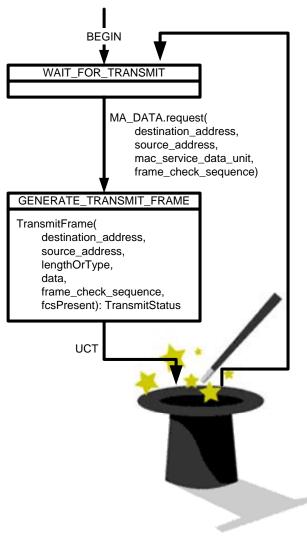
# **MAC Service Interface**

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August 11, 2008

# Two problems identified

- Ambiguity of rules when state diagrams are combined with Pascal
- MAC Clients need to resort to "magic" to find out when a MAC\_DATA.request can be generated or whether it succeeded



#### Problem 1: Ambiguity of rules when state diagrams are combined with Pascal

# **Combining State Diagrams and Pascal**

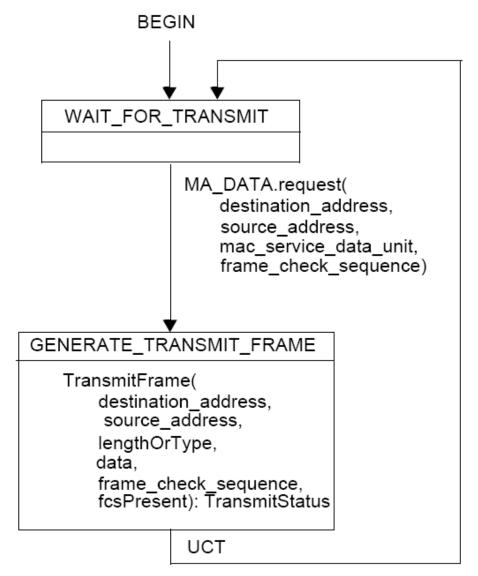
- **1.2.1:** State transitions and sending and receiving of messages occur instantaneously. When a state is entered and the condition to leave that state is not immediately fulfilled, the state executes continuously, sending the messages and executing the actions contained in the state in a continuous manner.
- **21.5.1 (extensions to 1.2.1):** <u>The actions inside a state block</u> <u>execute instantaneously.</u> Actions inside state blocks are atomic (i.e., uninterruptible). After performing all the actions listed in a state block one time, the state block then continuously evaluates its exit conditions until one is satisfied, at which point control passes through a transition arrow to the next block. While the state awaits fulfillment of one of its exit conditions, the actions inside do not implicitly repeat.
- **4.2.8:** The TransmitFrame operation is synchronous. <u>Its duration is</u> <u>the entire attempt to transmit the frame</u>; when the operation completes, transmission has either succeeded or failed, as indicated by the TransmitStatus status code.

## Need to clarify the conventions

- If a state calls TransmitFrame() function, should 21.5.1 or 4.2.8 take precedence?
- If 4.2.8 takes precedence, then, the state machine will remain in the state until TransmitFunction() returned, even if the exit condition is satisfied immediately
  - This is analogous to a serial execution in any single-threaded (single-stack) finite automata
- If 21.5.1 takes precedence, then calling TransmitFrame() function will be an instantaneous event and the execution will immediately proceed with the state code that follows this function call.
  - This is analogous to a multi-threaded model, where a call to TransmitFrame() simply spawns another thread (process) which executes asynchronously from the parent process.
- Both approaches are justified. We need to make a choice and document it.

#### If 4.2.8 takes precedence...

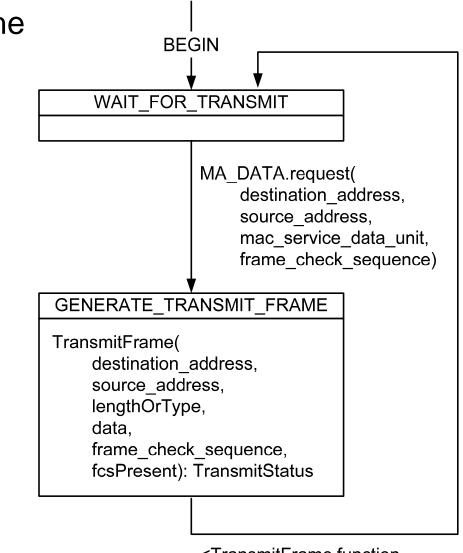
 Existing state diagram in Figure 4-6 assumes 4.2.8 takes precedence.



# If 21.5.1 takes precedence...

• ... then, the transition from the state should wait for a condition.

- Few ways to specify the condition:
  - 1. Simply describe it in a note
  - 2. Add a boolean TransmitFrameCompleted
  - 3. Wait for specific value(s) of TransmitStatus

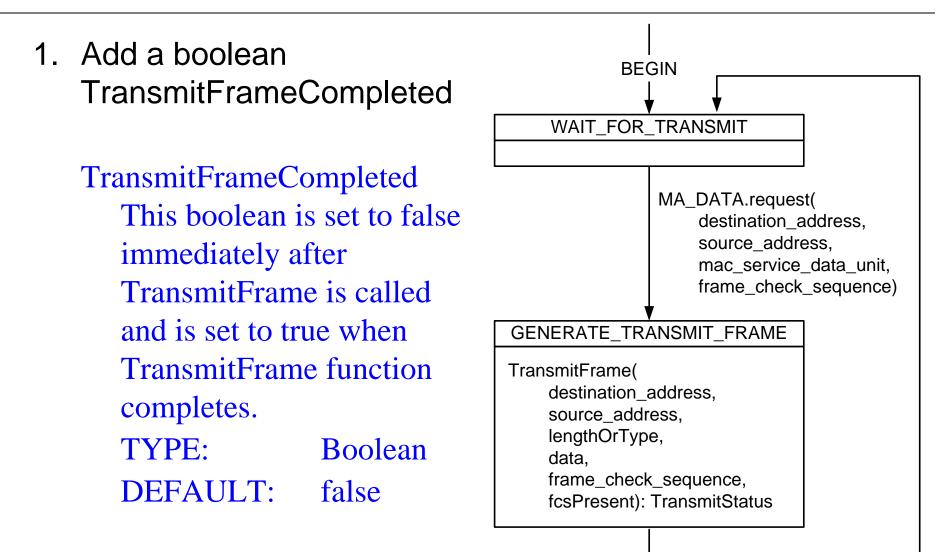


#### **Option 1: Add a note**

Simply describe it in a note

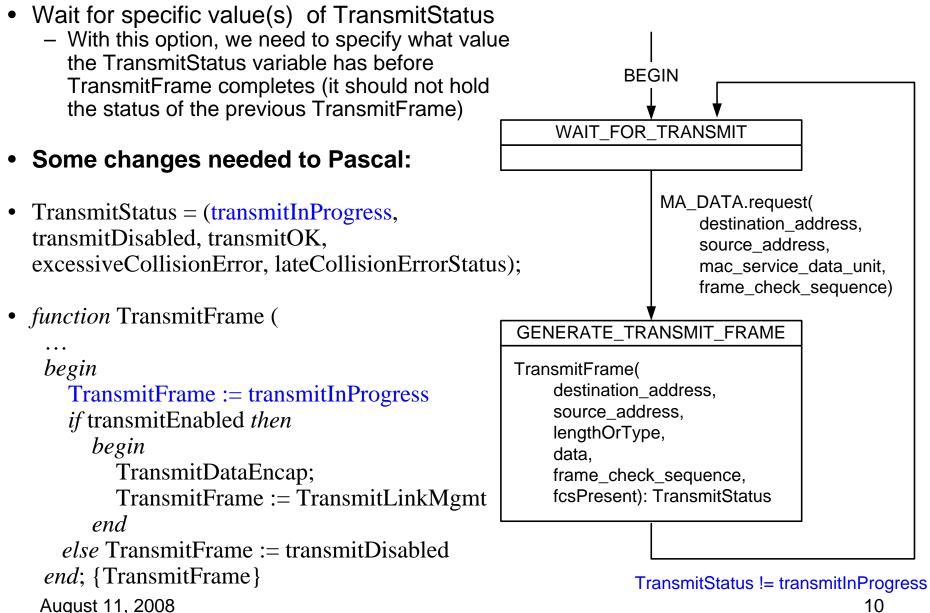
"Transition from state GENERATE\_TRANSIT\_FRAME occurs immediately upon completion of TransmitFrame() function."

#### **Option 2: Add a new Boolean**



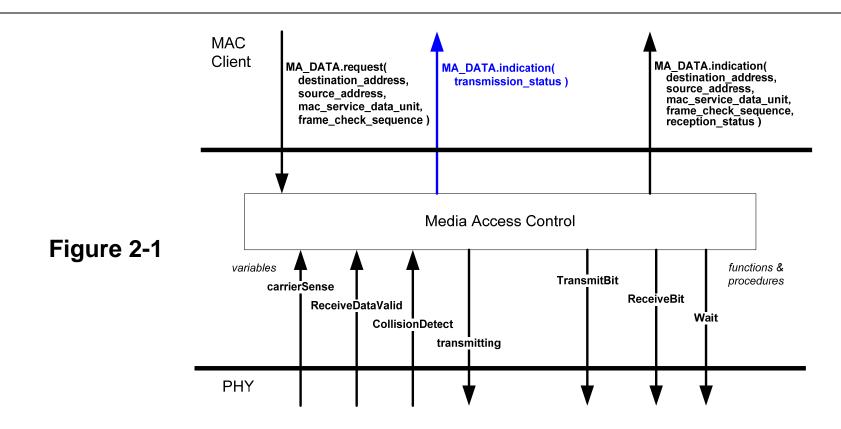
#### TransmitFrameComplete = true

# **Option 3: Wait for a specific TransmitStatus**



#### Problem 2: MAC Clients doesn't know when a MAC\_DATA.request can be generated or whether it succeeded

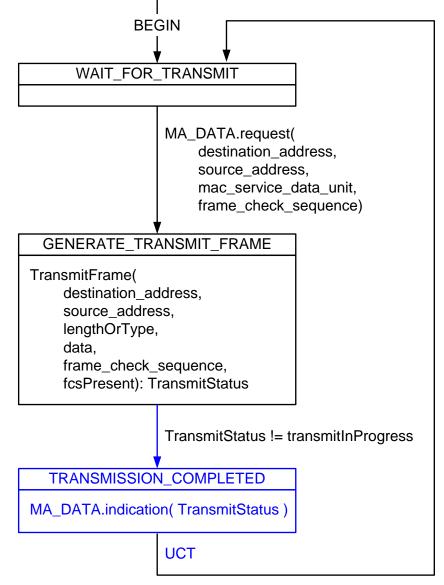
#### **Three-legged MAC Service Interface**



• To let the MAC client know when frame transmission ended, another indication can be added to the MAC Service Interface.

# **MAC Client Transmit Interface**

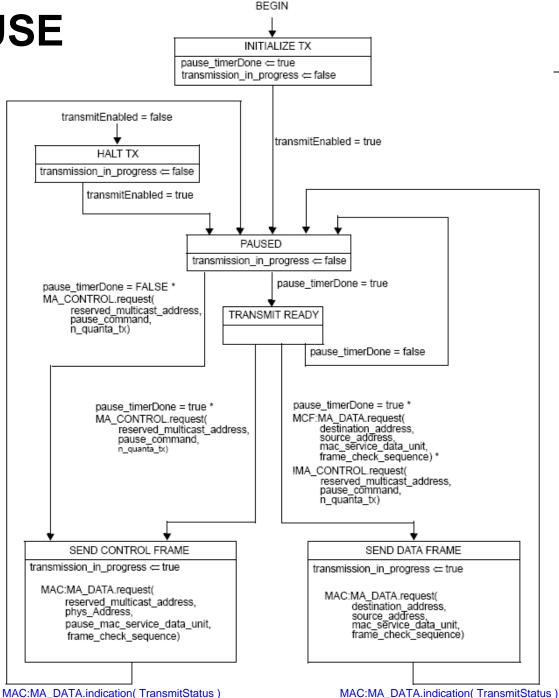
- Modification to Figure 4-6 MAC Client transmit interface state diagram.
- (This example assumes option 3 is selected, but this is not necessary)



# **MAC Client: PAUSE**

 To pace itself, a MAC client after issuing MA\_DATA.request(...) would wait for MA\_DATA.indication( TransmitStatus)

 Example shown for PAUSE Operation Transmit state diagram (Figure 31B-1) →



# **MAC Client: OAM**

 Example shown for OAM Multiplexer state diagram (Figure 57-7) →

