#### COM update 4.1

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### **Contributors**

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# Background

### COM direction on RXFFE clarified in July 2023

#### Straw Poll #1

I would support the direction of the RXFFE changes to Annex 93A (COM) in mellitz\_3dj\_01a\_2307 slides 6, 7, and 8 Results (all): Y: 61, N: 0, NMI: 7, A: 19

#### Straw Poll #9

I would support the direction of a RXFFE based reference RX to the 200G/lane AUI C2M and AUI C2C

Results (all): Y: 61, N: 0, NMI: 10, A: 26

https://www.ieee802.org/3/dj/public/23\_07/motions\_3cwdfdj\_2307.pdf

# **Progress Report**

### Key Changes for Rx<sub>FFE</sub> in Annex 93A (COM)

- □ Consider an update to the COM reference model, figure 93A-1
  - See slide 6
- $\square$  Provide for implementation noise,  $\eta_1$
- □ Include another term,  $H_{rxffe}(f)$ , the receiver FFE response, into the voltage transfer function,  $H^{(k)}(f)$ 
  - $H^{(k)}(f) = Hffe(f) H_t(f) H_{21}^{(k)}(f) Hr(f) Hctf(f) H_{rxffe}(f)$
- Provide a receiver equalizer description like the transmitter equalizer in sub-section 93A.1.4.2.
- Reuse the specified COM FOM for the determination of the variable equalizer parameters settings

https://www.ieee802.org/3/dj/public/23\_07/mellitz\_3dj\_01a\_2307.pdf

## **COM 4.1 Update Agenda**

#### For .3dj project work

- □ Changes from COM 4.0
- Block Diagram
- □ COM flow
- □ COM Keyword update
- $\Box$  Tx anchor for  $Rx_{FFE}$
- $\Box$  Rx<sub>ffe</sub> determination

# Changes from 4.0 $\rightarrow$ 4.1

- 1. Rx<sub>ffe</sub> suggested in mellitz\_3dj\_01a\_0723
  - a) COM 4.0 and earlier used first zero crossing to reference T<sub>s</sub> one UI later for Rx<sub>ffe</sub> tap determination
- feature

- a) After determination, Mueller-Muller (MM) is used for T<sub>s</sub>
- b) COM 4.1 determines initial T<sub>s</sub> anchor uses pulse response (PR) peak for Rx<sub>FFE</sub> tap determination
  - a) The oversampled offset away form the anchor is determined using in the specified over sampled range.
  - b) Ts is determined for the best FOM of all specified oversamples in combination with all CTF and Tx FFE combinations.
- 2. PDF & CDF correction as suggested in kirkland\_3dj\_elec\_01\_230406
  - a) Tends to offset the COM impact when sample adjustment is set to 0 in 1b
- 3. Renormalize inputted s-parameters. 50 ohms reference no longer required.
- 4. Removed RL data from reports unless bread\_crumbs is set (memory saving)
- 5. S21.^2 changed to s12.\*s21 in s21\_pkg. Corrected VTF needed for non-passive s-parameters

IEEE P802.3dj 200 Gb/s, 400 Gb/s, 800 Gb/s, and 1.6 Tb/s Ethernet Task Force

Bug

feature

Bug

Bug

### **COM reference model proposal**

#### WITH RX FFE



# $Rx_{FFE}$ is within the Full Grid Optimization Loop and includes $T_s$ sweep

Added COM parameter	Example value	Default	information	notes
sample_adjustment	[-32 32]	0	Min max sample offset range from ts anchor	Integer related to M
ts_anchor	1	0	Ts anchor for sample adjustment (0,1)	See next slides

Full grid loop hierarchy

- 1. CTF
  - for each G<sub>DC</sub> and G<sub>DC2</sub>

#### 2. Tx<sub>ffe</sub>

- for each C(n)
- 3. For RxFFE only (new for COM 4.1)

Determine T<sub>s</sub> (like a CDR)

- Initial T<sub>s</sub> anchor uses Mueller-Muller (MM), PR peak, or max dv/UI and then continue for each oversample step in "sample\_adjustment"
- If sample\_adjustment= 0 then only MM is used for  $T_s$  and thus  $Rx_{ffe}$
- Sample adjustment
- Find Rx<sub>FFE</sub> taps C<sub>rx</sub>(n) and apply
- 4. For Rx<sub>FFE</sub> with sample\_adjustment=0 or no Rx<sub>FFE</sub>
  - $T_s$  is determined from Mueller-Muller (MM), equation 93A–25
- 5. Compute FOM for steps [ 1 2 3 4 ]
- 6. Determine variable equalizer settings for best FOM

### **COM 4.1 Configuration Keyword Update**

#### ADDED, REVISED, AND RETIRED

Added COM parameter	Example value	Default	information	notes
sample_adjustment	[-32 32]	0	Min max sample offset range from ts anchor	Integer related to M
ts_anchor	1	0	Ts anchor for sample adjustment (0,1)	See next slides

Revised COM parameter	Example value	Default	information	notes
Local Search	2	0	Distance length for coordinate decent	Sample_adjustment
			0 disables	incorporated for COM 4.1
ffe_main_cursor_min	1		Minimum value for the $C_{1}(0)$	All taps are normalized
				such that C <sub>rx</sub> (0)=1
ffe_pre_tap_len	5	0	Number of pre taps	if both are 0, Rx_FFE and
ffe_post_tap_len	24	0	Number of post taps	eta1 is not used
ffe_pre_tap1_max	1	1	Maximum value for C_RX(1)	
ffe_post_tap1_max	1	1	Maximum value for C_RX(-1)	
ffe_tapn_max	1	1	Maximum value of all other taps	
ffe_tap_step_size		0	Step size (normalized)	May be revisited

<b>Retired COM parameters</b>	Default	information	Notes. Defaulted in COM script
ffe_backoff	0		

### For each Tx<sub>ffe</sub> and CTF setting

#### STEPS 1 AND 2



### COM 4.1 $T_s$ over sample sweep

#### \*TS\_ANCHOR = 1 FOR $RX_{FFE}$



### **Rx FFE Determination**

mellitz\_3ck\_adhoc\_01a\_100318 (COM 2.51 with RX<sub>FFE</sub> updates)

- Rx FFE tap determination is within the inner loop for the Tx, CTF, and T<sub>s</sub> sweeps
- More information on the vector forcing algorithm is per <u>mellitz 3ck adhoc 01a 100318.pdf</u>

□ Rx FFE taps, C<sub>rx</sub>, is a least squares solution for the following equation

- $\overline{FV} = [HH]\overline{C_{Rx}}$ , where
  - HH the convolution matrix derived from the sampled pulse response
  - FV is a forcing vector zero everywhere except
    - FV(0) corresponds to the sample point
    - FV(1) is set to the pre-RX<sub>FFE</sub> postcursor DFE value (up to b<sub>max</sub>(1)).
- Solve for  $C_{RX}$

• 
$$C_{RX} = \left( \left( (HH^T \ HH) \right)^{-1} HH^T \right)^T FV^T$$

• A partial response is embodied in the forcing vector FV

### **Next Steps**

Determine what is good enough for 200 Gbps PAM4 COM?

- Test COM 4.1 more broadly across industry with provided channels and investigate reference EQ needs for baseline proposals
- □ Refine COM 4.1 as needed for RXFFE functionality and accuracy
- □ Expand COM for MLSE feature (CR/KR applications)

# **Thank You!**

### back up slides – extra information

### **Determining FFE taps, C within the inside loop**

#### FROM: MELLITZ\_3CK\_ADHOC\_01A\_100318.PDF SLIDE 9

#### $\Box C = ((HH^{T} * HH^{-1} * HH^{T})^{T} * FV^{T}$

- C are the Rx FFE taps
- HH is derived from  $h^{(0)}(t)$
- HH is shifted sampled ISI matrix
- $\hfill\square$  FV is the forcing vector ,
- $\Box FV = [... 0, 0, FV0, FV1, 0, 0, 0, 0...]$
- □ FV for the cursor tap is
  - FV0=  $h^{(0)}(t_s)$
  - This forces the cursor tap to 1
- Modified from mellitz\_3ck\_01\_0718: FV for the post cursor tap (2.51 update)
  - $FV1 = sign(h^{(0)}(t_s + T_b)) min(|h^{(0)}(t_s + T_b))|, |b_1 h^{(0)}(t_s)|)$
  - This makes sure the b<sub>1</sub> is not violated for the DFE
- $\Box$   $h_{fferx}(f)$  is computed from the C found as in eq 93A-21

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