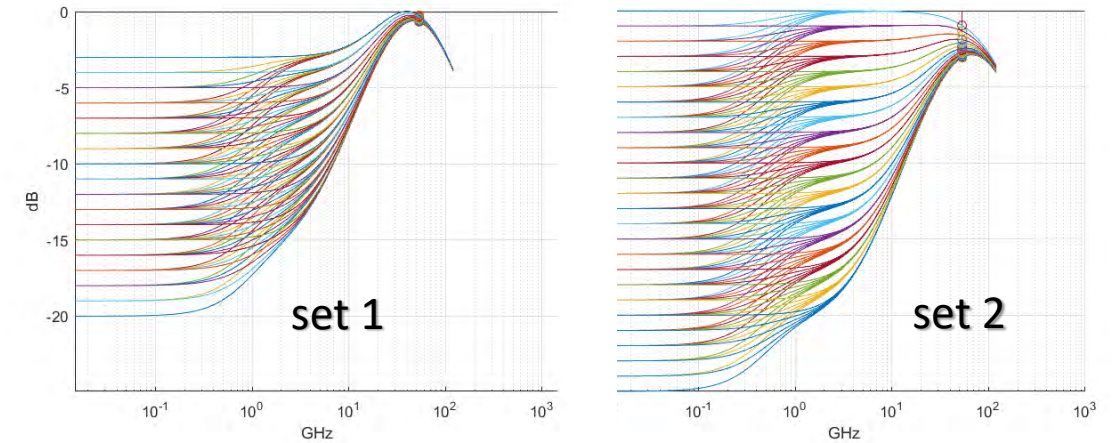
Details in References on slide 11

# Example parameters sets which suggest > 3 dB COM feasibility for “X” = 40 dB

THIS IS NOT A PARAMETER PROPOSAL

parameter	Used for this work set 1	Used for this work set 2
$\eta_0$ [V <sup>2</sup> /GHz]	4e-9	5e-9
SNR_Tx	33	33
$t_r$ [ps]	4	4
$f_r$	0.58	0.5
$b_{\max}$	0.75	0.85
DFE equivalent [Taps]	1	1
Tx FFE Pre/Post	4/1	4/1
Rx FFE pre/post cursor	6/60	6/24
FFE floating groups/ floating taps per group*	NA	4/5
DER <sub>0</sub>	1e-4	1e-4
MLSE used	yes	yes

\* RX FFE floating taps estimated in COM 4.0 with RX DFE floating taps in the presentation



parameter	Used for this work set 1	Used for this work Set 2
fz	fb/4.223	fb/2.5
fp1	fb/2.6562	fb/2.5
fp2	Fb/1.8973	Fb
fLF	Fb/80	Fb/160
Gdc	-15 to 0-3 (step 1)	-20 to 0 (step 1)
Gdc2	-5 to 0 (step 1)	-6 to 0 (step 1)



# Example 200 Gb/s KR COM configuration set 1

Packages were adjusted to achieve around 40 dB die to die loss

Table 93A-1 parameters				I/O control			Table 93A-3 parameters			
Parameter	Setting	Units	Information				Parameter	Setting	Units	Information
f_b	106.25	GBd		DIAGNOSTICS	1	logical	package_tl_gamma0_a1_a2	[0 0.0008455 0.000340225]		
f_min	0.05	GHz		DISPLAY_WINDOW	1	logical	package_tl_tau	0.00644805	ns/mm	
Delta_f	0.01	GHz		CSV_REPORT	0	logical	package_Z_c	[92 92 ; 70 70; 80 80; 100 100]	Ohm	
C_d	[0.4e-4 0.9e-4 1.1e-4 ; 0.4e-4 0.9e-4 1.1e-4]	nF	[TX RX]	RESULT_DIR	results\CACR_set1_{date}\		z_p_select	[1:10]		[test cases to run]
L_s	[0.13 0.15 0.14; 0.13 0.15 0.14]	nH	[TX RX]	SAVE_FIGURES	0	logical	z_p (TX)	[ 6 31 ; 1 1; 1 1 ; 0.5 0.5 ]	mm	[test cases]
C_b	[0.3e-4 0.3e-4]	nF	[TX RX]	Port Order	[ 1 3 2 4 ]		z_p (NEXT)	[ 8 29 ; 1 1; 1 1 ; 0.5 0.5 ]	mm	[test cases]
R_0	50	Ohm		RUNTAG	KR_se1_eval_		z_p (FEXT)	[ 6 31 ; 1 1; 1 1 ; 0.5 0.5 ]	mm	[test cases]
R_d	[ 45 45]	Ohm	[TX RX]	COM_CONTRIBUTION	1	logical	z_p (RX)	[ 8 29 ; 1 1; 1 1 ; 0.5 0.5 ]	mm	[test cases]
A_v	0.386	V	vp/vf=	Operational			C_p	[0.5e-4 0.5e-4]	nF	[TX RX]
A_fe	0.386	V	vp/vf=	ERL Pass threshold	10	dB	Floating Tap Control			
A_ne	0.6	V		COM Pass threshold	3	db	N_bg	0	0 1 2 or 3 groups	
L	4			DER_0	1.00E-04		N_bf	3	taps per group	
M	32			T_r	0.00400	ns	N_f	80	UI span for floating taps	
filter and Eq				FORCE_TR	1	logical	bmaxg	0.2	max DFE value for floating taps	
f_r	0.58	*fb		PMD_type	C2C		B_float_RSS_MAX	0.1	rss tail tap limit	
c(0)	0.55		min	EW	1		N_tail_start	25	(UI) start of tail taps limit	
c(-1)	[ -0.4:0.02:0 ]		[min:step:max]	MLSE	1	logical	Filter: Rx FFE			
c(-2)	[ 0:.02:0.1 ]		[min:step:max]	TDR and ERL options			ffe_pre_tap_len	6	UI	
c(-3)	0		[min:step:max]	TDR	1	logical	ffe_post_tap_len	60	UI	
c(-4)	0		[min:step:max]	ERL	1	logical	ffe_tap_step_size	0		
c(1)	[ -0.2:0.05:0 ]		[min:step:max]	ERL_ONLY	0	ns	ffe_main_cursor_min	1		
N_b	1	UI		TR_TDR	0.01		ffe_pre_tap1_max	1		
b_max(1)	0.75		As/dffe1	N	1000	logical	ffe_post_tap1_max	1		
b_max(2..N_b)	0.15		As/dfe2..N_b	TDR_Butterworth	1		ffe_tapn_max	1		
b_min(1)	0		As/dffe1	beta_x	0		ffe_backoff	0		
b_min(2..N_b)	-0.15	S	As/dfe2..N_b	rho_x	0.618					
g_DC	[-15:1:-3]	dB	[min:step:max]	TDR_W_TXPKG	0	UI				
f_z	25.16	GHz		N_bx	20					
f_p1	40.00	GHz		fixture delay time	[ 0 0 ]					
f_p2	56.00	GHz		Tukey_Window	1					
g_DC_HP	[-5:1:0]		[min:step:max]	Noise, jitter						
f_HP_PZ	1.328125	GHz		sigma_RJ	0.01	UI				
Butterworth	1	logical	include in fr	A_DD	0.02	V^2/GHz				
				eta_0	4.00E-09	dB				
				SNR_TX	33					
				R_LM	0.95					

# Example 200 Gb/s KR COM configuration set 2

Packages were adjusted to achieve around 40 dB die to die loss

Table 93A-1 parameters			
Parameter	Setting	Units	Information
f_b	106.25	GBd	
f_min	0.05	GHz	
Delta_f	0.01	GHz	
C_d	[0.4e-4 0.9e-4 1.1e-4 ; 0.4e-4 0.9e-4 1.1e-4 ]	nF	[TX RX]
L_s	[0.13 0.15 0.14; 0.13 0.15 0.14 ]	nH	[TX RX]
C_b	[0.3e-4 0.3e-4 ]	nF	[TX RX]
A_v	0.413	V	vp/vf=
A_fe	0.413	V	vp/vf=
A_ne	0.608	V	
L	4		
M	32		
filter and Eq			
f_r	0.5	*fb	
c(0)	0.54		min
c(-1)	[-0.4:0.02:0]		[min:step:max]
c(-2)	[0:.02:0.16]		[min:step:max]
c(-3)	[-0.1:0.02:0]		[min:step:max]
c(-4)	[0:.02:0.1]		[min:step:max]
c(1)	[-0.2:0.02:0]		[min:step:max]
N_b	1	UI	
b_max(1)	0.85		As/dffe1
b_max(2..N_b)	[0.3 0.2*ones(1,22)]		As/dfe2..N_b
b_min(1)	0		As/dffe1
b_min(2..N_b)	[-0.3 -0.2*ones(1,22)]	S	As/dfe2..N_b
g_DC	[-20:1:0]	dB	[min:step:max]
f_z	42.50	GHz	
f_p1	42.50	GHz	
f_p2	106.25	GHz	
g_DC_HP	[-6:1:0]		[min:step:max]
f_HP_PZ	0.6640625	GHz	

I/O control		
DIAGNOSTICS	1	logical
DISPLAY_WINDOW	1	logical
CSV_REPORT	0	logical
RESULT_DIR	.\results\CAKR_set2_{date}\	
SAVE_FIGURES	0	logical
Port Order	[ 1 3 2 4 ]	
RUNTAG	KR_set2_eval_	
COM_CONTRIBUTION	1	logical
Operational		
ERL Pass threshold	10	dB
COM Pass threshold	3	db
DER_0	1.00E-04	
T_r	0.004	ns
FORCE_TR	1	logical
PMD_type	C2C	
EW	1	
MLSE	1	logical
TDR and ERL options		
TDR	1	logical
ERL	1	logical
ERL_ONLY	0	ns
TR_TDR	0.01	
N	3500	logical
TDR_Butterworth	1	
beta_x	0	
rho_x	0.618	
TDR_W_TXPKG	0	UI
N_bx	21	
fixture delay time	[ 0 0 ]	
Tukey_Window	1	
Noise, jitter		
sigma_RJ	0.01	UI
A_DD	0.02	V^2/GHz
eta_0	5.00E-09	dB
SNR_TX	33	
R_LM	0.95	

Table 93A-3 parameters			
Parameter	Setting	Units	Information
package_tl_gamma0_a1_a2	[0.0005 0.00089 0.0002]		
package_tl_tau	0.006141	ns/mm	
package_Z_c	[87.5 87.5 ; 92.5 92.5 ]	Ohm	
z_p select	[ 1 2 ]		[test cases to run]
z_p (TX)	[12 42; 1.8 1.8 ]	mm	[test cases]
z_p (NEXT)	[12 40; 1.8 1.8 ]	mm	[test cases]
z_p (FEXT)	[12 42; 1.8 1.8 ]	mm	[test cases]
z_p (RX)	[12 40; 1.8 1.8 ]	mm	[test cases]
C_p	[0.4e-4 0.4e-4]	nF	[TX RX]
R_0	50	Ohm	
R_d	[ 46.25 46.25]	Ohm	[TX RX]
Floating Tap Control			
N_bg	4		0 1 2 or 3 groups
N_bf	5		taps per group
N_f	60		UI span for floating taps
bmaxg	0.05		max DFE value for floating taps
B_float_RSS_MAX	0.02		rss tail tap limit
N_tail_start	50		(UI) start of tail taps limit
Filter: Rx FFE			
ffe_pre_tap_len	6	UI	
ffe_post_tap_len	24	UI	
ffe_tap_step_size	0		
ffe_main_cursor_min	0.7		
ffe_pre_tap1_max	0.7		
ffe_post_tap1_max	0.7		
ffe_tapn_max	0.7		
ffe_backoff	0		

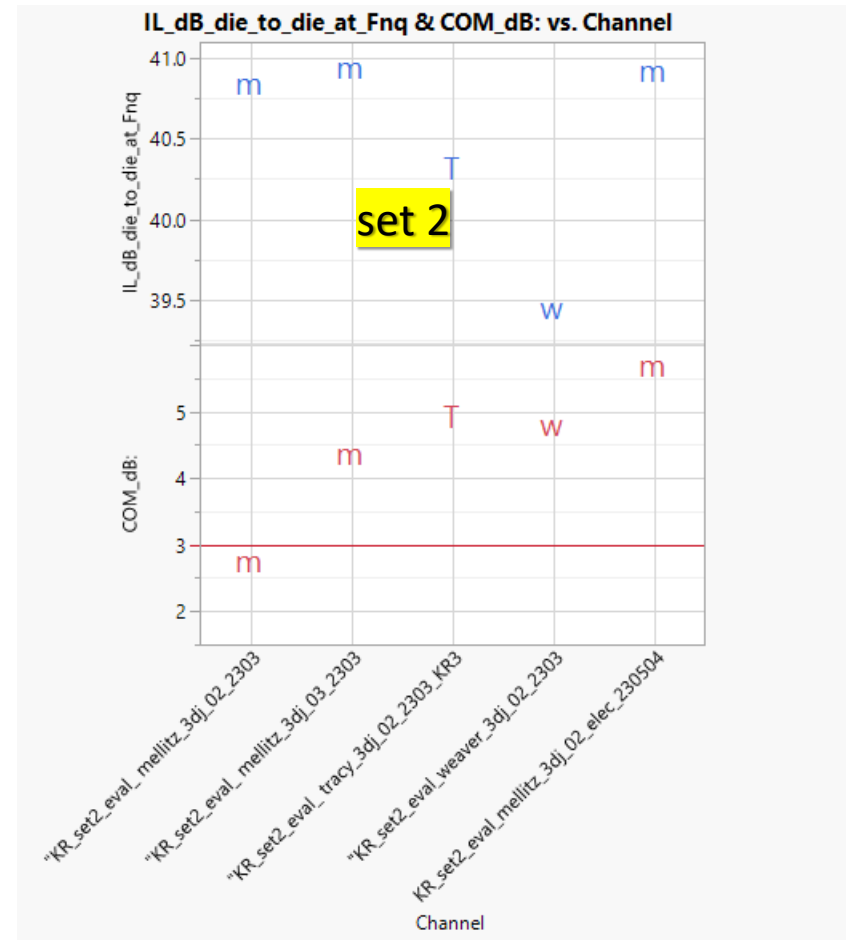
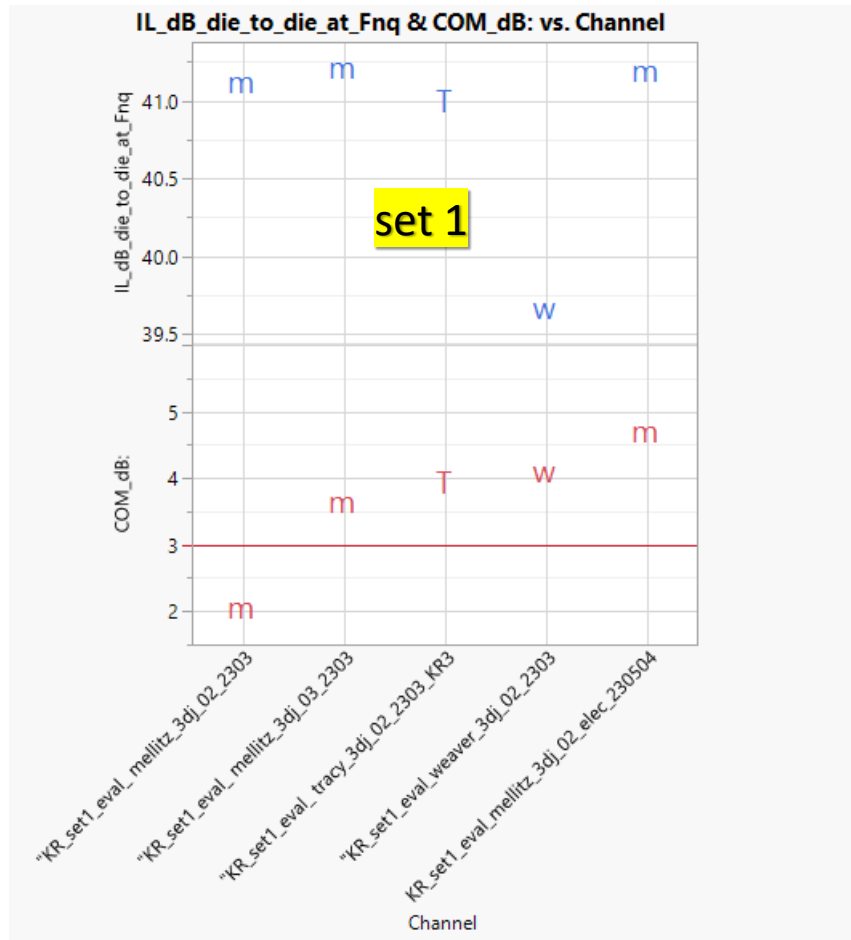
# Channels which reached X of 40 dB with 7 dB loss packages

## □ Channels in this presentation (with key)

- [tracy\\_3dj\\_02\\_2303 \(T\)](#)
  - TE\_KR3\_2p7dBPCB\_10in30AWG\_Conn\_1m26AWG\_Conn\_10in30AWG\_2p7dBPCB\_THRU
- [weaver\\_3dj\\_02\\_2303 \(w\)](#)
  - KR\_ch\_3in\_PCB\_NPC\_300mm\_29AWG\_BP\_800mm\_27AWG\_thru
- [mellitz\\_3dj\\_02\\_2303 \(m\)](#)
  - KRCA\_wXTALK\_25\_PCB-25-25\_mm\_FO-300-300\_mm\_CA-1000\_mm\_thru
- [mellitz\\_3dj\\_03\\_2303 \(m\)](#)
  - KRCA\_wXTALK\_LD\_25\_PCB-25-25\_mm\_FO-300-300\_mm\_CA-1000\_mm\_thru
- [mellitz\\_3dj\\_02\\_elec\\_230504 \(m\)](#)
  - KRCA\_wXTALK\_MX\_4\_PCB-25-25\_mm\_FO-200-200\_mm\_CA-200\_mm\_thru

# Landing zone channels for X=40 dB

Both sets of COM parameter can achieve 3 dB of COM



# Proposed IEEE P802.3dj Objectives

- Define a physical layer specification that supports 200 Gb/s operation over 1 lane over electrical backplanes supporting a die-to-die insertion loss  $\leq 40$  dB at 53.125 GHz
- Define a physical layer specification that supports 400 Gb/s operation over 2 lanes over electrical backplanes supporting a die-to-die insertion loss  $\leq 40$  dB at 53.125 GHz
- Define a physical layer specification that supports 800 Gb/s operation over 4 lanes over electrical backplanes supporting a die-to-die insertion loss  $\leq 40$  dB at 53.125 GHz
- Define a physical layer specification that supports 1.6 Tb/s operation over 8 lanes over electrical backplanes supporting a die-to-die insertion loss  $\leq 40$  dB at 53.125 GHz

# Summary

- ❑ 3 dB COM demonstrated for channels with 40 dB die to die loss
- ❑ Replace X with 40 dB in straw poll #1 of motions\_3dfdj\_2303
  - Technical feasibility illustrated with 3 KR channels from different sources and different COM parameters,
- ❑ Propose: Add 200GBASE-KR1, 400GBASE-KR2, 800GBASE-KR4, and 1.6TBASE-KR8 objectives to IEEE P802.3dj as on slide 13

# Straw Poll

I would support the backplane objectives for 200GBASE-KR1, 400BASE-KR2, 800GBASE-KR4, and 1.6TBASE-KR8 in mellitz\_3dj\_01\_2305 slide 13

Y: N: A:

# Thank You!